

Development of EarthCARE ATLID data retrieval algorithm and validation plan using the ground-based lidar network

Nobuo Sugimoto (NIES)

Tomoaki Nishizawa, Akiko Higurashi, Eiji Oikawa, Atsushi Shimizu, Ichiro Matsui (NIES, Japan), Hajime Okamoto (Kyushu Univ. Japan), Rei Kudo (MRI, Japan)

Contents

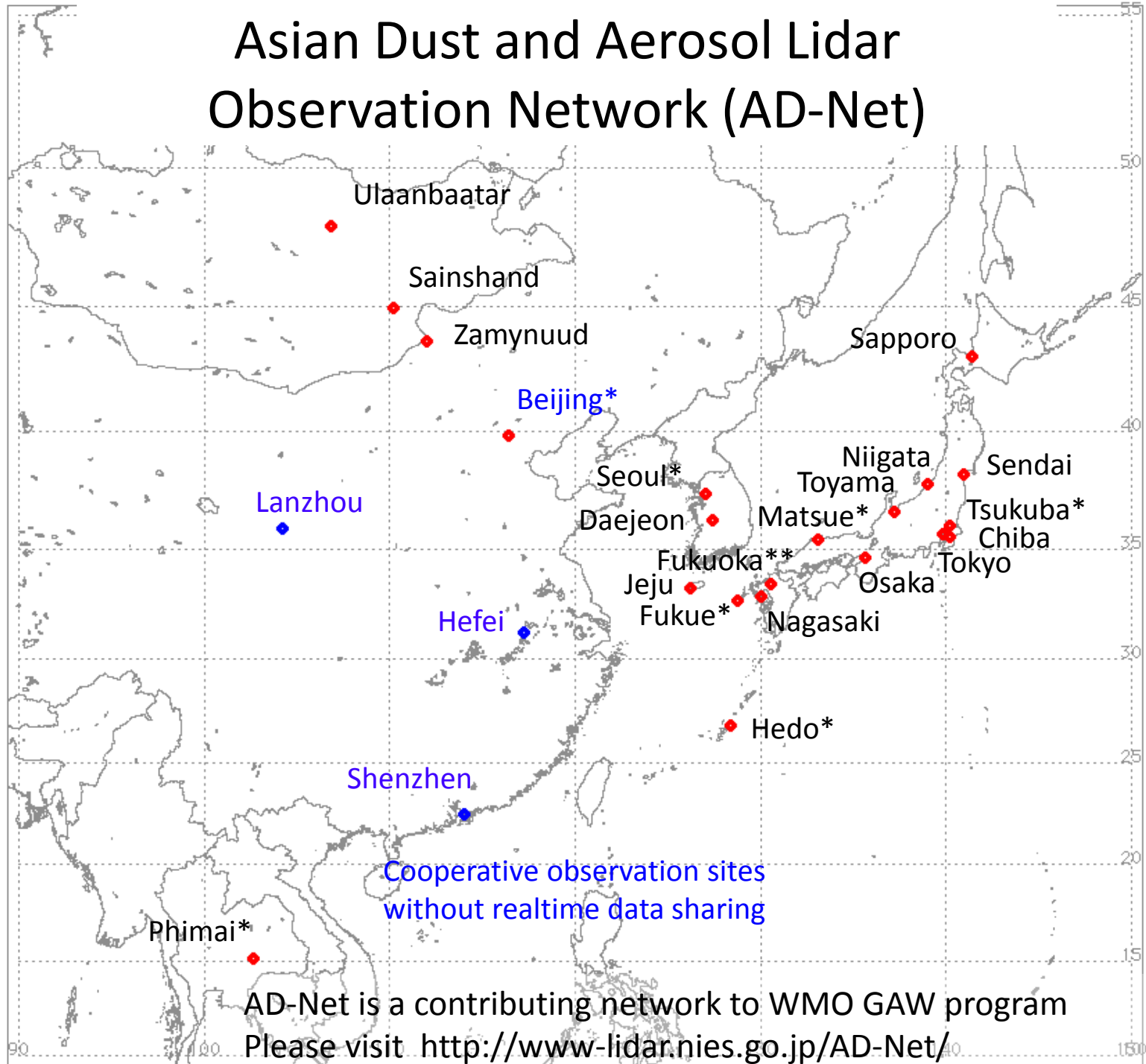
Introduction to AD-Net lidars and data analysis methods

EarthCARE ATLID data retrieval algorithm development in the Japanese Research Announcement studies

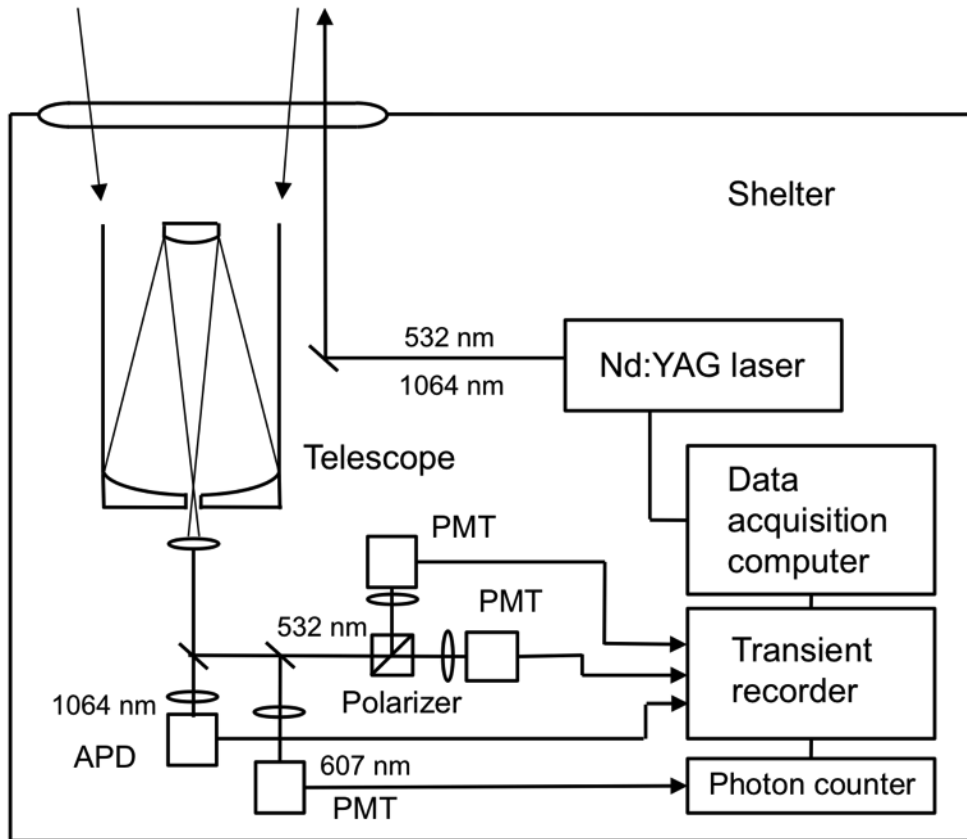
- Feature Mask, Target Mask (Aerosol Types), Aerosol Optical Parameters (Extinction, Backscatter, Depolarization)
- Aerosol Component Retrieval (Dust, Sea-salt, Water-soluble, Black carbon)

Validation plan using the ground-based lidar networks

Asian Dust and Aerosol Lidar Observation Network (AD-Net)



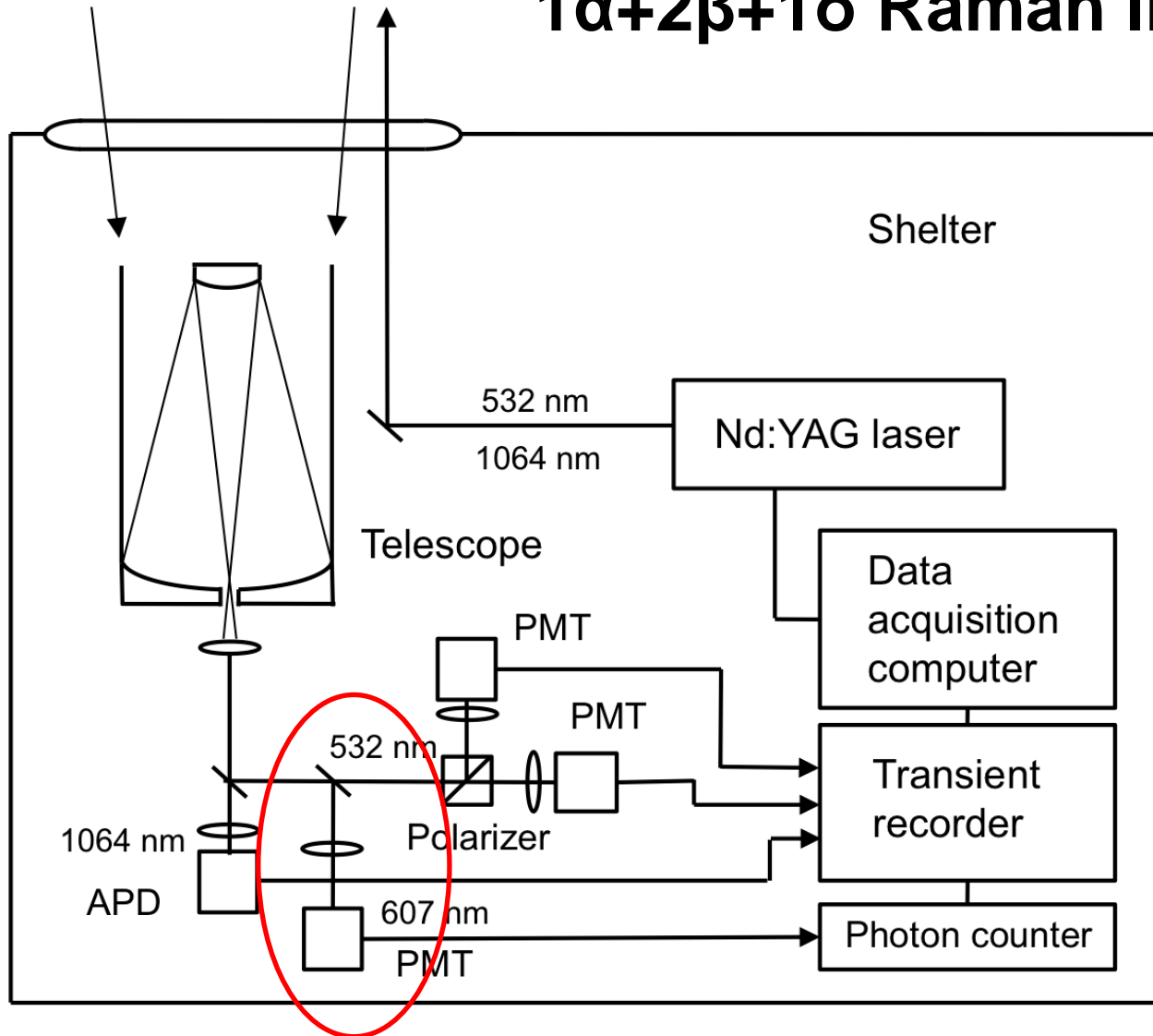
AD-Net Lidar



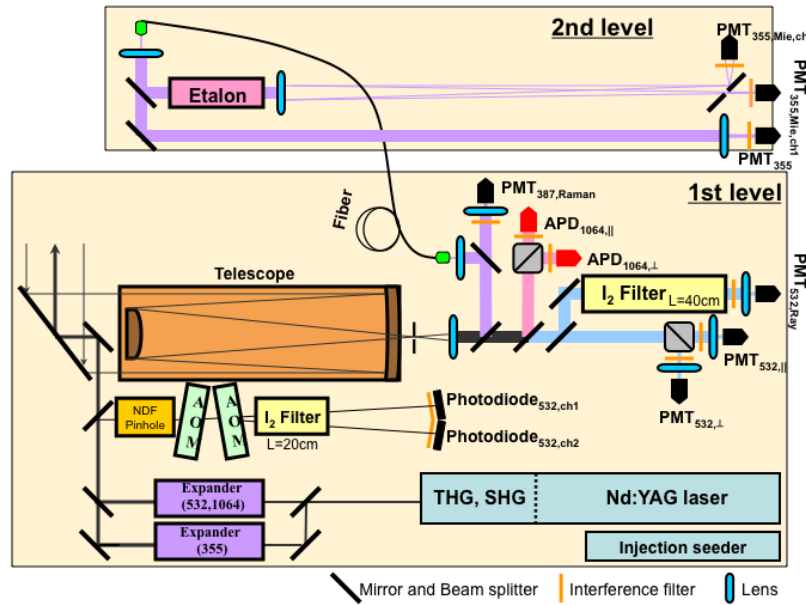
$2\beta+1\delta$ Mie-scattering lidar

Addition of N₂ Raman receiver for independent extinction coefficient measurements

1 α +2 β +1 δ Raman lidar



Development of lidars for the next generation AD-Net

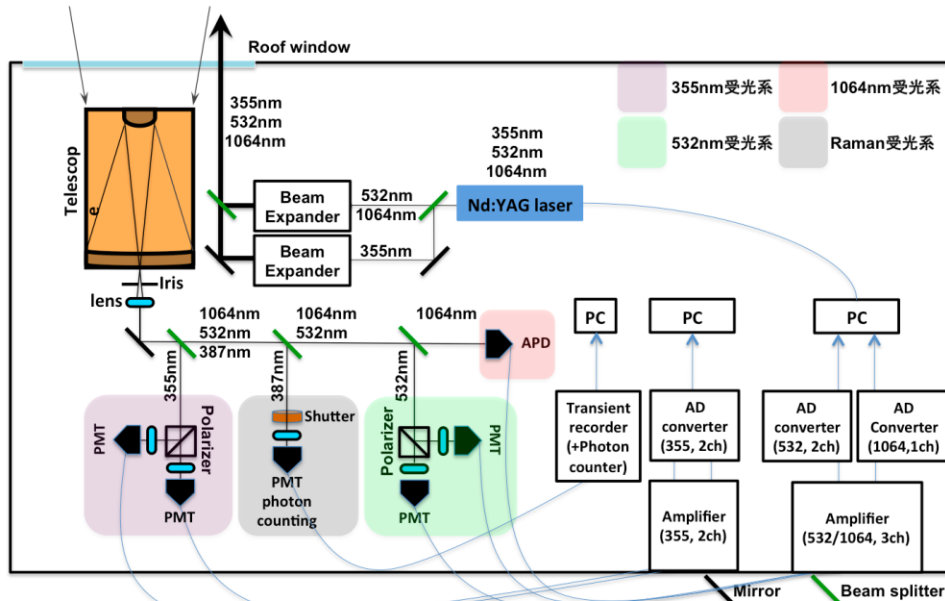


We have developed a

$2\alpha+3\beta+2\delta$ HSRL

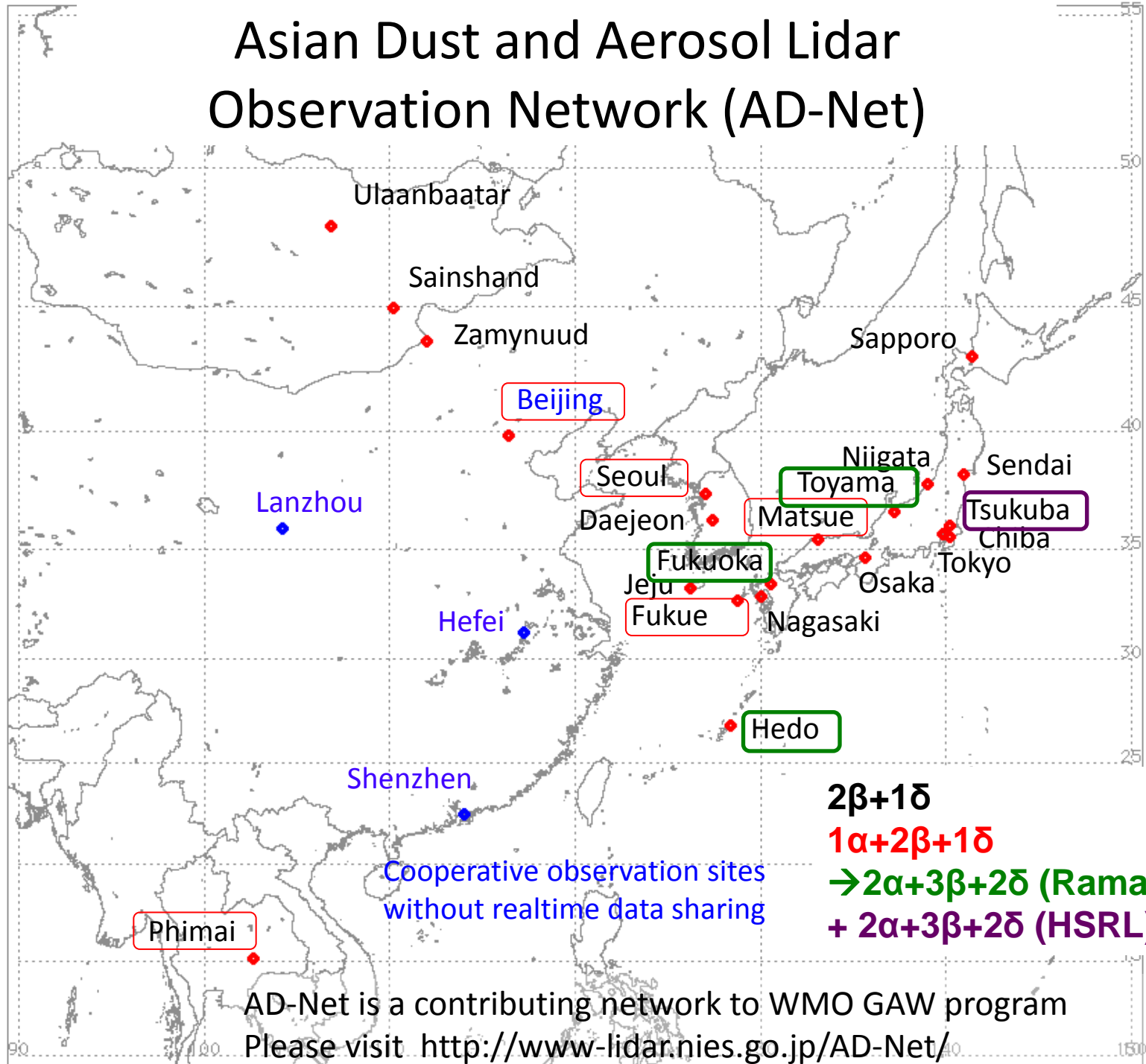
and

$2\alpha+3\beta+2\delta$ Raman lidars



HSRL: High-Spectral Resolution Lidar

Asian Dust and Aerosol Lidar Observation Network (AD-Net)



Evolution of lidars and data analysis methods with AD-Net (Aerosol component analysis)

1 β +1 δ method to estimate **dust** and **other spherical aerosols**
(Sugimoto et al., 2003; Shimizu et al., 2004)

2 β +1 δ method using spheroid dust model to estimate **dust**, **sea salt** and **water soluble** (Nishizawa et al., 2010)

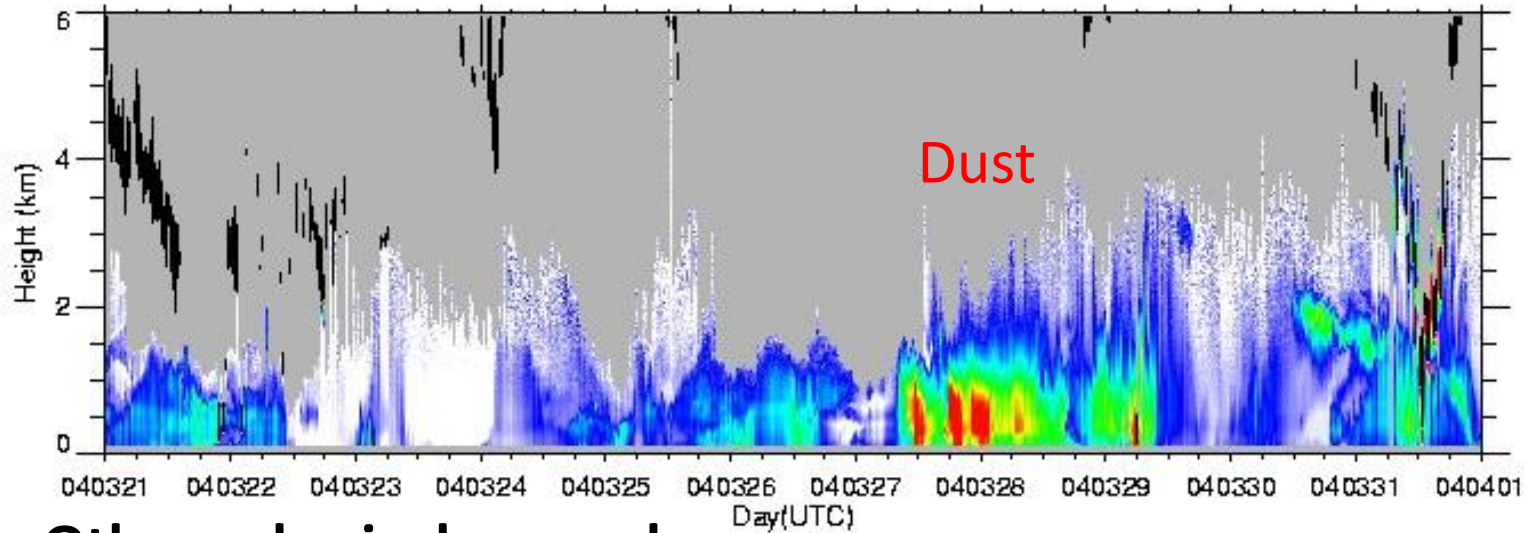
1 α +2 β +1 δ method to estimate **dust**, **sea salt**, **water soluble** and **black carbon** (Nishizawa et al., 2008)

1 α +1 β +1 δ method to estimate (**dust** or **sea salt**), **water soluble** and **black carbon** (Nishizawa et al., 2010) → EarthCARE

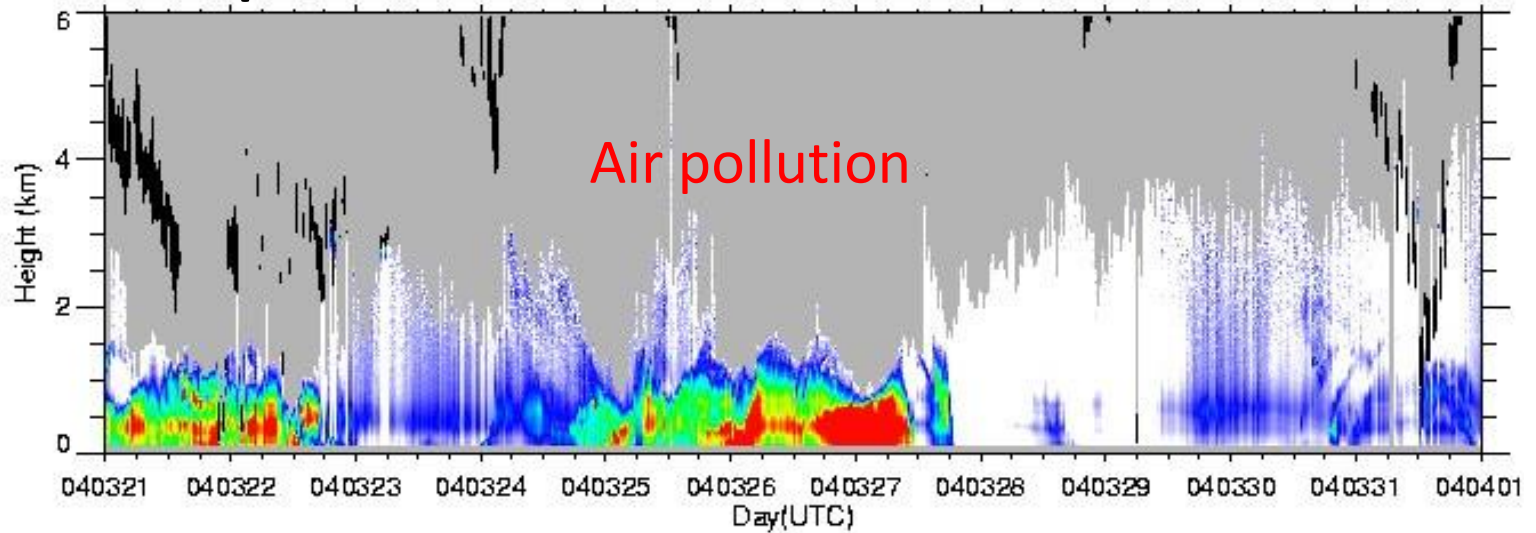
2 α +3 β +2 δ method to estimate **dust**, **sea salt**, **water soluble**, **black carbon** and **particle size of water soluble, dust, sea salt** (being developed)

Dust

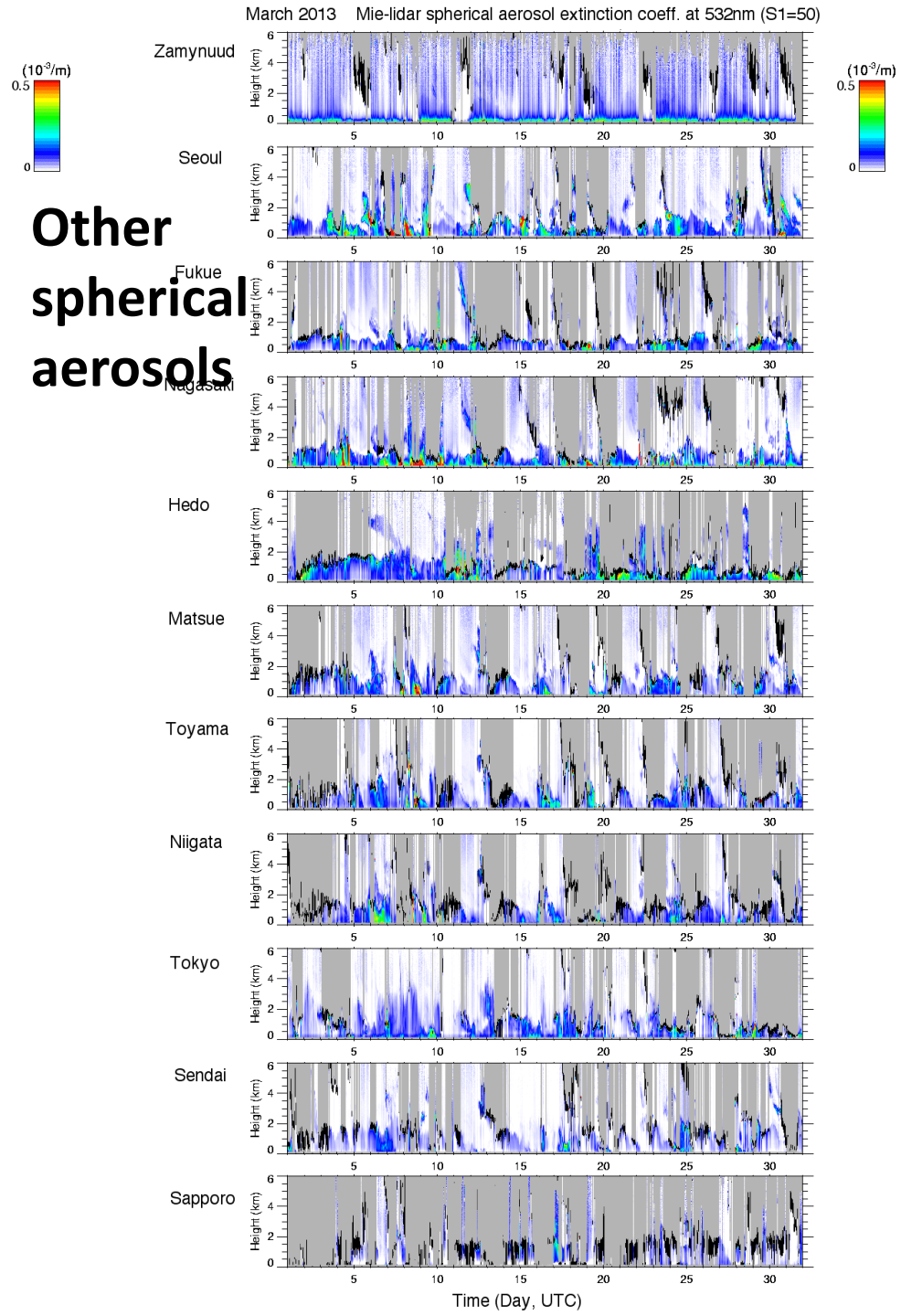
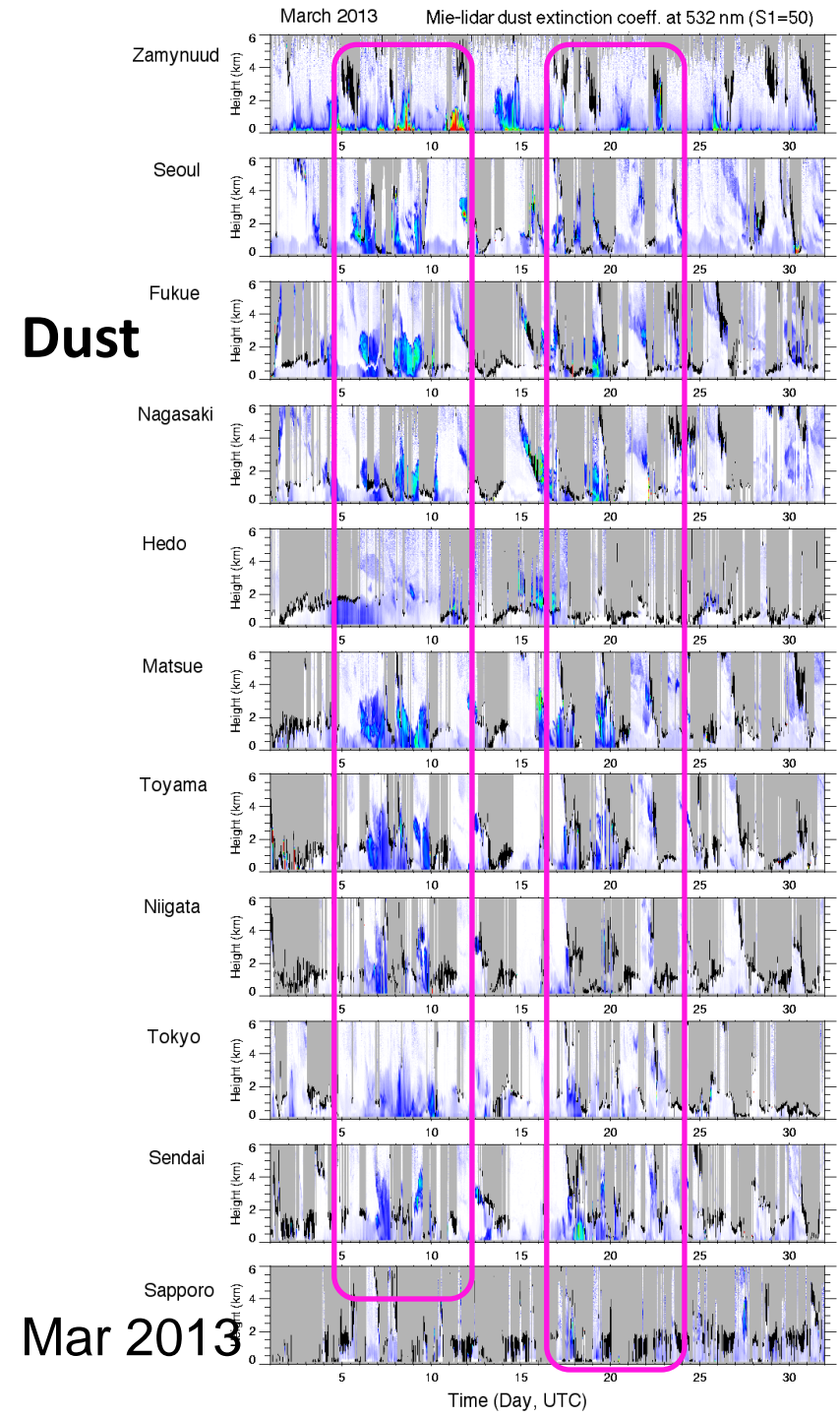
March 21-31, 2004 Beijing



Other spherical aerosols

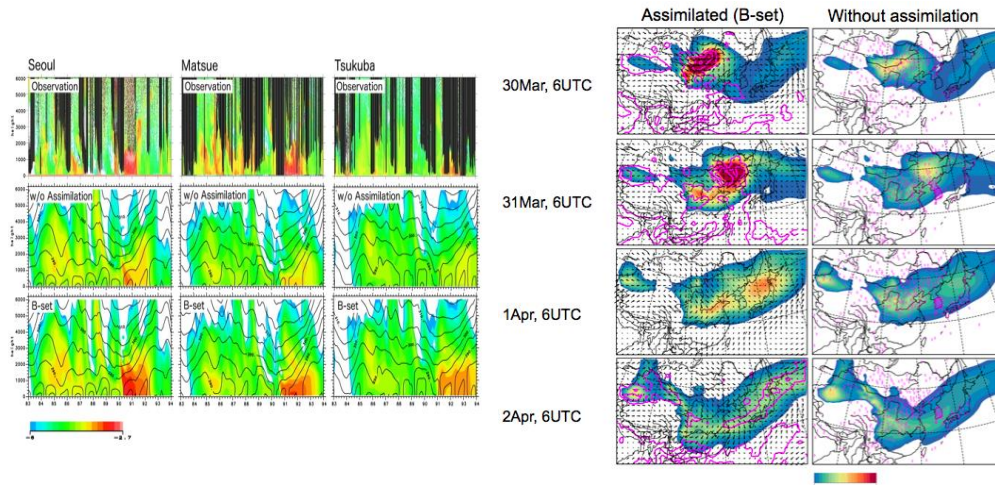


$1\beta+1\delta$ method for estimating the extinction coefficients of dust and spherical aerosols

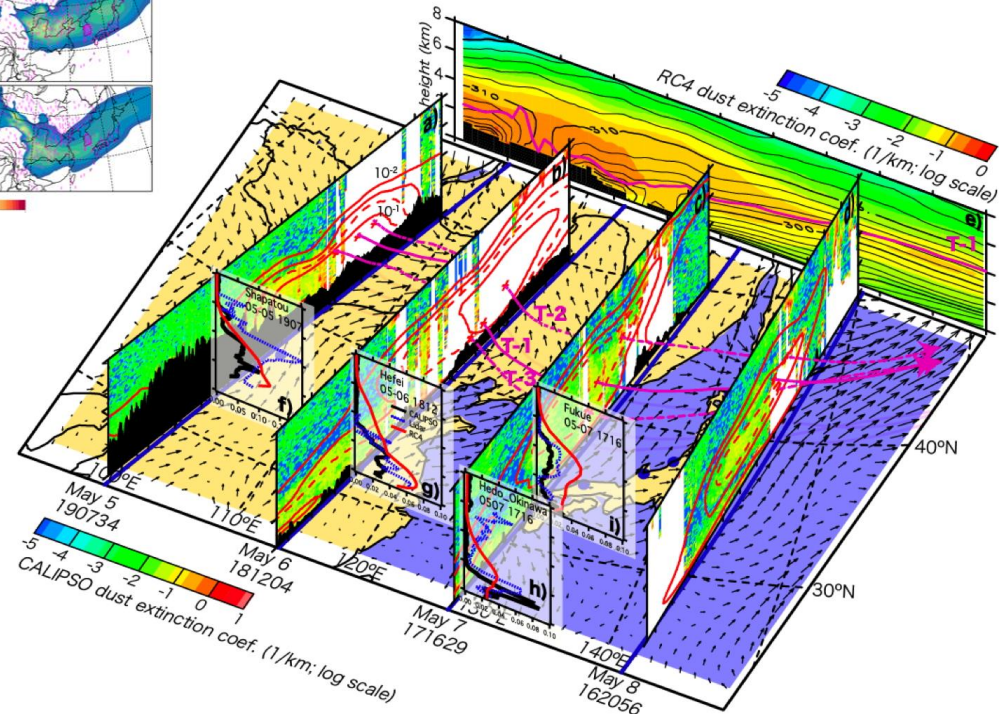
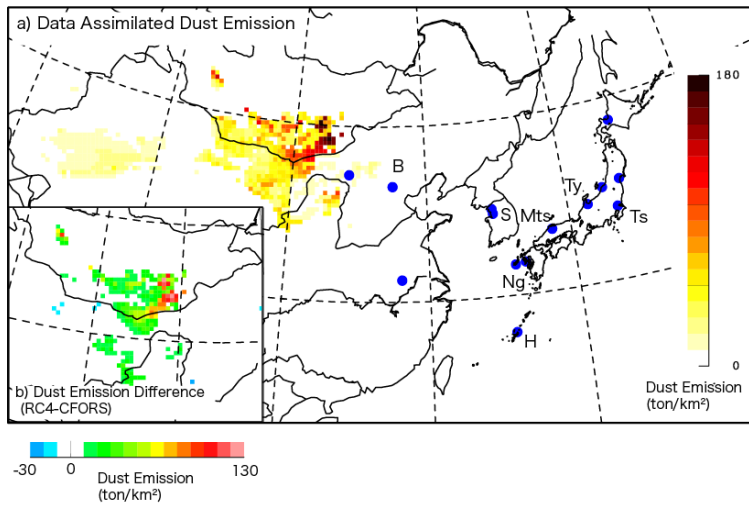


Mar 2013

Asian dust study using 4D-Var data assimilation



→ Keiya Yumimoto's presentation



4DVAR data assimilation of Asian dust using the NIES lidar network data (Yumimoto et al. 2007, 2008)

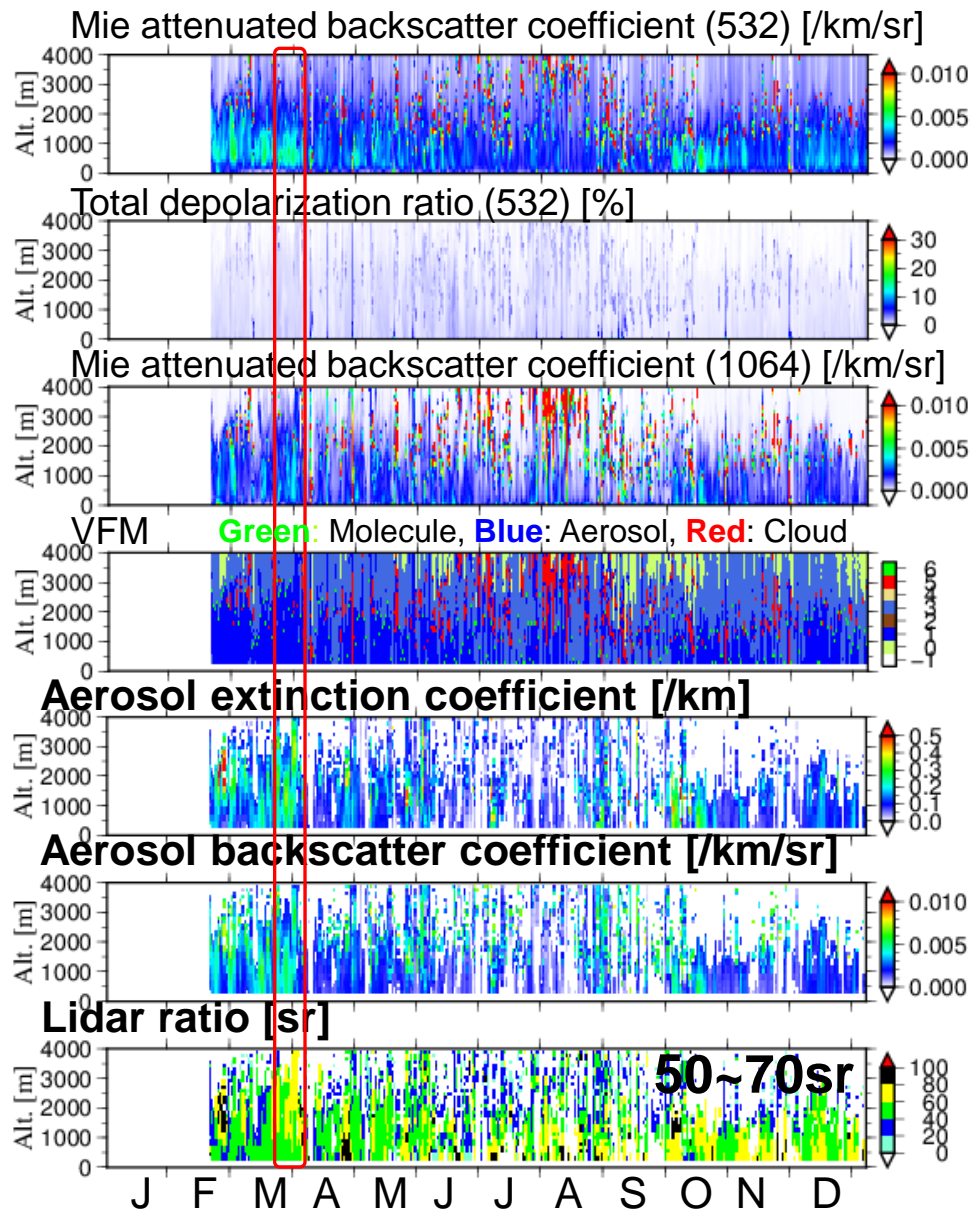
Comparison of the assimilated dust transport model with CALIPSO data (Hara et al. 2009)

Please see the publication list at <http://www-lidar.nies.go.jp/~cml/English/PublicationsE.html>

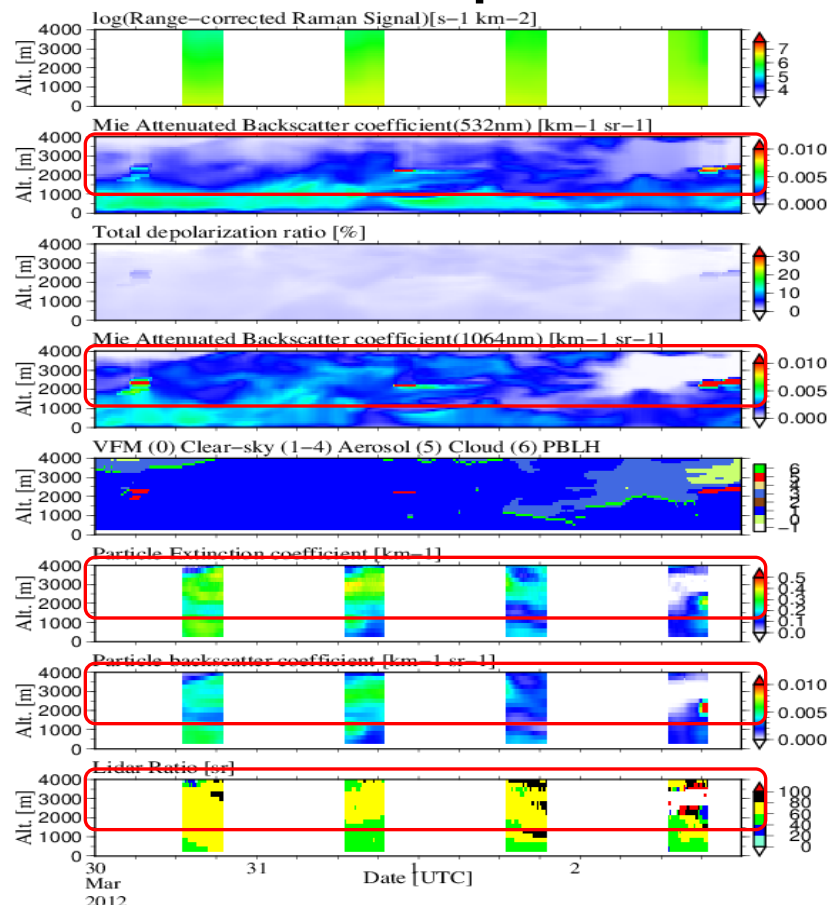
1 α +2 β +1 δ Raman lidar data

(Phimai, Thailand)

2012



30 Mar. ~ 2 Apr. 2012



Lidar ratio for biomass burning aerosols

AERONET :

Catrrall. 2005: 60 \pm 8 (Africa / S. America)

Omar. 2009 : 70 (all AERONET data)

Lidar (EARLINET)

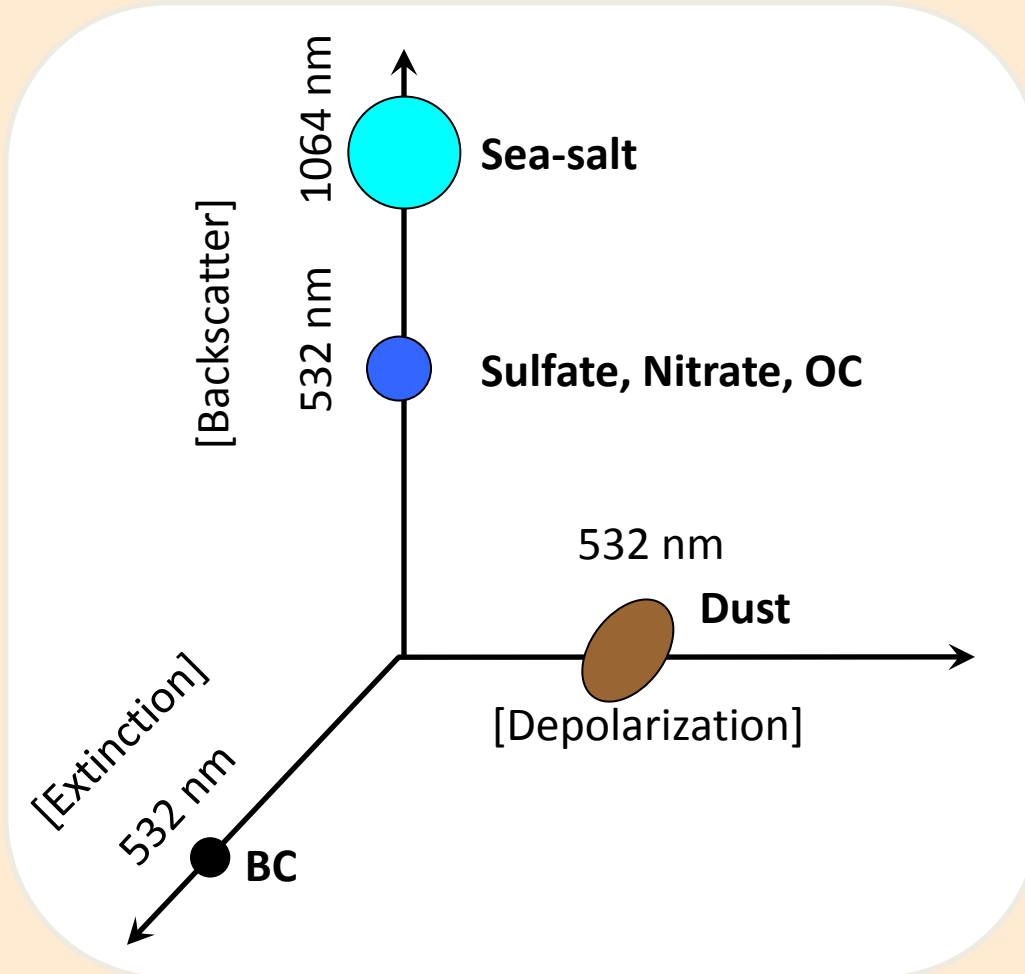
Muller. 2007 : 53 \pm 11 (Siberia/Canada)

1 α +2 β +1 δ algorithm

4 independent observation parameters \rightarrow Retrieve extinction coefficient profiles of 4 aerosol components

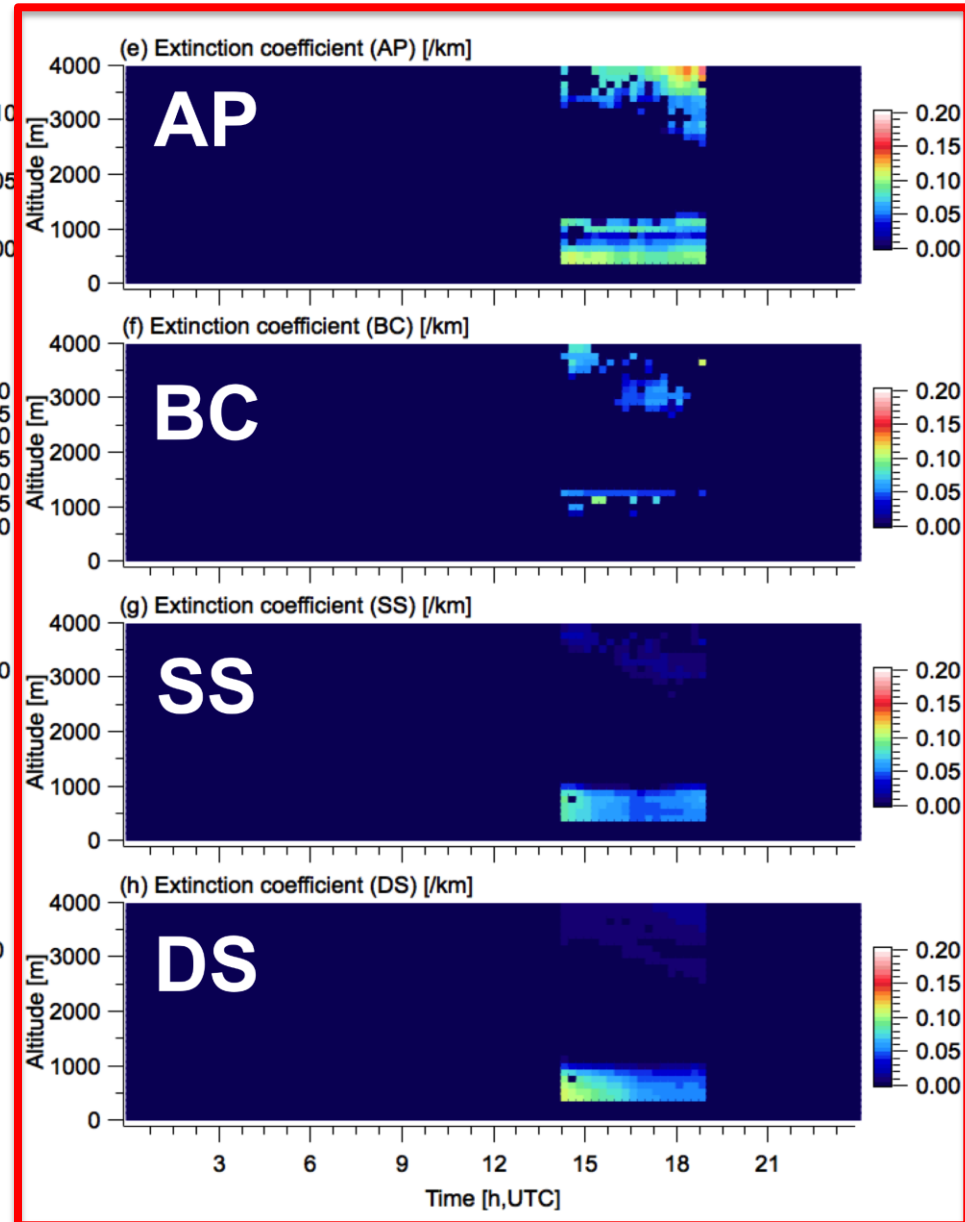
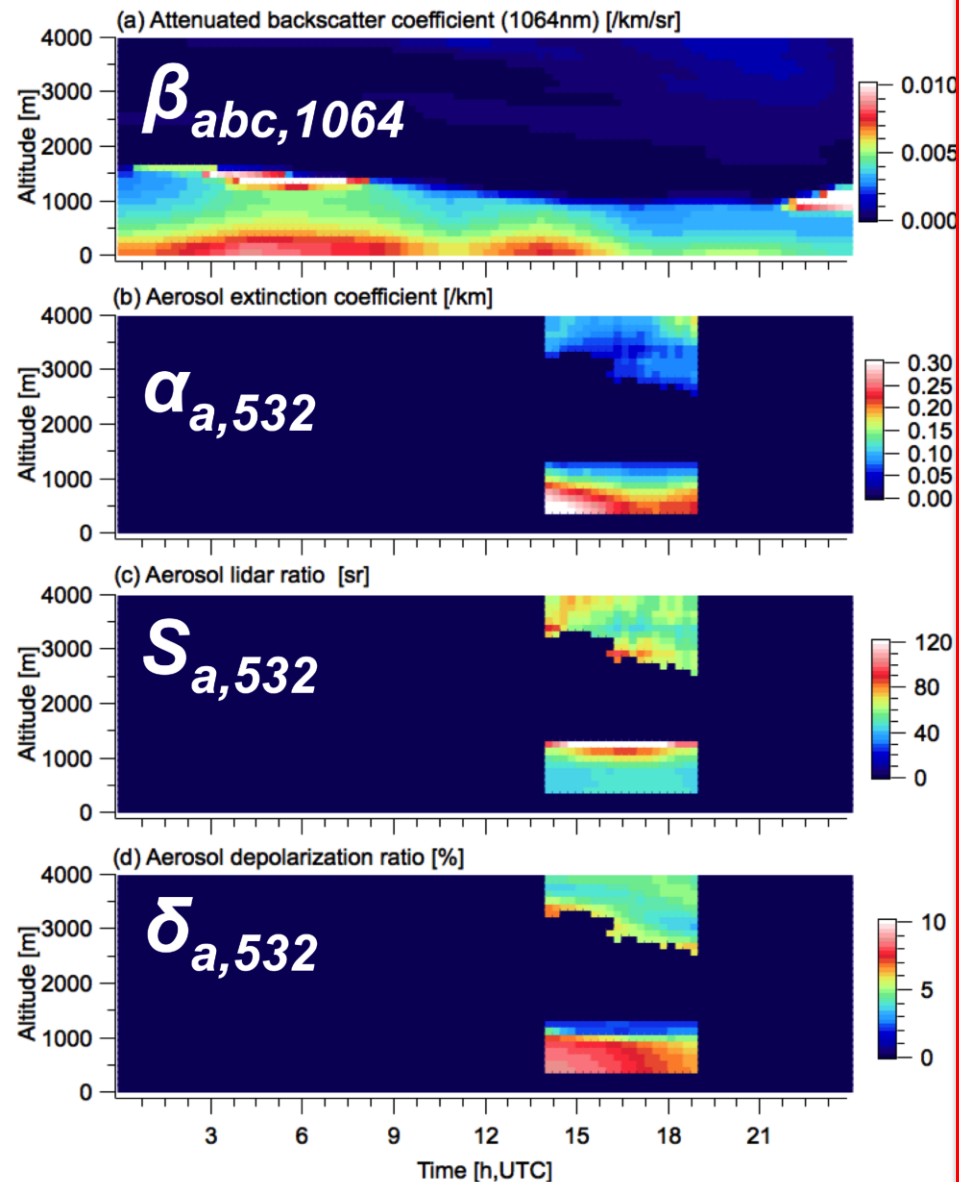
Assumption:

- External mixture of 4 components
- Lognormal size distribution
- Fix mode radii, refractive index
- Spheroid for dust



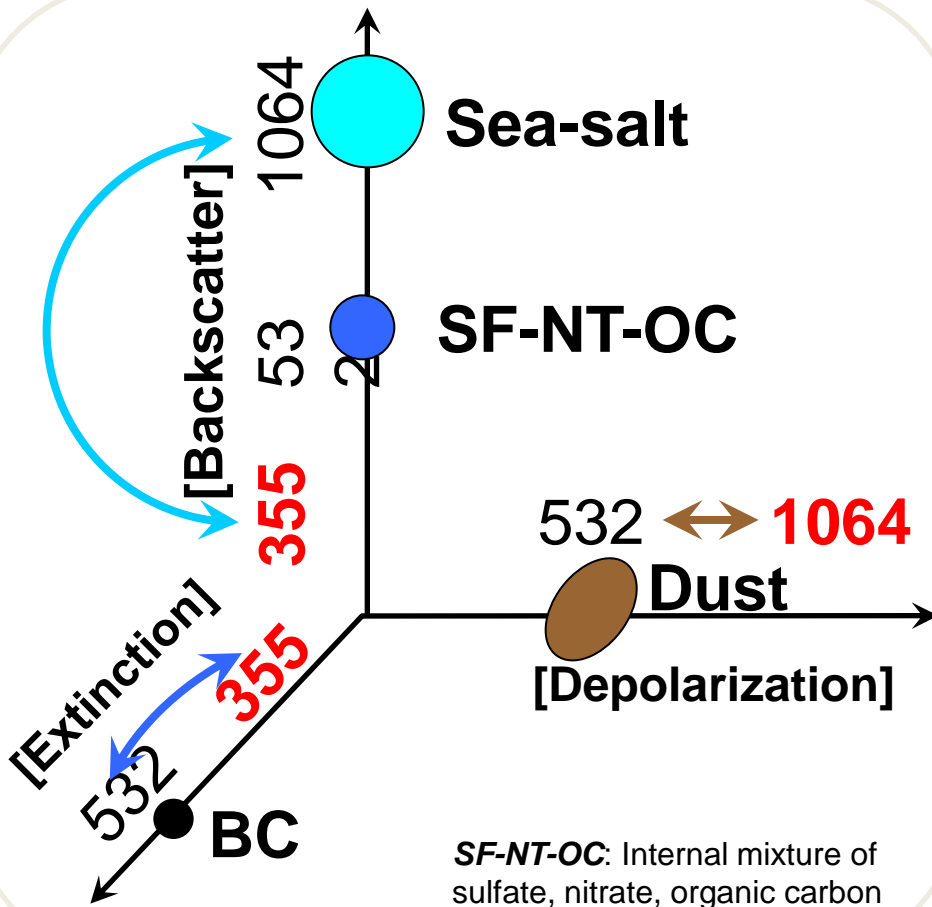
	SF-NT-OC	Dust	BC	Sea-salt
Mode radius [um]	0.13	2.0	0.05	3.0
Standard dev.	1.6	2.2	2.0	2.1
Refractive index (532nm)	1.41 2×10^{-3}	1.51 3×10^{-3}	1.75 0.4	1.36 3×10^{-9}
Lidar ratio (532nm, sr)	55	48	101	20
Dep. (532nm)	0.02	0.30	0.02	0.02
Backscatter color ratio (1064/532)	0.34	0.98	0.23	0.67

Component analysis



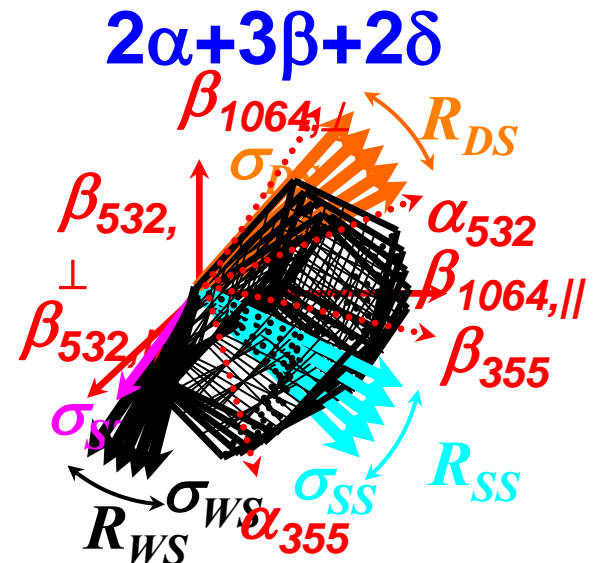
Algorithm for $2\alpha+3\beta+2\delta$ data

- Extinction coefficients for **4 aerosol components** at each layer (Mineral dust, Sea salt, Black carbon, Sulfate+Nitrate+OC)
- **Mode radii of 3 aerosol components** at each layer (Mineral-dust, Sea-salt, SF-NT-OC)



Assumption:

- External mixture of 4 components
- Lognormal size distribution
- Fix refractive index
- Spheroid for dust



Problems with aerosol component analysis

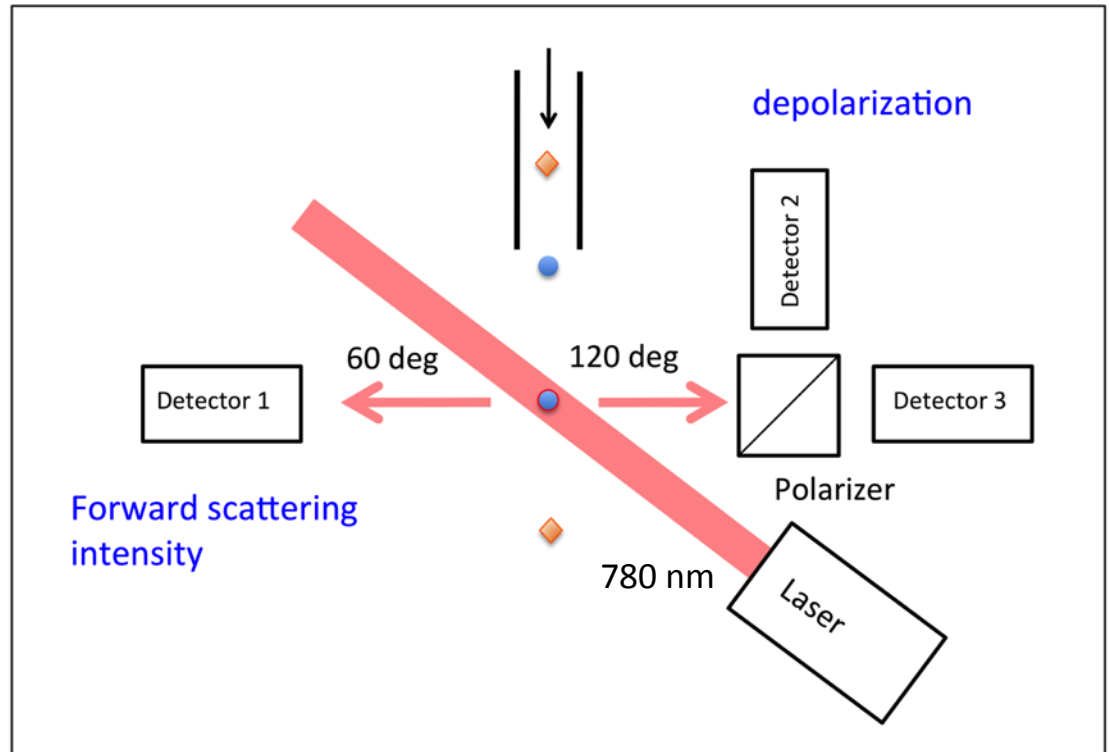
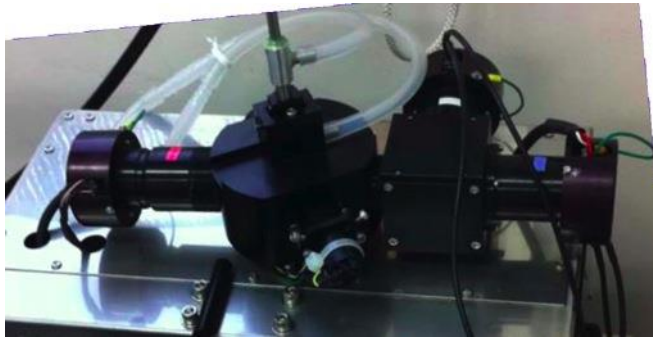
Are the **Definition of aerosol components and their optical models** reasonable?

- Water soluble (Sulfate + Nitrate + OC): non-light-absorbing fine particles
- Mineral dust: non-spherical coarse aerosols
- Sea salt: optically non-light-absorbing coarse particles
- Black carbon: light-absorbing fine particles

How **Internally mixed aerosols** are handled?
Are they optically detectable?

→ Polluted dust was observed with $2\beta+1\delta$ lidars and identified with a Polarization Optical Particle Counter (POPC).

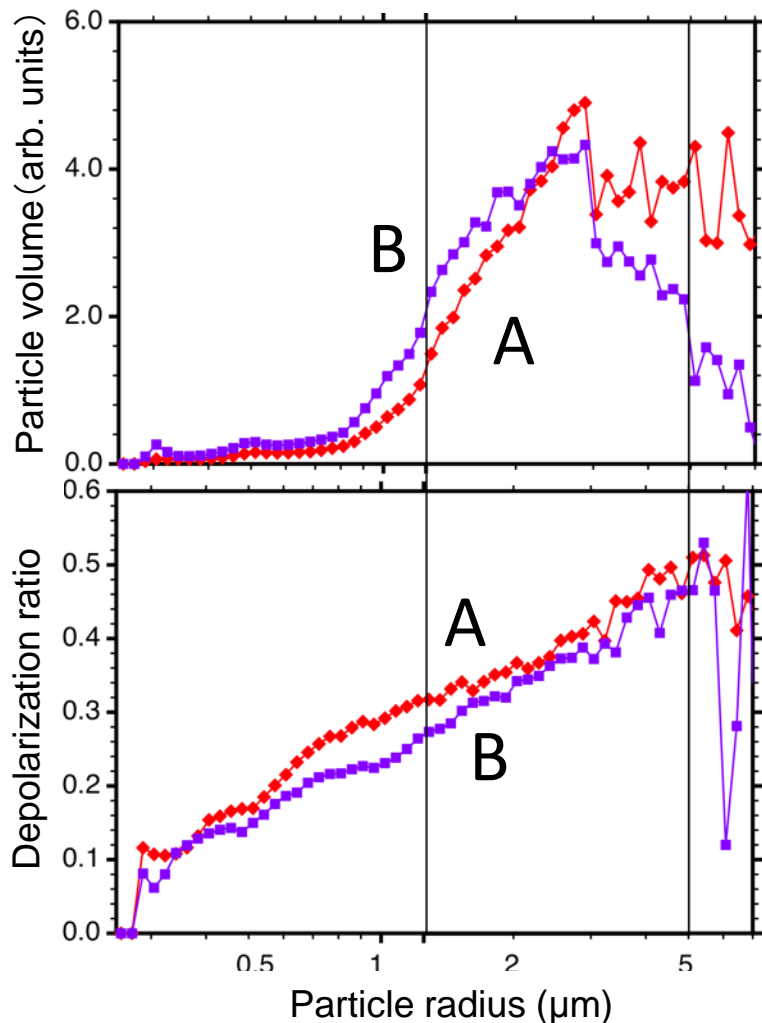
Asian dust internally mixed with air-pollution aerosols observed with a polarization optical particle counter (in Seoul April 2013)



Forward scattering intensity and the backward depolarization ratio are measured simultaneously for every single particle.

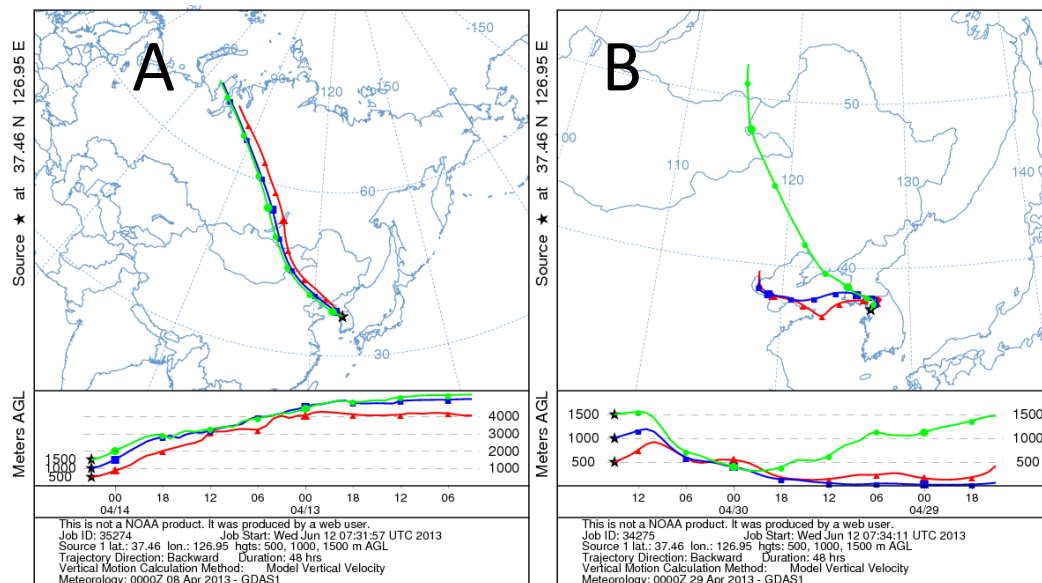
Optical characteristics of pure and polluted Asian dust (Seoul, Apr. 2013)

Polarization OPC

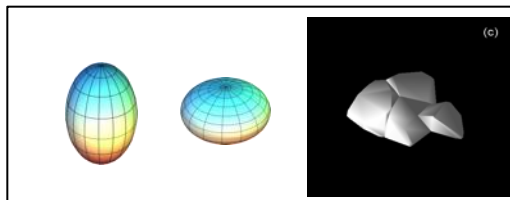
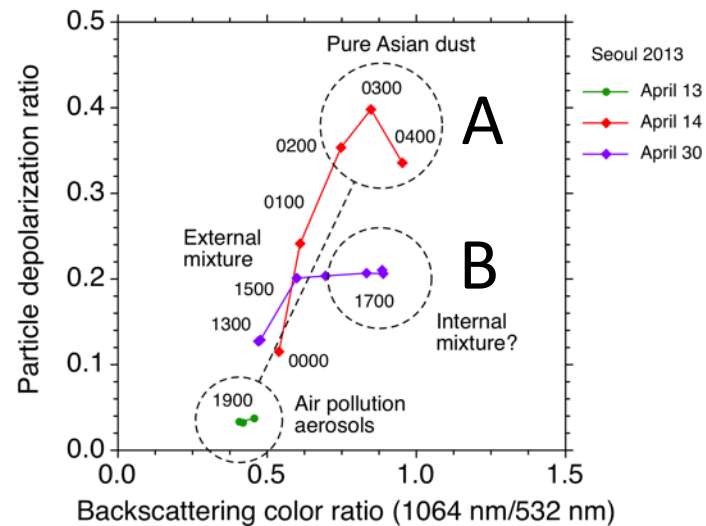


A: Relatively pure dust case (April 14, 2013, 0300 UTC; RH=22%)
 B: Polluted dust case (April 30, 2013, 1500 UTC; RH=66%)

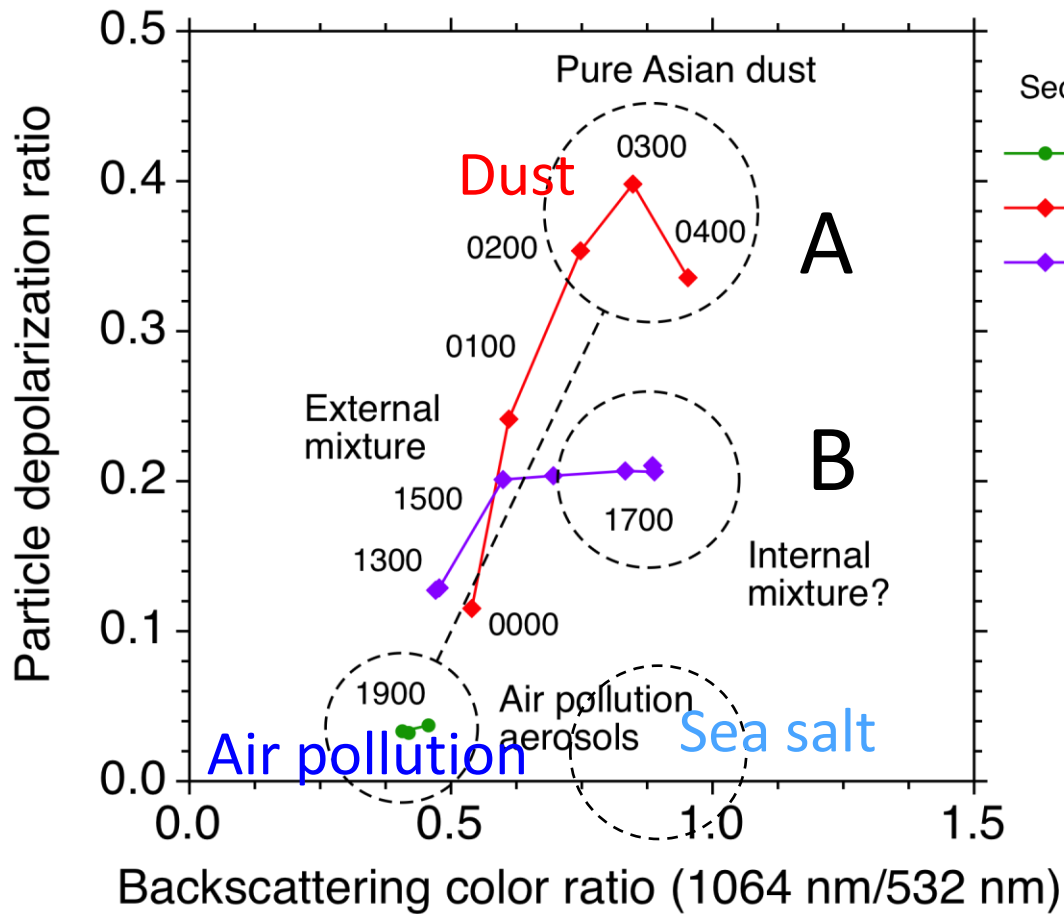
Back trajectory



$2\beta+1\delta$ Lidar



Seeking optical models for pure and polluted dust

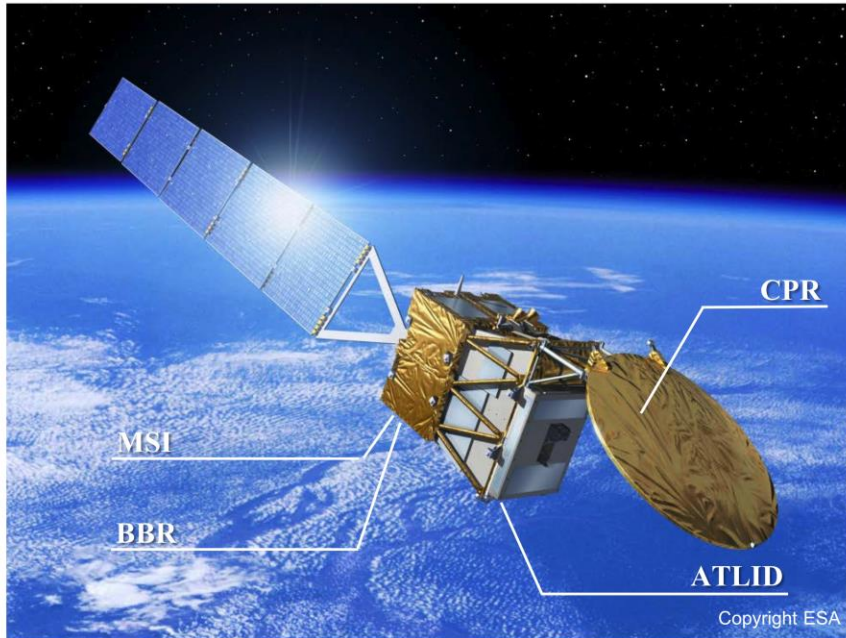
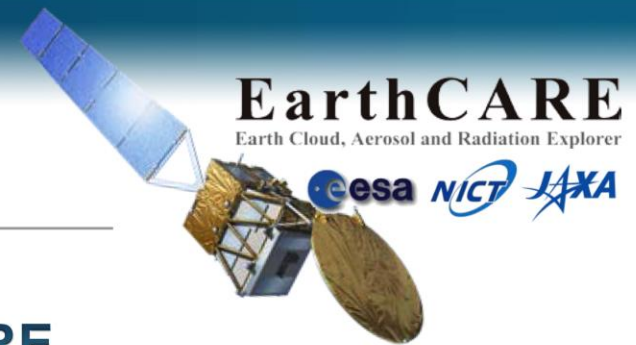


Polluted dust is interpreted as external mixture of dust and sea salt in aerosol component analysis.

→ Data assimilation may solve the problem

$2\beta+1\delta$ Lidar

EarthCARE Satellite



Institutions	European Space Agency (ESA) / National Institute of Information and Communications Technology (NICT) / Japan Aerospace Exploration Agency (JAXA)
Launch	2015 using Soyuz or Zenit (by ESA)
Mission Duration	3-years
Mass	Approx. 2200kg
Orbit	Sun-synchronous sub-recurrent orbit Altitude: approx. 400km Mean Local Solar Time (Descending): 14:00
Repeat Cycle	25 days
Orbit Period	5552.7 seconds
Semi Major Axis	6771.28 km
Eccentricity	0.001283
Inclination	97.050°

EarthCARE

Earth Clouds, Aerosol and Radiation Explorer

ATLID: HSRL at 355 nm

Observation Instruments on EarthCARE

- CPR** Cloud Profiling Radar
- ATLID** Atmospheric Lidar
- MSI** Multi-Spectral Imager
- BBR** Broadband Radiometer



Synergetic Observation by 4 sensors

ATLID L2A & ATLID+MSI L2B products

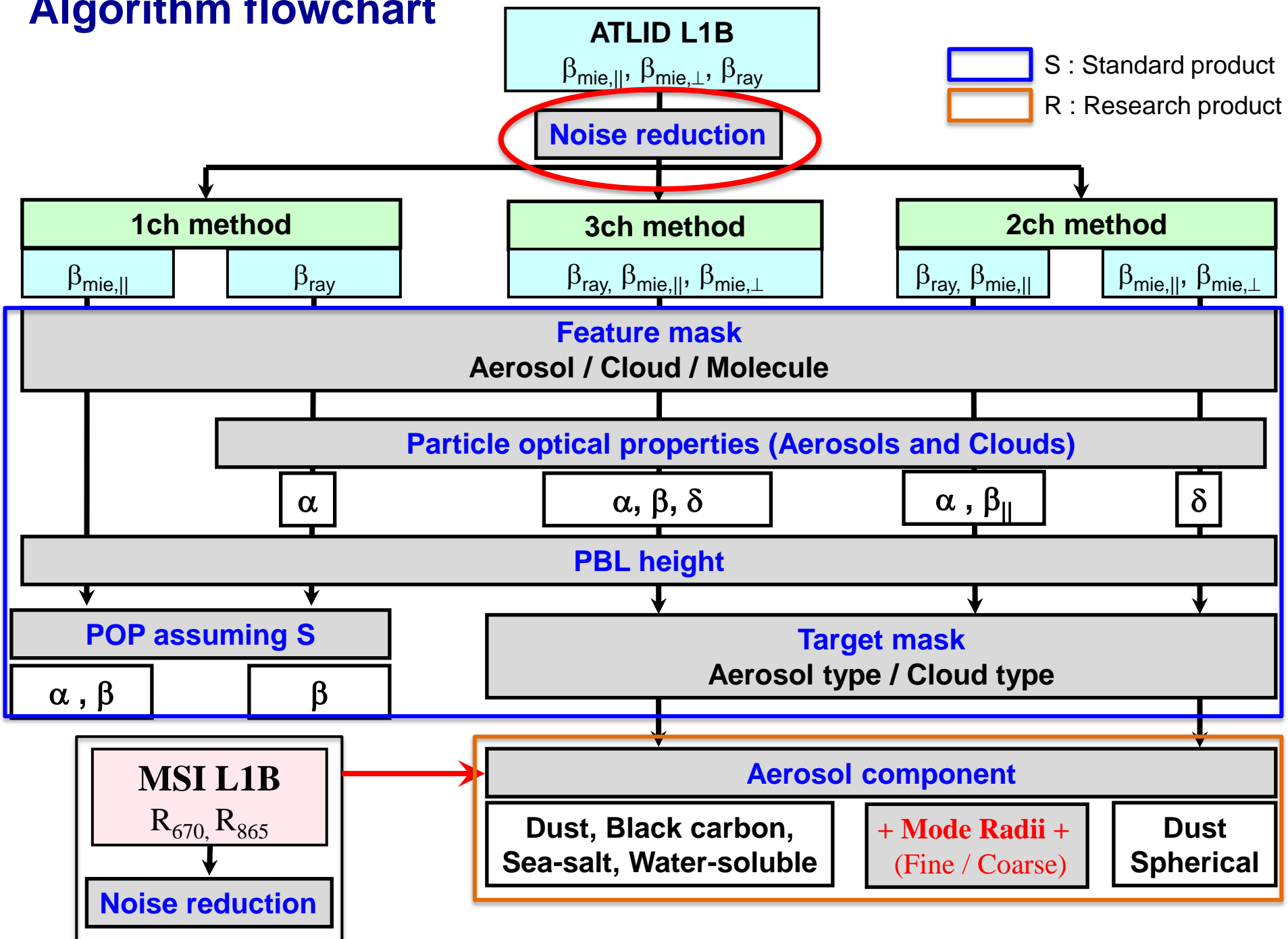
	Parameter	Used ATLID channel			Resolution (Note)
		1ch	2ch	3ch	
ATLID L2A (S)	Feature mask (Molecule/Aerosol/Cloud classification)	○	○	○	$\Delta Z=0.1\text{km}$ $\Delta H = 0.285\text{km}/1\text{km}/10\text{km}$
	Target mask (Cloud type/Aerosol type classification)	×	○	○	$\Delta Z=0.1\text{km}$ $\Delta H = 1\text{km}/10\text{km}$
	Aerosol optical property (Extinction, Backscatter, Depolarization , Lidar ratio)	△	△	○	$\Delta Z=0.1\text{km}$ $\Delta H = 1\text{km}/10\text{km}$ (1ch, 2ch: S1 assumption)
	Cloud optical property (Extinction, Backscatter, Depolarization, Lidar ratio)	△	△	○	$\Delta Z=0.1\text{km}$ $\Delta H = 1\text{km}/10\text{km}$ (1ch, 2ch: S1 assumption)
	Planetary boundary layer height	○	○	○	$\Delta H = 1\text{km}/10\text{km}$
ATLID L2A (R)	Extinction of aerosol components (Dust, Sea-salt, Water-soluble, Black carbon)	×	○	○	$\Delta Z=0.1\text{km}$ $\Delta H = 10\text{km}$ (2ch: Dust, Water-soluble)
ATLID-MSI L2B (R)	Extinction of aerosol components	×	○	○	$\Delta Z=0.1\text{km}$ $\Delta H = 10\text{km}$
	Mode radii (Fine and Coarse)	×	○	○	$\Delta H = 10\text{km}$ (Constant in a column)

Validation: Comparison for various cases

✓ Clean/Dirty ✓ Land / Ocean, ✓ Industrial / rural

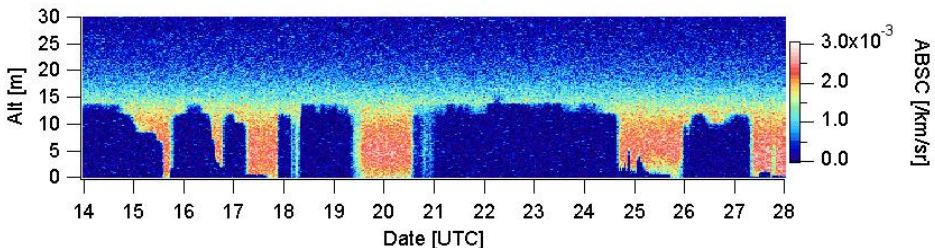
✓ Asia / Europe / America ... ✓ Dust / Biomass-burning / Pollution ...

Algorithm flowchart

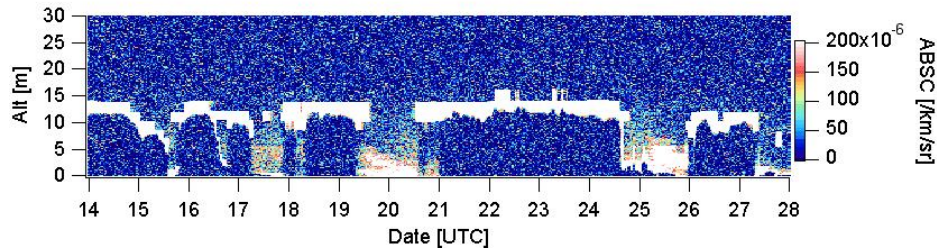


Noise reduction by Discrete Wavelet analysis

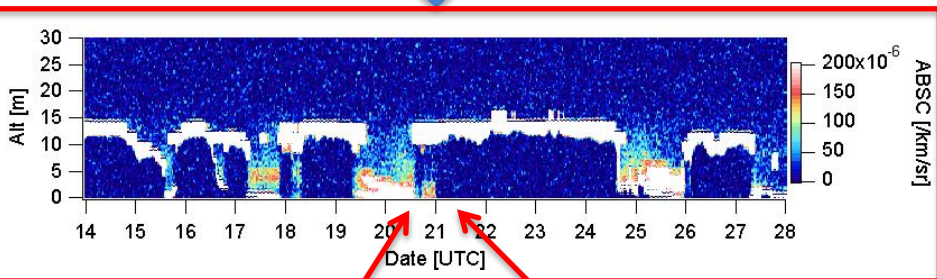
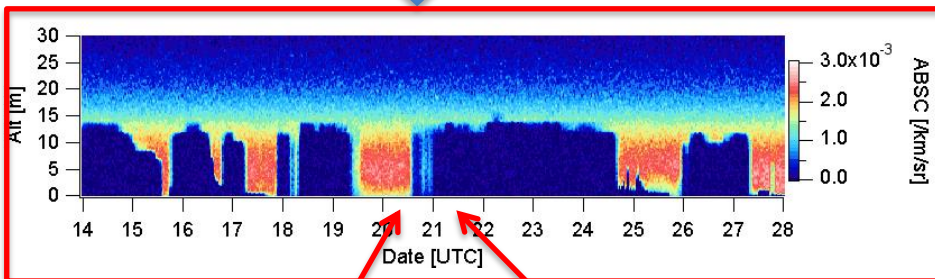
Rayleigh with random noises (SN~10)



Mie copol with random noises (SN~10)



Apply wavelet analysis



SN becomes twice (SN ~ 20)

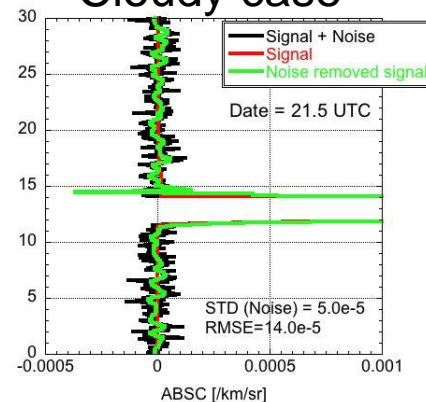
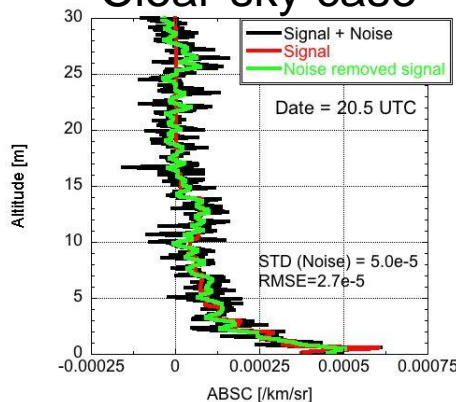
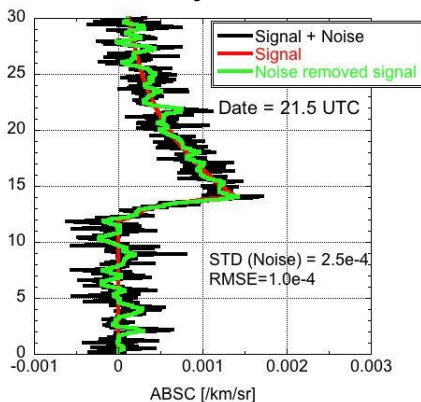
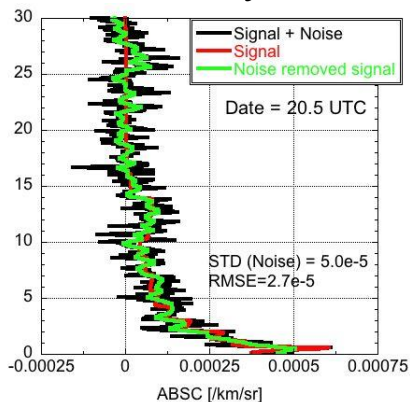
SN becomes twice (SN ~ 20)

Clear-sky case

Cloudy case

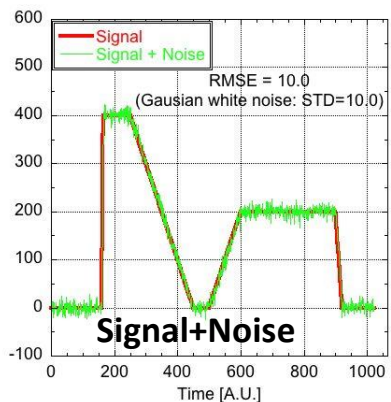
Clear-sky case

Cloudy case

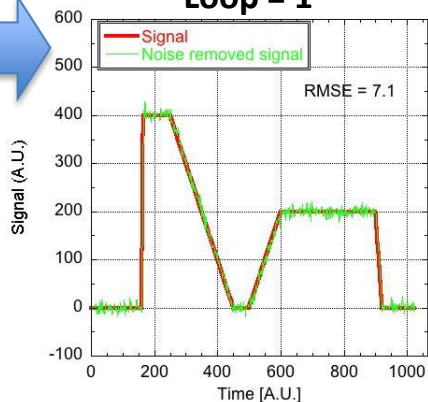


Iterative computation

Daubechies
(N=6)

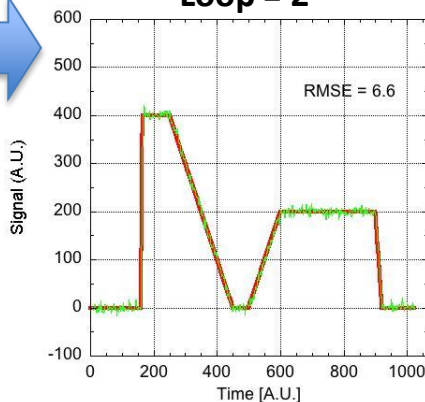


Loop = 1



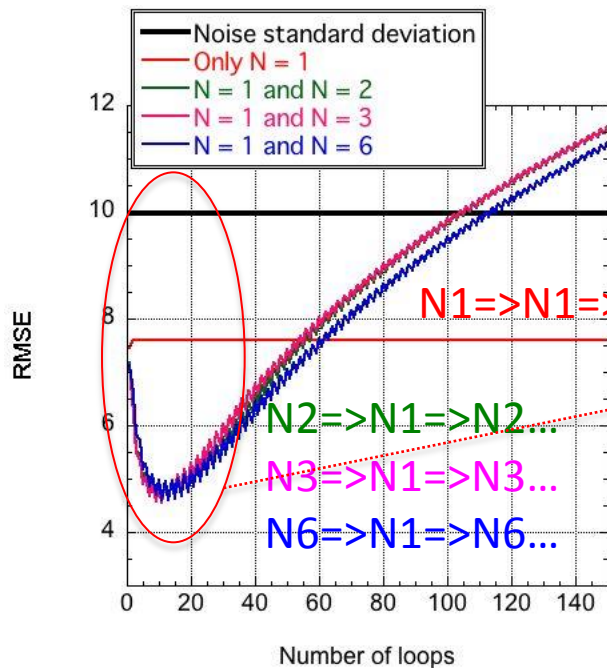
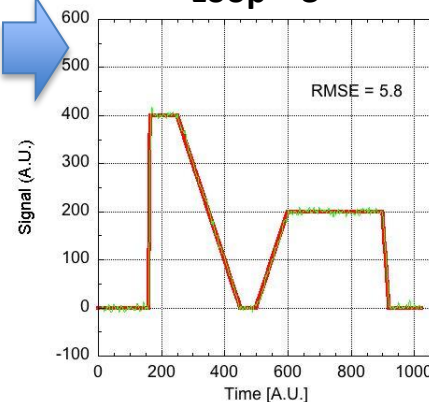
Daubechies
(N=1)

Loop = 2



Daubechies
(N=6)

Loop = 3

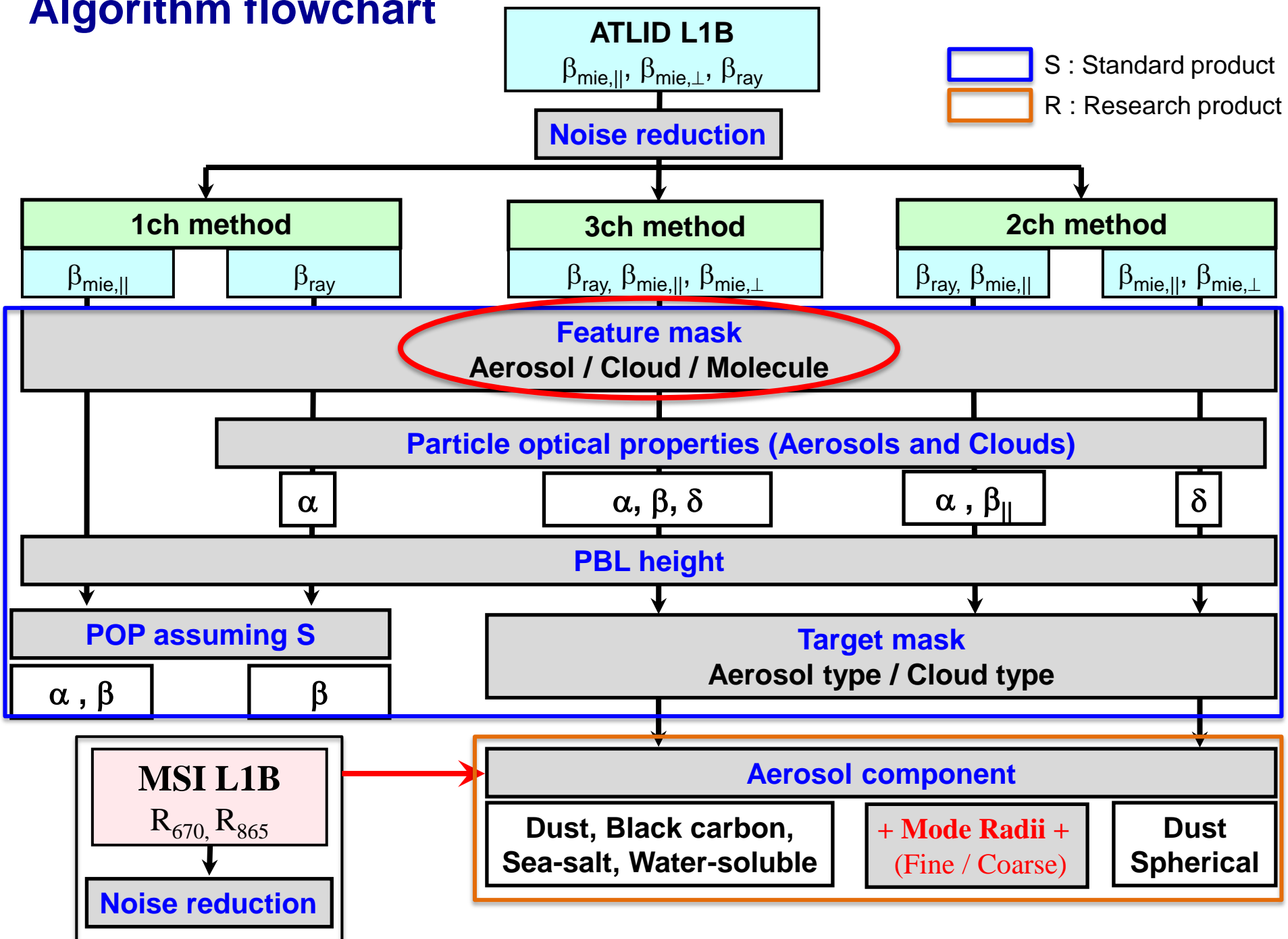


Noise STD

N6=>N1=>N6

Noises are reduced by 50%
($\Delta\text{Noise} \sim -50\%$)

Algorithm flowchart



Vertical feature mask

Identify molecule-rich, aerosol-rich, or cloud-rich slab layer using the threshold method [Vaughan et al 2009; Hagihara et al. 2009]:

Molecule-rich: $P_{r,noise} > P_r$

Aerosol-rich: $P_{r,cloud} + P_{r,noise} > P_r > P_{r,noise}$

Cloud-rich: $P_r > P_{r,cloud} + P_{r,noise}$

$P_{r,noise}$: Noise level, $P_{r,cloud}$: Threshold for cloud-rich slab layer

P_r : Diagnostic parameter derived from ATLID L1b data

3ch method:
$$P_r = \frac{b}{b_m} = \frac{b_{mie,||} + b_{mie,\wedge}}{b_{ray}}$$

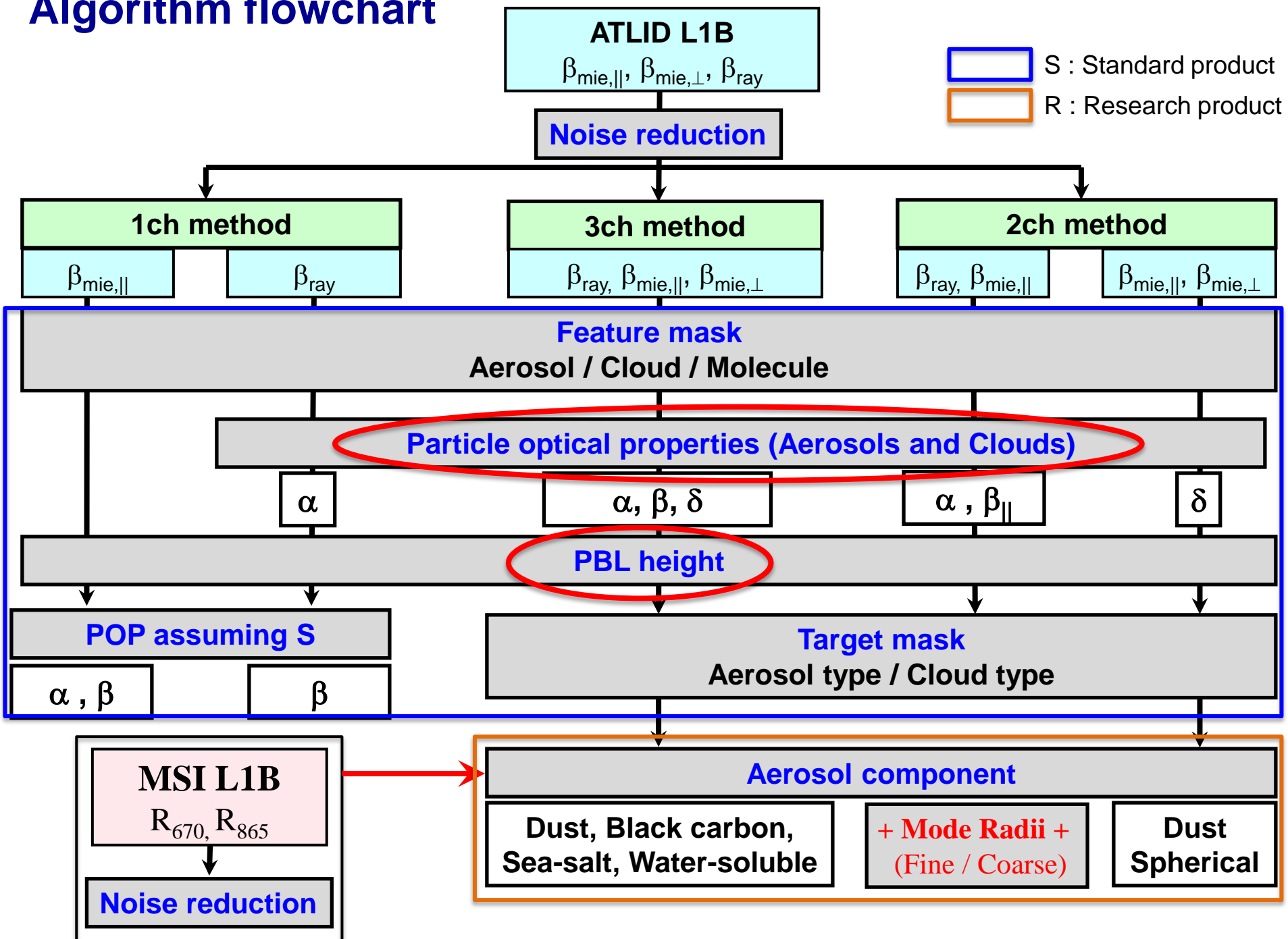
2ch method ($\beta_{mie,||}$, β_{ray}):
$$P_r = \frac{b_{||}}{b_m} = \frac{b_{mie,||}}{b_{ray}}$$

2ch method ($\beta_{mie,||}$, $\beta_{mie,\perp}$):
$$P_r = \frac{b(z) \exp\left[-2 \int_{\hat{z}}^{z_{ATLID}} a(z') dz'\right]}{\int_{\hat{z}}^{z_{ATLID}} a_m(z') dz'} = \frac{b_{mie,||} + b_{mie,\wedge}}{\int_{\hat{z}}^{z_{ATLID}} a_m(z') dz'}$$

1ch method ($\beta_{mie,||}$):
$$P_r = \frac{b_{||}(z) \exp\left[-2 \int_{\hat{z}}^{z_{ATLID}} a(z') dz'\right]}{\int_{\hat{z}}^{z_{ATLID}} a_m(z') dz'} = \frac{b_{mie,||}}{\int_{\hat{z}}^{z_{ATLID}} a_m(z') dz'}$$

1ch method (β_{ray}):
$$P_r = a(z)$$

Algorithm flowchart



Equations for deriving α , β , and δ

Level 1

$$P_{Mie,co} = b_{Mie,co} \exp\left[-2 \int_{\hat{z}}^{z_{ATLID}} (S_{Mie} + S_{Ray}) dz\right] \quad \text{[Mie co-pol]} \quad \textcircled{1}$$

$$P_{Mie,cr} = b_{Mie,cr} \exp\left[-2 \int_{\hat{z}}^{z_{ATLID}} (S_{Mie} + S_{Ray}) dz\right] \quad \text{[Mie cr-pol]} \quad \textcircled{2}$$

$$P_{Ray,co} = b_{Ray,co} \exp\left[-2 \int_{\hat{z}}^{z_{ATLID}} (S_{Mie} + S_{Ray}) dz\right] \quad \text{[Ray co-pol]} \quad \textcircled{3}$$

Level 2

$$a = S_{Mie} = \frac{1}{2} \frac{d \ln P_{Ray,co}}{dz} - S_{Ray} \quad \leftarrow \textcircled{3}$$

$$d = \frac{b_{Mie,cr}}{b_{Mie,co}} = \frac{P_{Mie,cr}}{P_{Mie,co}} \quad \leftarrow \textcircled{1} + \textcircled{2}$$

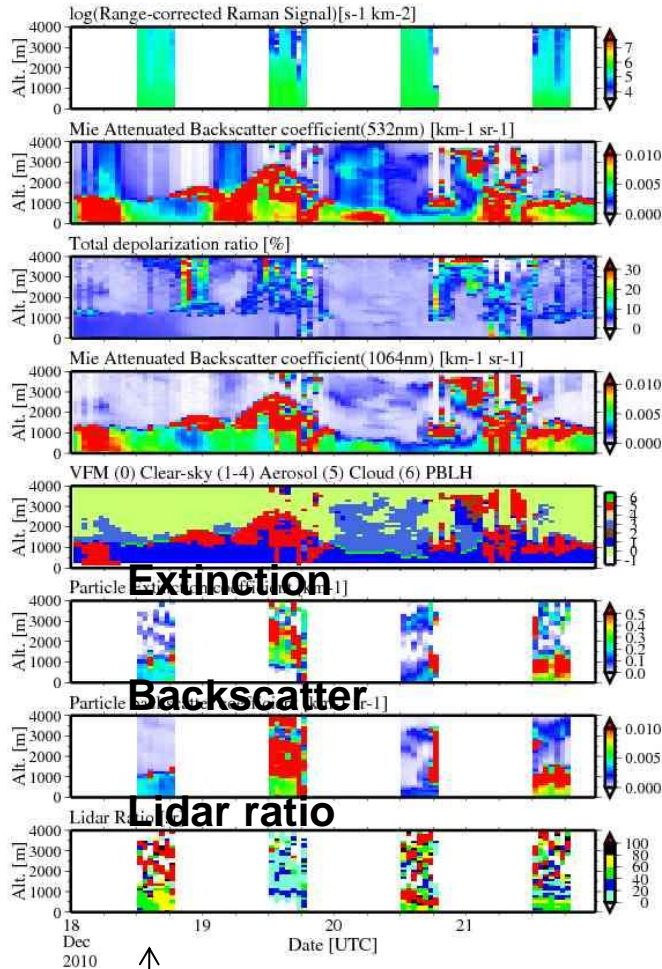
$$b = b_{Mie,co} + b_{Mie,cr} = (1 + d)b_{Mie,co} = (1 + d) \frac{P_{Mie,co}}{P_{Ray,co}} b_{Ray,co} \quad \leftarrow \textcircled{1} + \textcircled{2} + \textcircled{3}$$

Testing particle extinction retrievals

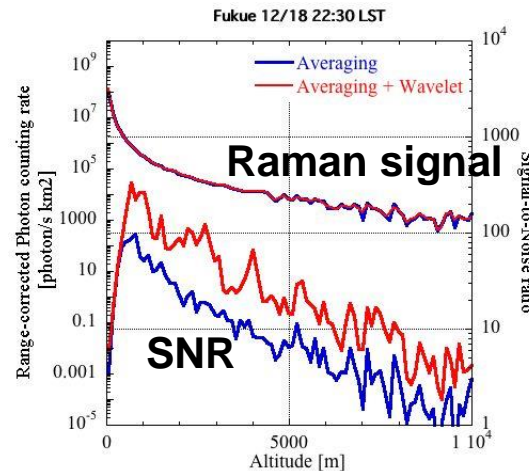
using AD-Net ground-based Raman lidar at 532nm

- ✓ Signal noise reduction
Observed data ($\Delta Z=30m, \Delta t=15min$)
→ Averaging ($\Delta Z=120m, \Delta t=1hour$) + Wavelet analysis

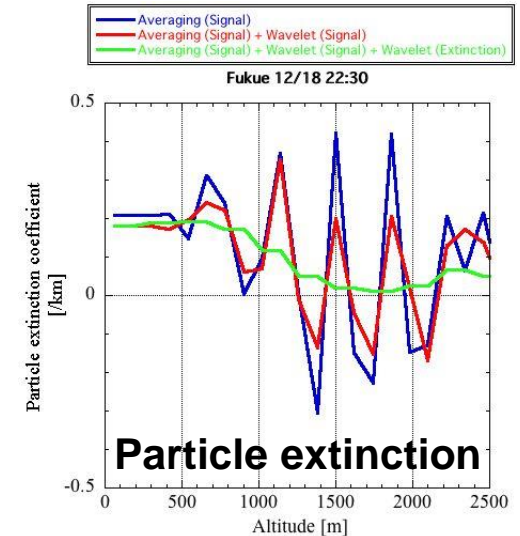
- ✓ Particle extinction is derived by direct method
- ✓ PBLH is retrieved by using vertical gradient of 1um backscatter data [Sugimoto et al. 2009].



Blue : Only averaging, **Red** : Wavelet + Averaging
Green: Wavelet + Averaging + Wavelet (extinction)



SNR is improved by three times by wavelet analysis



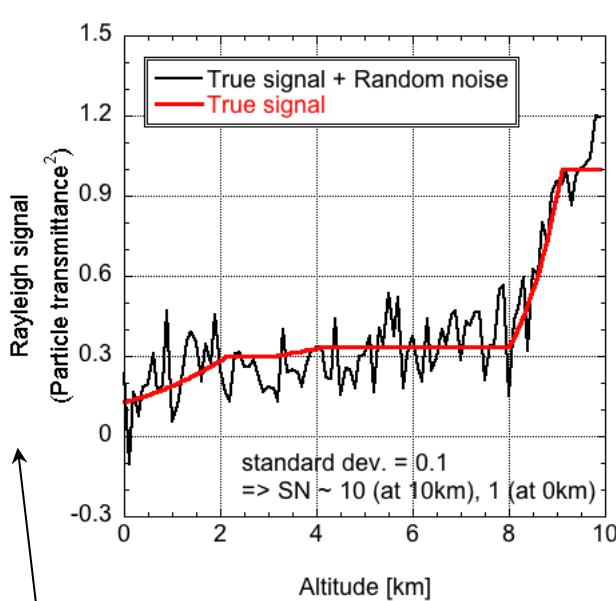
We improve estimation accuracy by applying wavelet to derived extinction.

SNR is defined as $SNR = \text{Signal} / \text{Standard deviation} (\Delta Z=120m, \Delta t=1hour) \times \sqrt{N}$

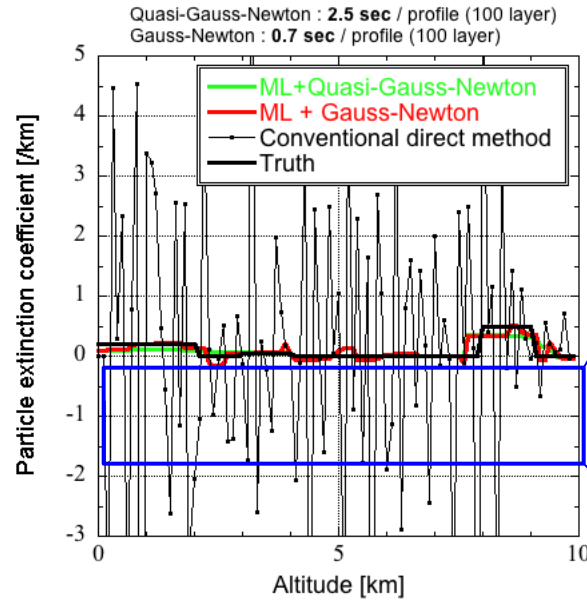
Use of Inversion method to reduce noise

Maximum likelihood method (ML)

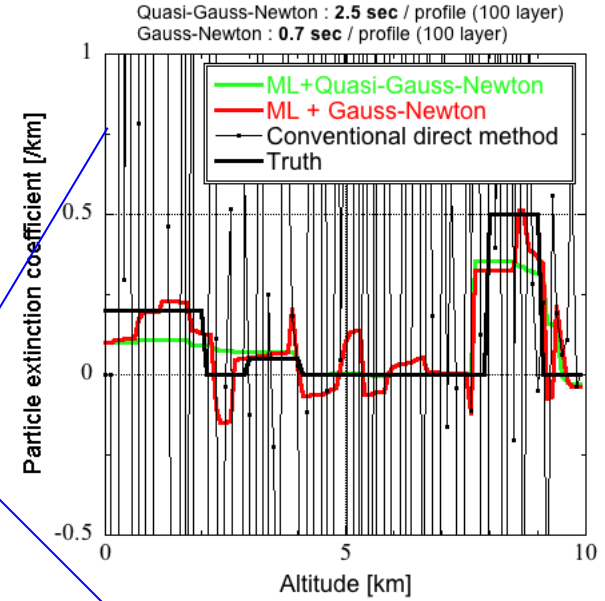
+ Gauss-Newton method



Rayleigh signal



Particle extinction



Particle extinction

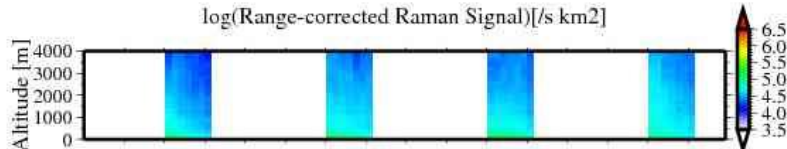
$$T_p^2 = P_{Ray} / b_{mol} / T_{mol}^2$$

- ✓ Inversion method + Smoothing to more improve estimation accuracy
- ✓ Inversion method treating constraints (e.g., Penalty function method)

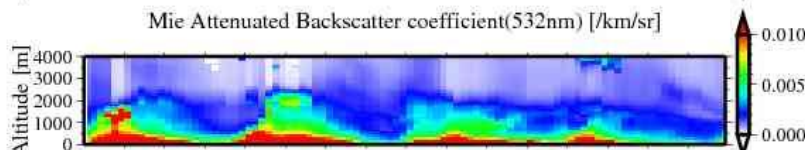
PBL height

[AD-Net Seoul, 12-15 May. 2010,
Ground-based Mie-Raman lidar]

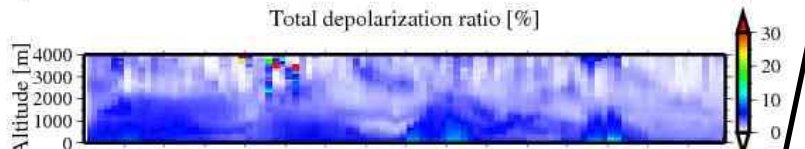
Raman signal
(607nm)



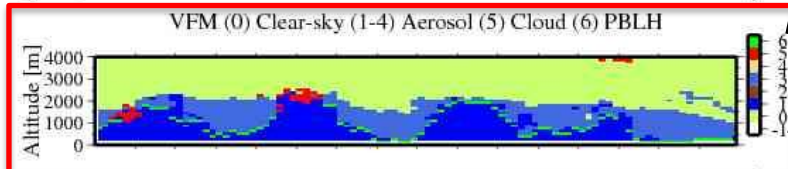
Attenuated
Backscatter
(532nm)



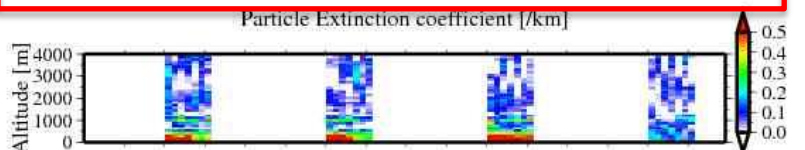
Total dep.
(532nm)



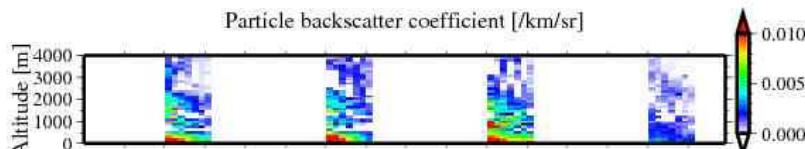
Feature mask



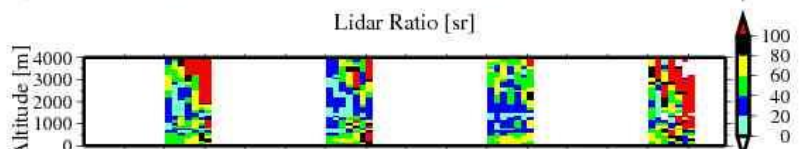
Particle
Extinction
(532nm)



Particle
Backscatter
(532nm)



Lidar ratio
(532nm)



Feature mask

- Blue** : Spherical aerosols
- Brown** : non-spherical aerosols
- Red** : Clouds
- Yellowish green** : Molecules
- Green** : PBL height

* Use 1064 attenuated backscatter and
532nm total depolarization data
[Shimizu et al., 2004; Hagihara et al., 2010]

$\sim 0.3 \text{ km}^{-1}$

$\Delta Z = 120 \text{ m}$

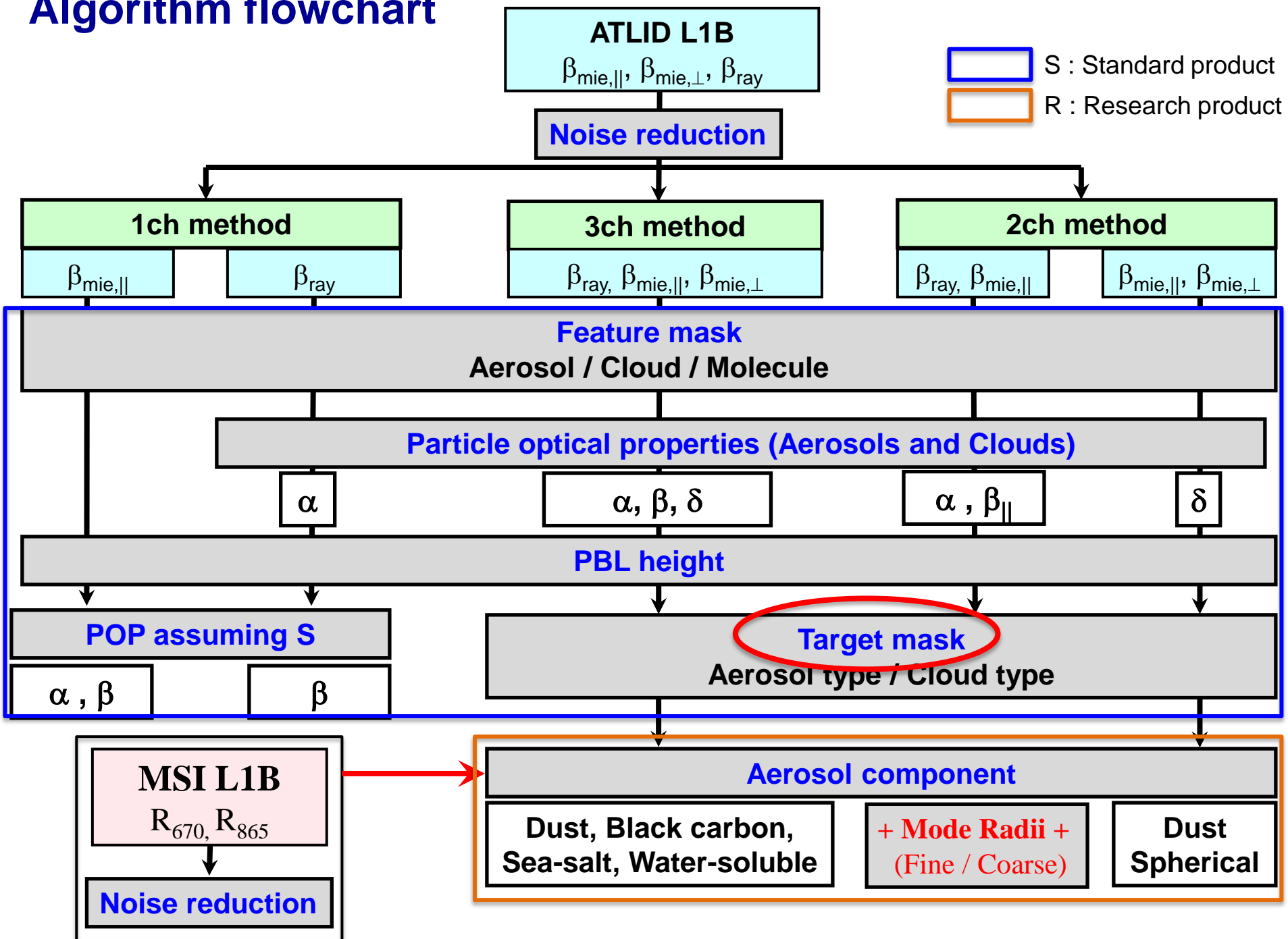
$\Delta T = 60 \text{ min}$

$\sim 0.005 \text{ sr}^{-1} \text{ km}^{-1}$

40~80 sr

12 May 2010
Date [UTC]

Algorithm flowchart



Aerosol Target Mask

Aerosol layer is classified into several types like CALIPSO aerosol types, **Clean-continental (CC)**, **Polluted continental (PC)**, **Polluted dust (PD)**, **Desert dust (DD)**, **Marine (MA)**, **Smoke (SM)**, and so on, using particle lidar ratio (S) and depolarization ratio (δ), and particle backscatter (β) with information on altitude, location, and surface type.

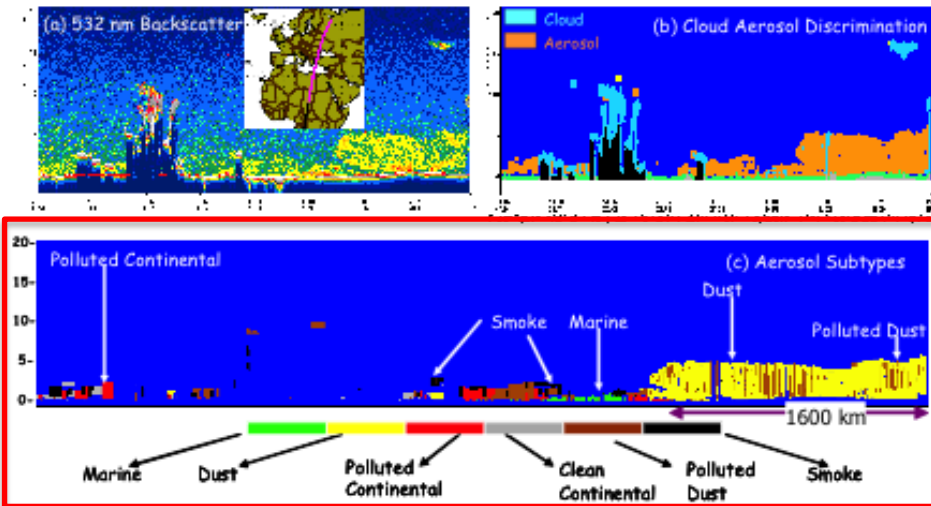
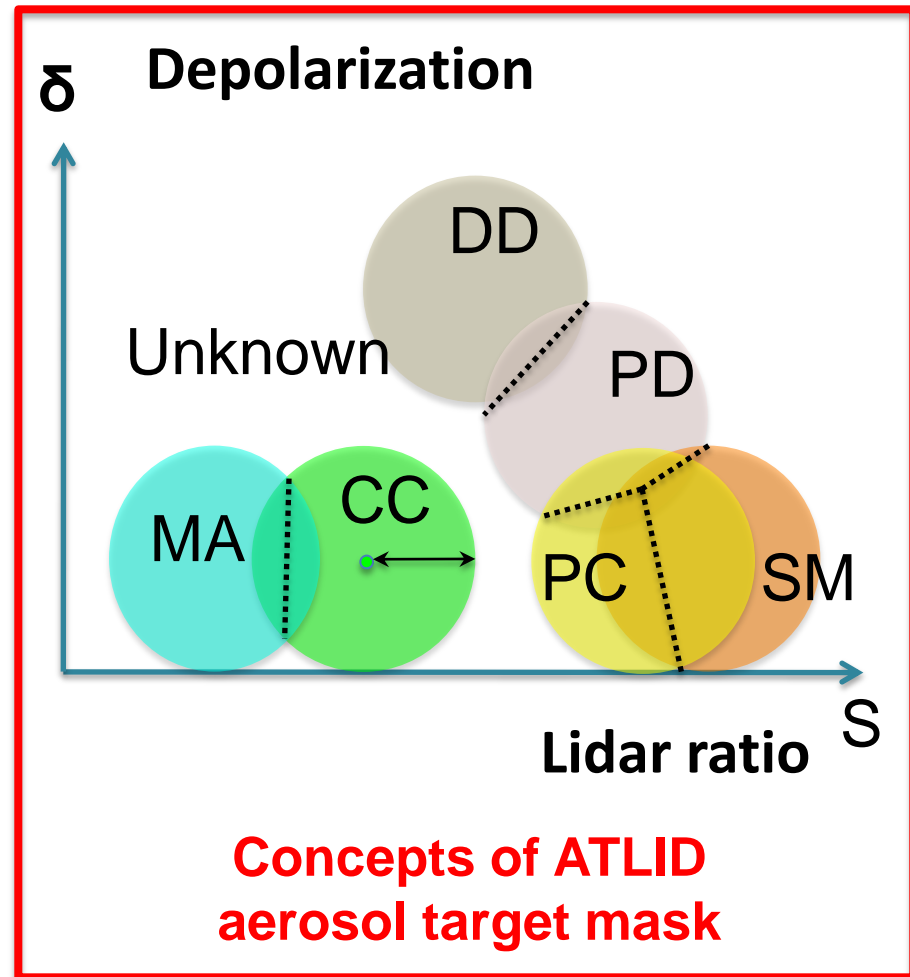


Figure 5 (a) 532-nm backscatter browse image, (b) cloud/aerosol feature mask, and (c) the aerosol subtyping plot of the same scene showing all the six aerosol types for this orbit section observed on Aug. 8, 2006. The relative scales of the three figures are as in Fig. 3

CALIOP aerosol target mask

[Omar et al. JTECH, 2009]



Cluster Analysis Using AERONET Data

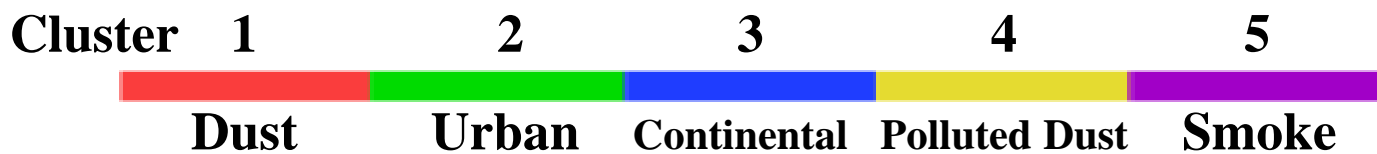
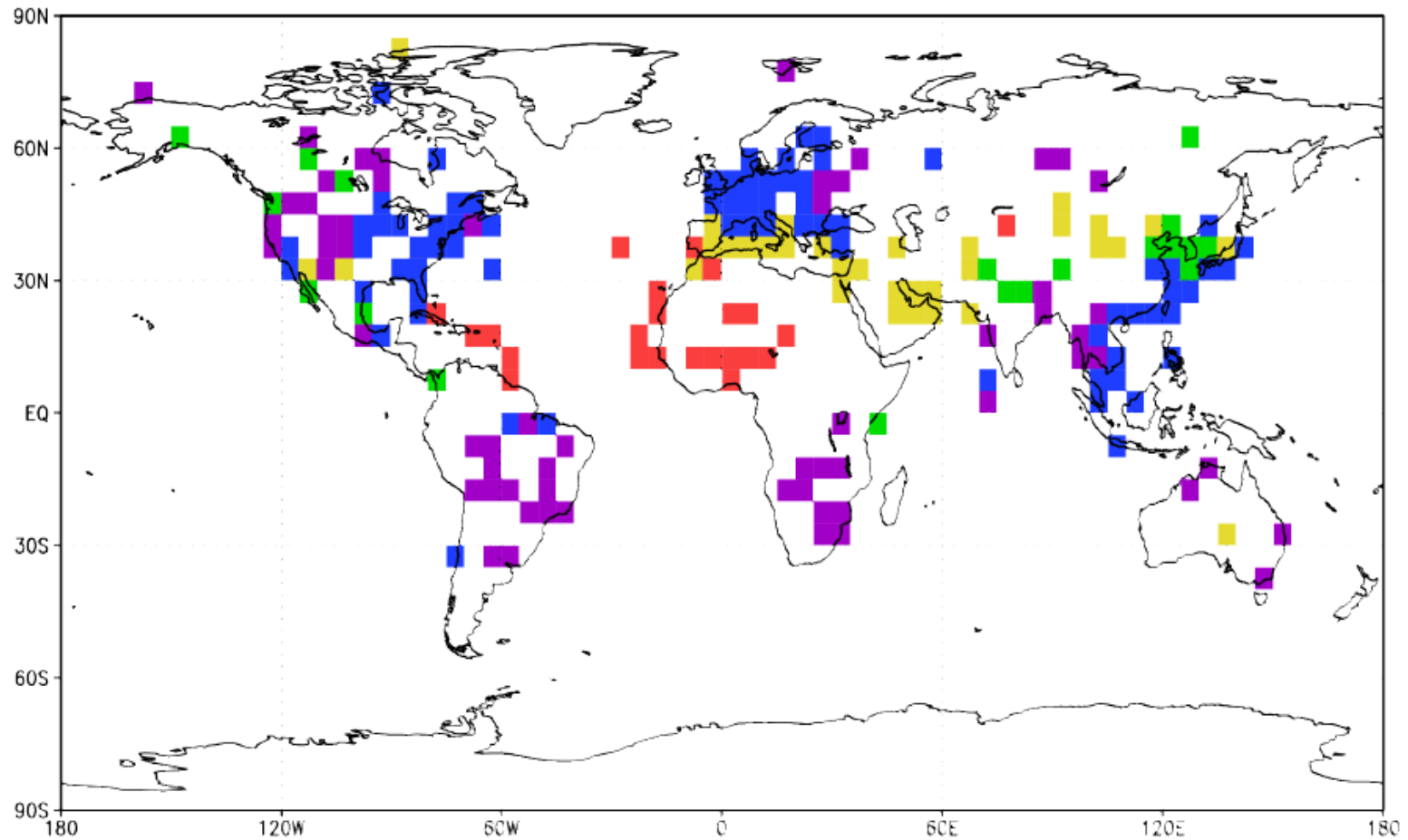
Method : Fuzzy c means

Data : AERONET Level 2 (1992 ~ 2012)

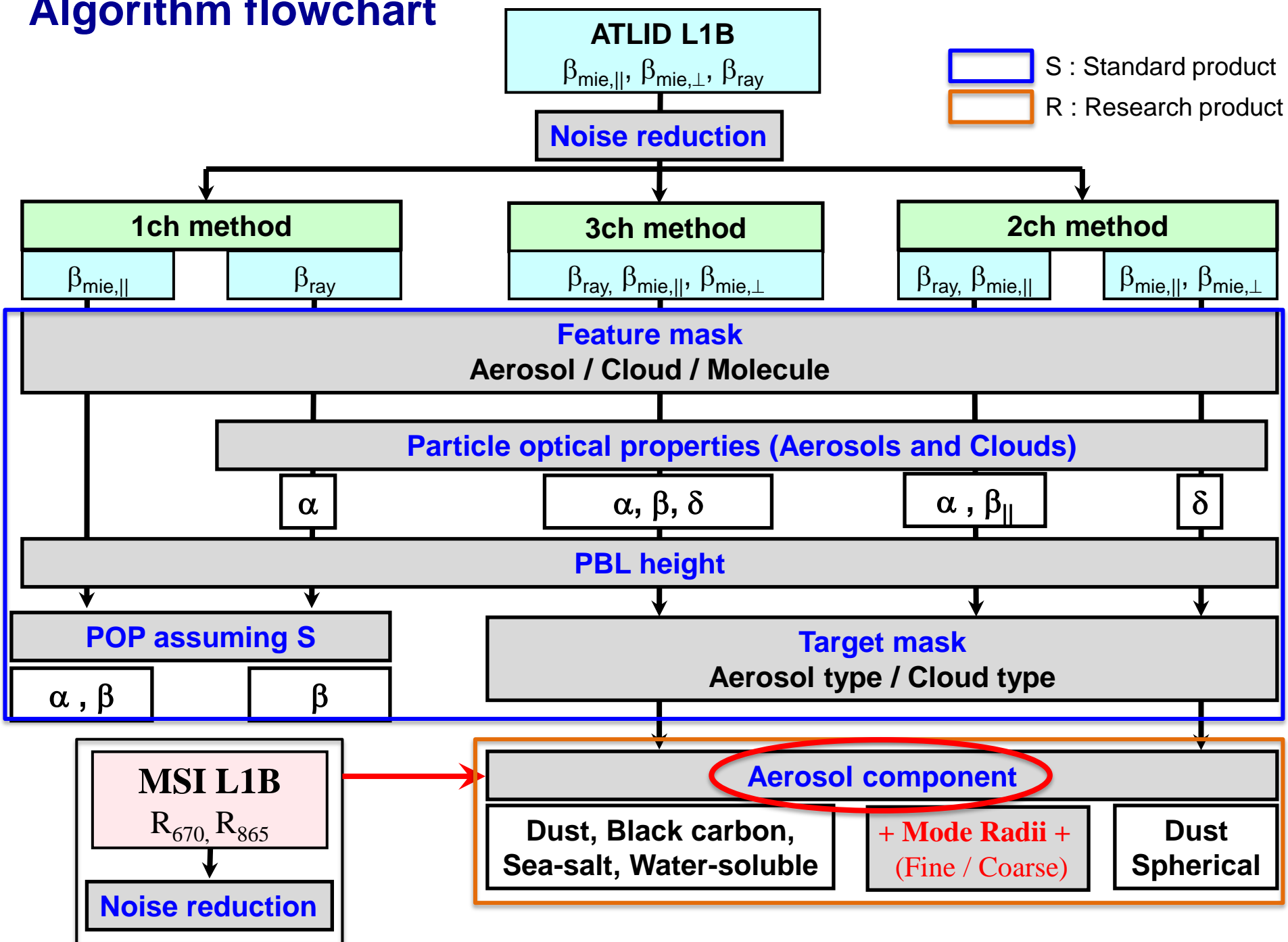
Input Parameters: 31 Parameters

AE (440-675/440-869/440-1020), AAE(440-675/440-869/440-1020),
SSA(440/675/869/1020), ASYM(total) (440/675/869/1020),
ASYM(fine) (440/675/869/1020), ASYM(coarse) (440/675/869/1020),
mr (440/675/869/1020), Eff. Rad (total), Eff. Rad. (fine), Eff. Rad (coarse),
Fine Mode Fraction, sphericity

Locations of the 5 clusters



Algorithm flowchart



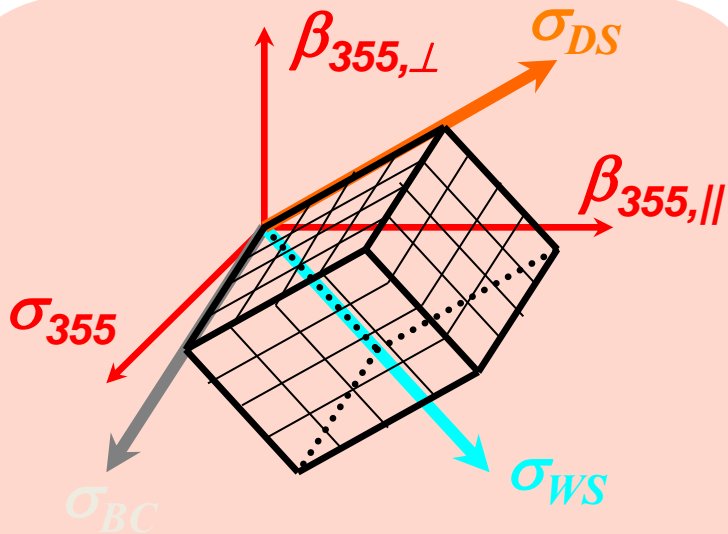
NIES $1\alpha + 1\beta + 1\delta$ algorithm (Type B)

Over Sea

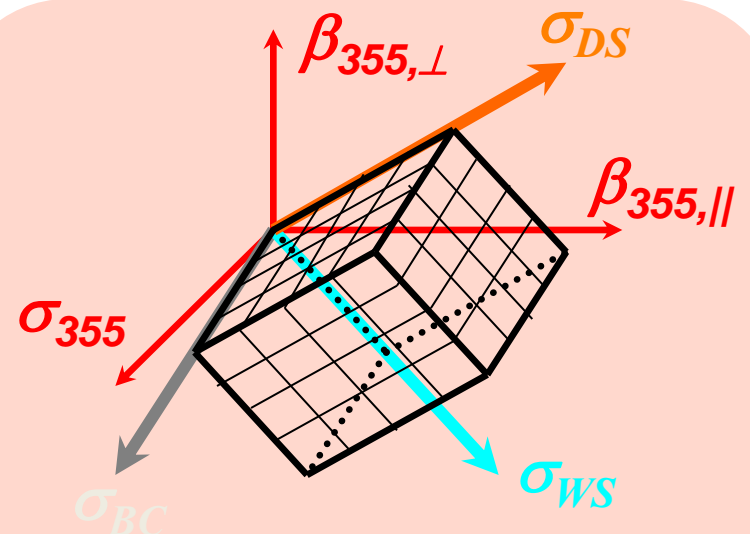
Over Land

Wind data
(Sea-surface)

σ_{SS}

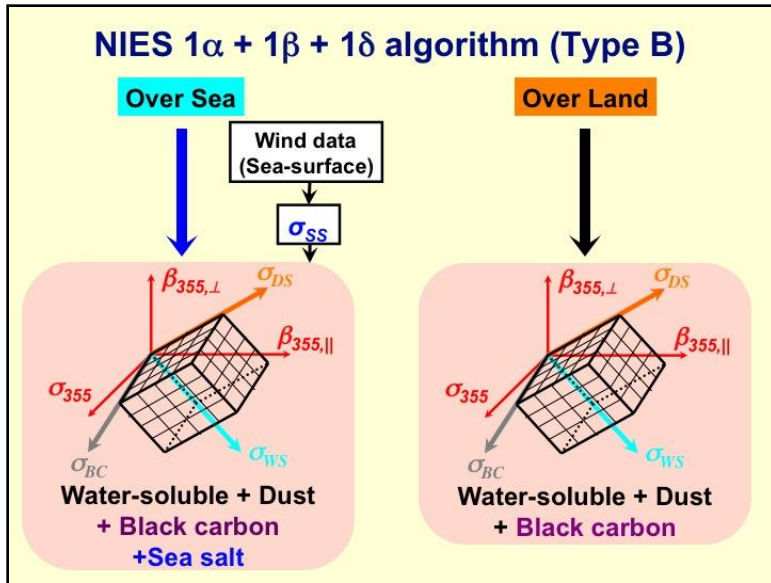


Water-soluble + Dust
+ Black carbon
+ Sea salt



Water-soluble + Dust
+ Black carbon

Aerosol component retrieval



Assumption:

✓ External mixture of 4 components at each layer

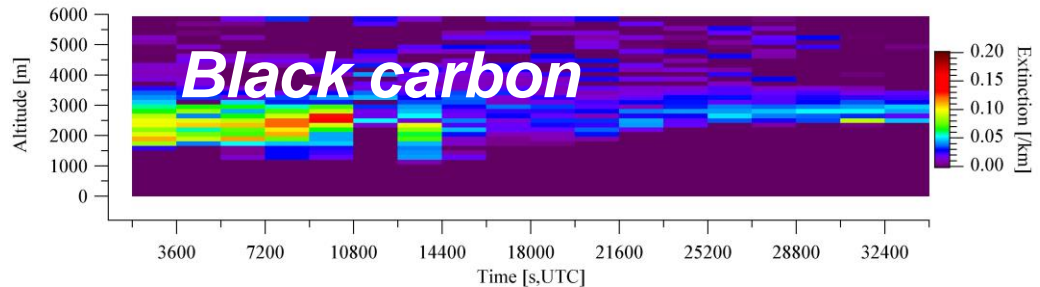
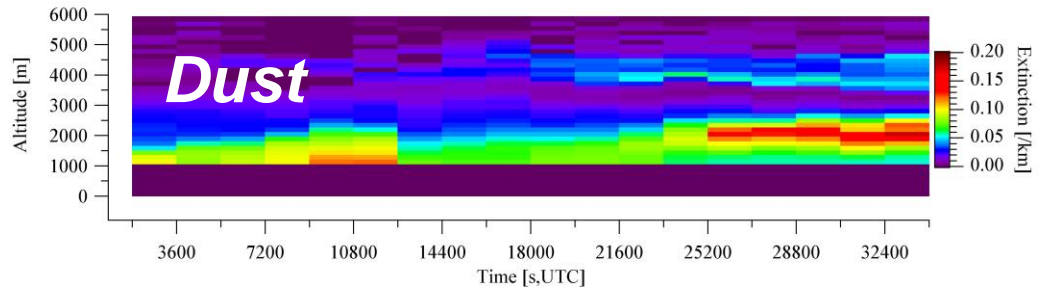
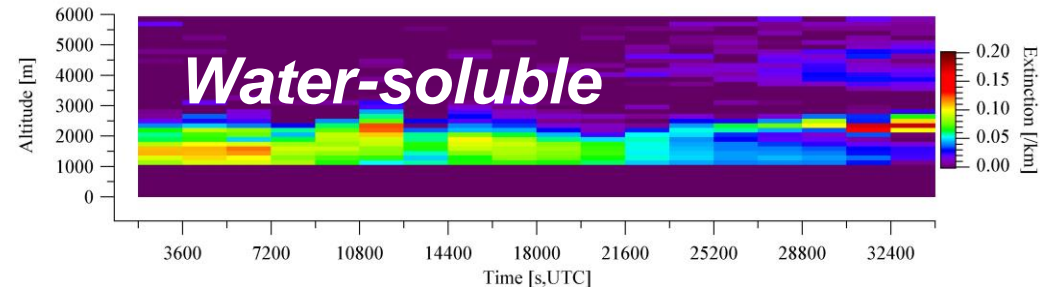
✓ Optical properties for each aerosol component are prescribed (e.g., size dist., lidar ratio etc...)

Water-soluble: moderate-absorption / spherical (small-size)

Dust: moderate absorption / non-spherical (large-size)

Sea-salt: weak-absorption / spherical (large-size)

Black carbon: strong-absorption / spherical (small-size)

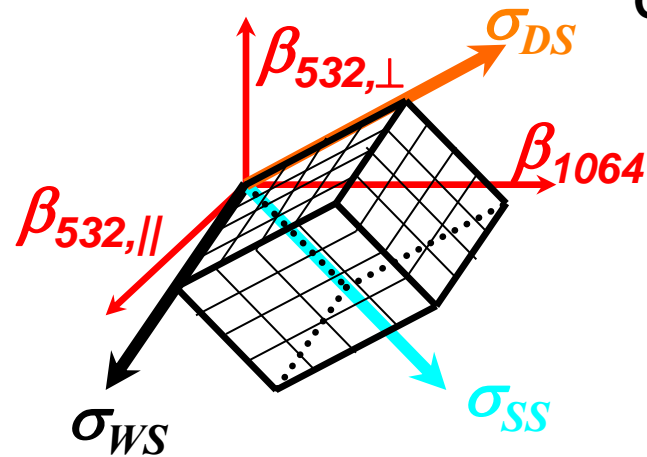


• $1\alpha(532)+1\beta(532)+1\delta(532)$ data measured with HSRL and MSL on Apr. 8 2005 were used in the analysis.

• The aerosol properties at 532 nm used in $2\beta+1\delta$ algorithm were used.

2 β + 1 δ aerosol component retrieval for CALIOP

[Nishizawa et al. 2011]



Optical model (RH=70%)

	WS	SS	DS
r_m	0.13	3.0	2.0
S	55	20	48
δ	0	0	0.3

r_m : mode radius, S : lidar ratio(532nm)
 δ : depolarization ratio (532nm)

Water-soluble: small-size / spherical (moderate-absorption)

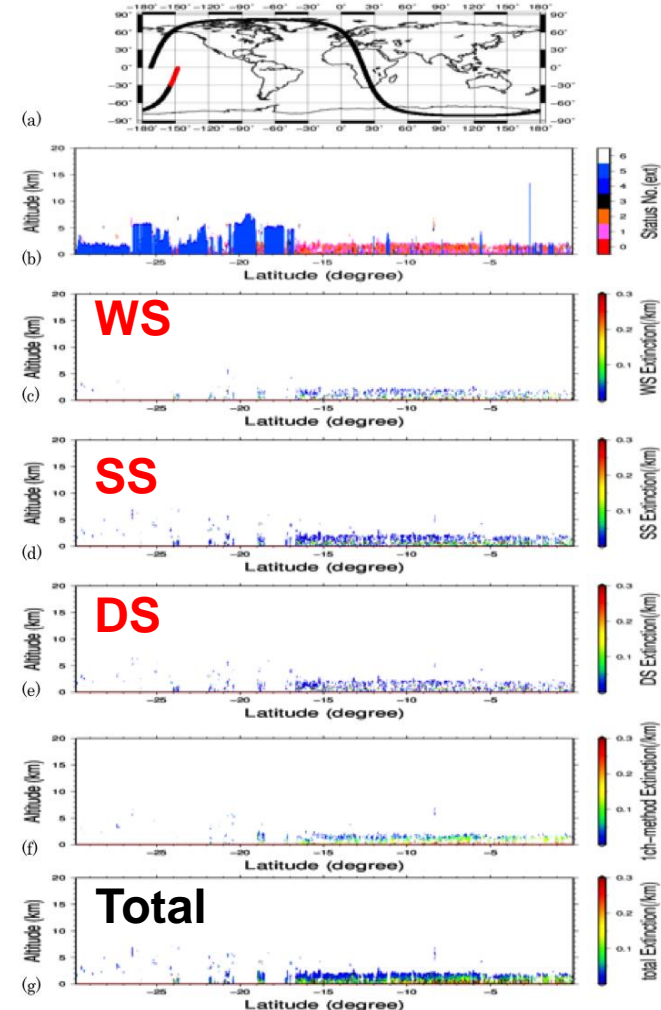
Dust: large-size / non-spherical (moderate absorption)

Sea-salt: large-size / spherical (weak-absorption)

Assumption:

- ✓ External mixture of 3 components at each layer
- ✓ Optical properties are prescribed
- ✓ DS (WS, SS): spheroid (spherical) <= Dubovik et al., [2006]
- ✓ WS, SS : hygroscopic growth
 => Change optical model depending on RH data (ECMWF)

Pacific ocean, 8/2, 2006
 Clean maritime environment
 [Kurogi & Okamoto 2012]

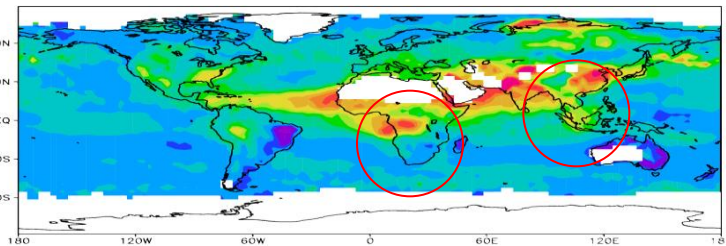
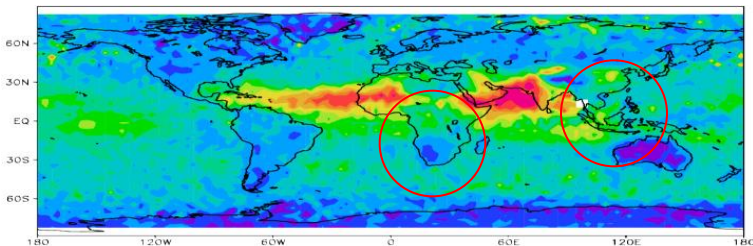


AOT comparison with MODIS (2006-2007)

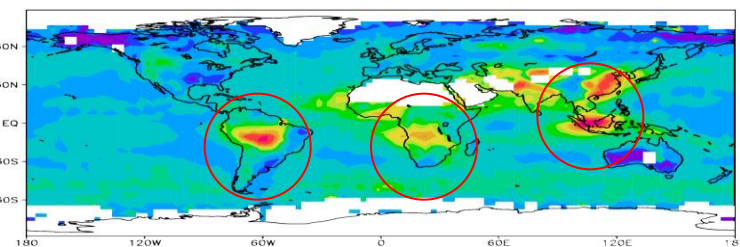
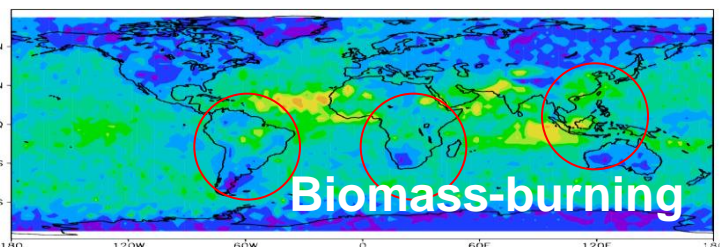
CALIPSO (532nm)

MODIS AOT(550nm)

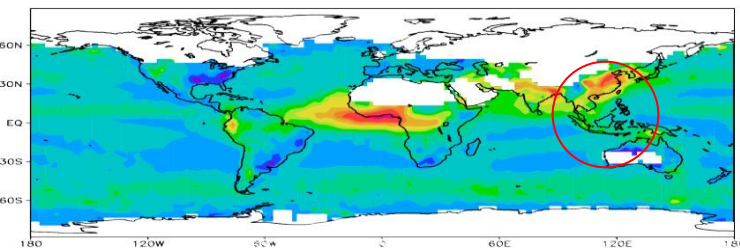
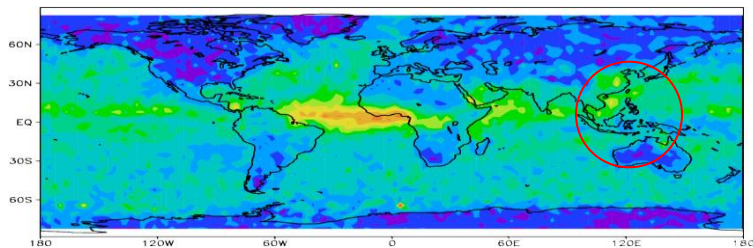
Summer
(JJA)



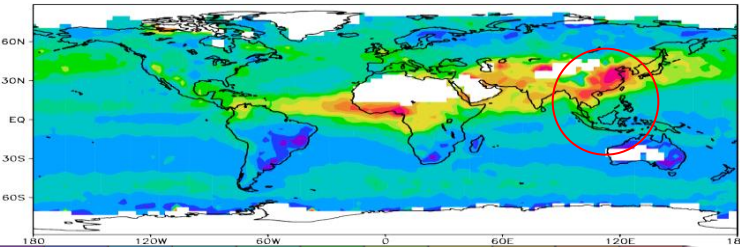
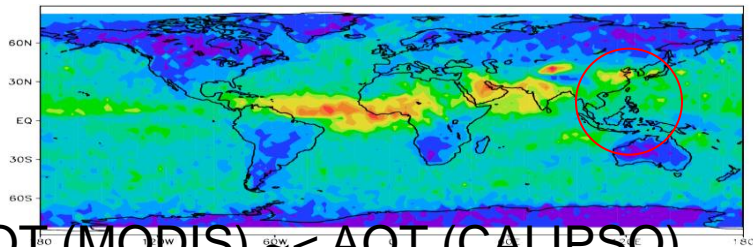
Autumn
(SON)



Winter
(DJF)



Spring
(MAM)

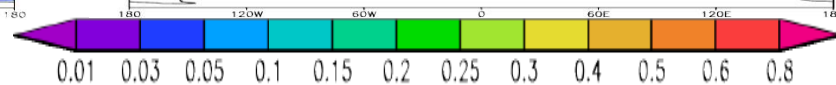


Ocean: AOT (MODIS) \sim < AOT (CALIPSO)

Land: AOT (MODIS) > AOT (CALIPSO)

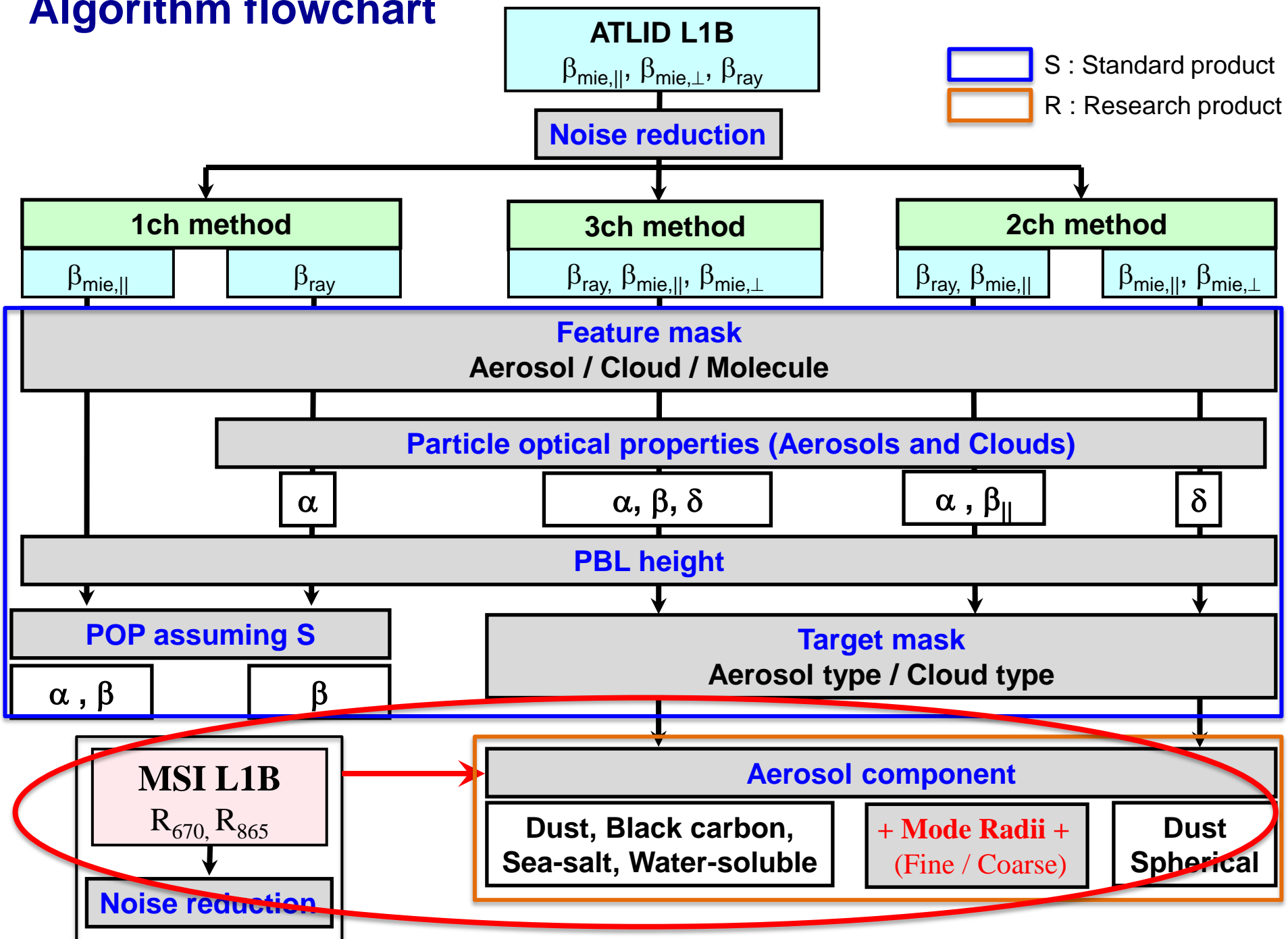
✓ Biomass-burning aerosols (BC, OC)

✓ East Asia



*Averaged every 3°x3° grid for daytime

Algorithm flowchart




Concepts

ATLID L2A aerosol component retrieval (ER)

- ✓ α , β , δ at 355nm \Rightarrow σ for WS, DS, BC
- ✓ Wind speed \Rightarrow σ for SS (over ocean)
 - External mixture of the 4 aerosol components
 - Assuming mode-radius, refractive index, shape

+MSI L1b : Radiances at 675 and 865nm (Over ocean)

- ✓ α , β , δ at 355nm \Rightarrow σ for WS, DS, BC
- ✓ Wind speed \Rightarrow σ for SS (over ocean)
- ✓ **Column-mean mode-radii for WS & Dust** 
 - (Note: Mode radii of BC is prescribed)

WS (Water-soluble) : small-size / weak-absorption / spherical

DS (Dust) : large-size / moderate absorption / non-spherical

BC (Black carbon) : small-size / strong absorption / spherical

SS (Sea-salt) : large-size / weak-absorption / spherical

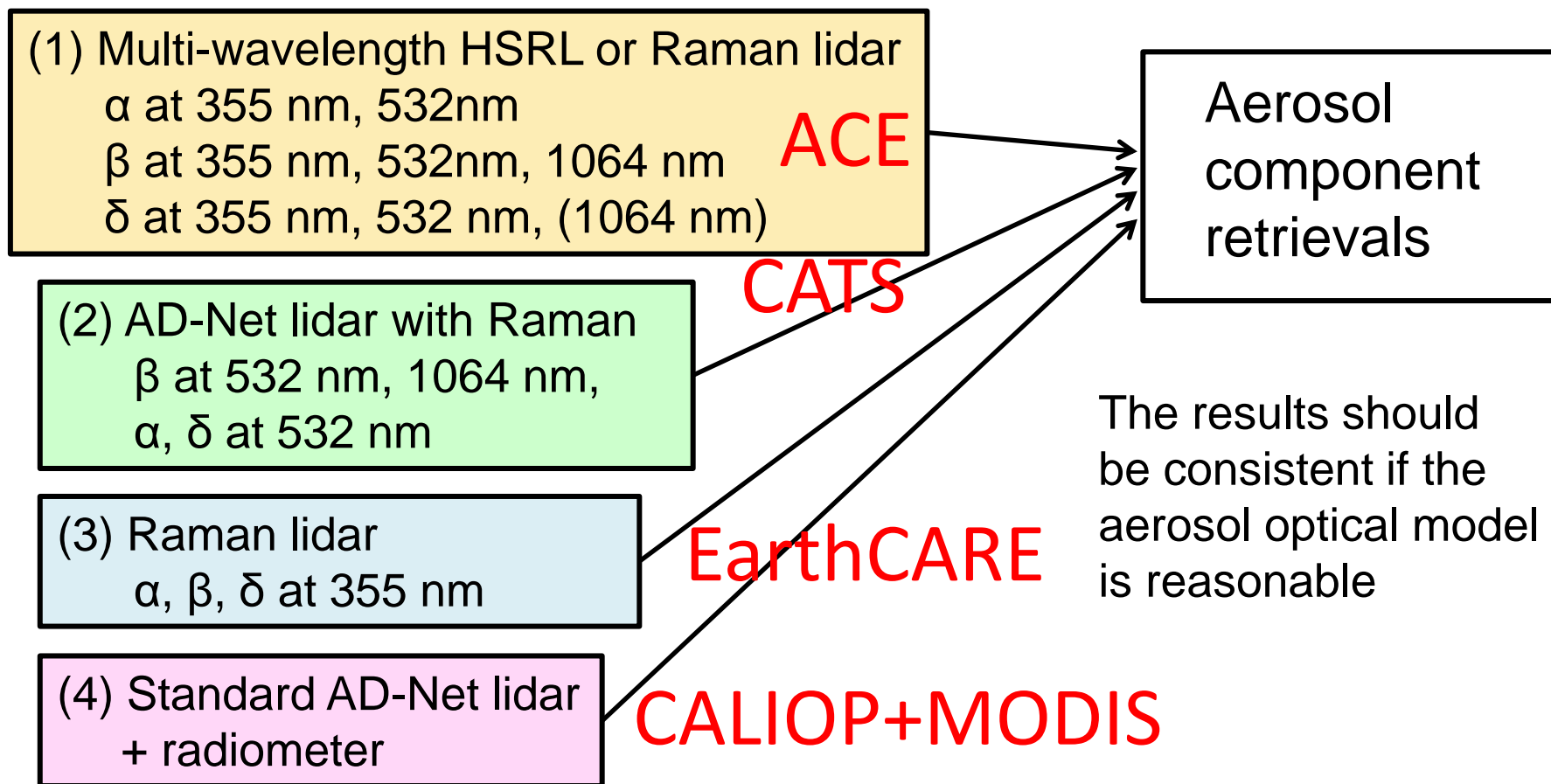
Validation plan using the ground-based lidar networks

- Direct comparison of ATLID α , β , δ with ground-based Raman lidars and HSRLs
- Validation of the ATLID aerosol component product with ground-based multi-wavelength Raman lidar, HSRL, AD-Net+SKYNET

Validation of the ATLID aerosol component product

ATLID (α , β , δ at 355 nm) + supplementary data \rightarrow Concentrations of 4 aerosol components (Mineral dust, Sea salt, Black carbon, Sulfate+Nitrate+OC)

Ground-based multi-wavelength HSRL and Raman lidars will be used for validating consistency of aerosol component analysis.



New project on data assimilation of multi-wavelength Raman (or HSR) lidars!

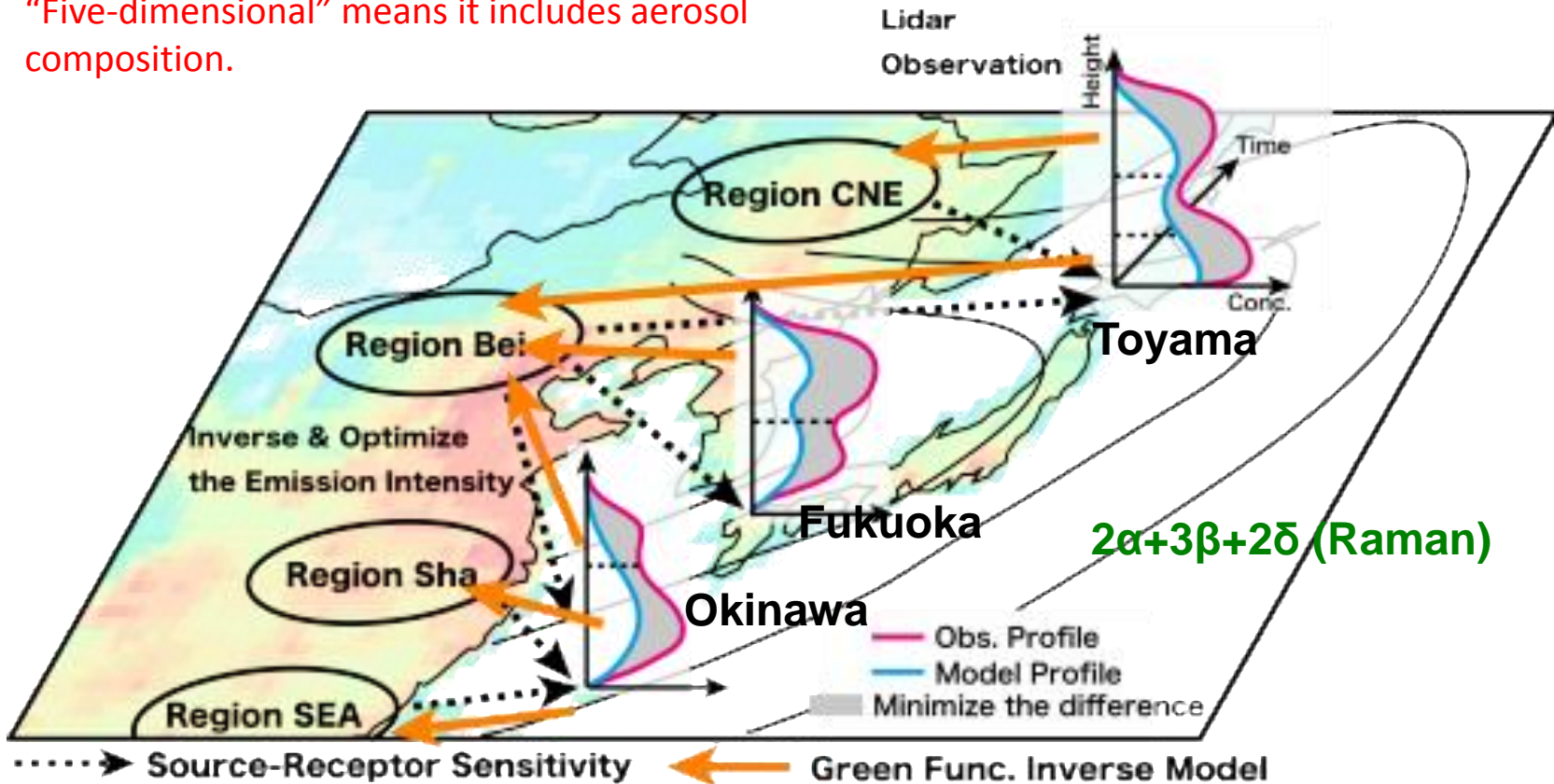
【Grant-in-Aid for Scientific Research(S)】
Integrated Disciplines (Environmental science)

Five-dimensional data assimilation of aerosol based on integrated analysis of multi-wavelength lidar and chemical transport model

PI: Itsushi Uno

(Kyushu University, Research Institute for Applied Mechanics)

“Five-dimensional” means it includes aerosol composition.



SATREPS Lidar Network in South America



ATLID L2A & ATLID+MSI L2B products

	Parameter	Used ATLID channel			Resolution (Note)
		1ch	2ch	3ch	
ATLID L2A (S)	Feature mask (Molecule/Aerosol/Cloud classification)	○	○	○	$\Delta Z=0.1\text{km}$ $\Delta H = 0.285\text{km}/1\text{km}/10\text{km}$
	Target mask (Cloud type/Aerosol type classification)	×	○	○	$\Delta Z=0.1\text{km}$ $\Delta H = 1\text{km}/10\text{km}$
	Aerosol optical property (Extinction, Backscatter, Depolarization , Lidar ratio)	△	△	○	$\Delta Z=0.1\text{km}$ $\Delta H = 1\text{km}/10\text{km}$ (1ch, 2ch: S1 assumption)
	Cloud optical property (Extinction, Backscatter, Depolarization, Lidar ratio)	△	△	○	$\Delta Z=0.1\text{km}$ $\Delta H = 1\text{km}/10\text{km}$ (1ch, 2ch: S1 assumption)
	Planetary boundary layer height	○	○	○	$\Delta H = 1\text{km}/10\text{km}$
ATLID L2A (R)	Extinction of aerosol components (Dust, Sea-salt, Water-soluble, Black carbon)	×	○	○	$\Delta Z=0.1\text{km}$ $\Delta H = 10\text{km}$ (2ch: Dust, Water-soluble)
ATLID-MSI L2B (R)	Extinction of aerosol components	×	○	○	$\Delta Z=0.1\text{km}$ $\Delta H = 10\text{km}$
	Mode radii (Fine and Coarse)	×	○	○	$\Delta H = 10\text{km}$ (Constant in a column)

Validation: Comparison for various cases

✓ Clean/Dirty ✓ Land / Ocean, ✓ Industrial / rural

✓ Asia / Europe / America ... ✓ Dust / Biomass-burning / Pollution ...

Thank you