Experiences from several data assimilation methods: - 4D-Var and EnKF -- Satellite and in-situ measurements -- Regional and global models -

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DA experiments with various models, observations and methods

Today's contents



Concluding remarks

Introduction: 4D-Var and EnKF

4D-Var



Use adjoint model

EnKF



Use ensemble simulation

Introduction: Backward and Forward methods

Adjoint (Backward) Source Receptor (emission) (observation)

Backward method calculates sensitivities of receptors (observations) to sources (emissions). *We need an adjoint model.

Forward



Forward method calculates sensitivities of sources (emissions) to receptors (measured concentrations). *We need a set of 'ensemble' simulations.

Today's contents



Concluding remarks



Fig. 1. Schematic of the RAMS/CTM-4DVAR data assimilation system. The numbers correspond to the equation numbers in the text.

(Yumimoto and Uno, 2006)

Goals

Developing a 4D-Var DA system with CTM in 2-year master's program (including an adjoint of the CTM)

* No TAMC. Line by line.



Fig. 2. Modeling domain and spatial distribution of the basic (priori) emissions of CO. Red triangles show observation sites; the red solid line is the R/V *Ronald H. Brown* ship track.

- Regional CTM (CFORS)
- 4D-Var
- Observational constraints

in-situ (surface) measurements of CO

Goals

Optimize CO emission in East Asia

Validate the DA system

Show the capability of 4D-Var

for chemical DA and inverse modeling.



a posteriori



3.0 Table 2 Recent estimates of annual anthropogenic CO emissions from China (Tg CO year⁻¹) 1.0 Study China (Tg year⁻¹) Anthropogenic Biomass burring Bottom up estimate The priori (Streets et al., 2003) 100 16 **REAS**^a 148 142 16 Streets et al. (2006) Top down (inverse) estimate Palmer et al. (2003) 163-173 12 6.0 Pétron et al. (2004) 132–194^b 195-222^b Arellano et al. (2004) Wang et al. (2004) 166 173 Heald et al. (2004) This study 147 .0 Modeling Allen et al. (2004) 113–177^b Carmichael et al. (2003b) 169-228 2.0

Results

The DA system worked well

Our posteriori CO emission is consistent with results from other inversions

(Yumimoto and Uno, 2006)



Results

The DA system worked well

Our posteriori CO emission is consistent with results from other inversions

Adjoint model is also useful for backward sensitivity analysis

(Yumimoto and Uno, 2006)



Results

The DA system worked well

Our posteriori CO emission is consistent with results from other inversions

Adjoint model is also useful for backward sensitivity analysis

The DA system is used for optimizing NOx emission over China



Asian dust attacked the Korean Peninsula

- Regional CTM (CFORS) 8 bins
- 4D-Var
- Observational constraints

NIES Lidar network

Goals

Optimize dust emission (the Gobi desert)

Show the capability for assimilating

remote sensing measurements.

Model Domain



Time --->

(Yumimoto et al., 2007, 2008)

- Regional CTM (CFORS) 8 bins
- 4D-Var
- Observational constraints

NIES Lidar network

Goals

Optimize dust emission (the Gobi desert)

Show the capability for assimilating

remote sensing measurements.

a priori dust emission



Results

We obtained the optimized dust emission of about 57 Tg/event.

The Lidar inversion is consist with an inversion with MODIS AOT.

⁽Yumimoto et al., 2007, 2008)



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Assimilation results are validated by NIES Lidar in-situ PM10 measurements CALIPSO and MODIS



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Various applications

Yumimoto et al., 2008b, Iwamoto et al. 2011, Hara et al., 2009, Uno et al., 2008

Progresses



Progresses



Figure 2. (a) Horizontal distribution of the emission scaling factor (ratio of the a posteriori emission flux to the a priori flux). (b–d) Y2007 or a priori (blue lines) and a posteriori (red lines) size distributions of dust emission fluxes in regions I–IV.

(Yumimioto et al., 2012)



- GEOS-Chem
- EnKF (LETKF)
- Observational constraints

Satellite (LEO and imaginary GEO)

Goals

Implement LETKF in GEOS-chem

Perform OSSE for geo-stationary satellite

Estimate impacts of satellite observation

on CO forecasting in East Asia.



Fig. 1. Schematic diagram of the observing system simulation experiment (OSSE) framework.

Table 1

Sets of simulated observations used in the OSSE.

Obs. Set	GEO-NIR+TIR	GEO-TIR	LEO-TIR
Orbit Frequency Sensprs	Geostationary 3-h interval Near Infra Red Thermal Infra Red	Geostationary 3-h interval Thermal Infra Red	Low Earth orbit Twice a day Thermal Infra Red

(Yumimoto, 2013)

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Satellite (LEO and imaginary GEO)

Goals

Implement LETKF in GEOS-chem

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Fig. 8. RMSD reduction rates of the FR compared with the CR for three vertical levels. The color shades represent forecast times: light, moderate, and dense shades denote 12-, 36-, and 60-h forecast times. The RMSDs were calculated from 27 FRs in the downwind region (20–50°N, 120–155°E). Red, orange and green bars denote RMSD reduction rates from GEO-NIR + TIR, GEO-TIR, and LEO-TIR, respectively. Higher reduction rate means greater positive impact on the FRs. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this

Results

GEO-satellite with two sensors achieved much better forecasts even in 60-h forecast.

(Yumimoto, 2013)



Results

GEO-satellite with two sensors achieved much better forecasts even in 60-h forecast.

and has big impact on forecast of transboundary CO over the downwind region



Progresses

• One month CO DA experiment in US with MOPITT/TERRA measurements



Progresses

• One month CO DA experiment in US.

with MOPITT/TERRA measurements



Progresses

• One month CO DA experiment in US with MOPITT/TERRA measurements

• Bias aware method has capability for introducing better DA performance

assimilated. GEOS-Chem/LETKF is capable

for assimilating various chemical component and aerosols

Five-dimensional data assimilation of aerosol based on integrated analysis of multi-wavelength lidar and chemical transport model





- SPRINTARS
- EnKF (LETKF)
- Observational constraints

Satellite (MODIS AOT)

Goals

Implement LETKF in SPRINTARS

One-month DA experiment and validation

Estimate impacts of DA on radiative forcing.



Figure 2. Spatial distributions of monthly mean AOT in May 2007. (a) MODIS/TERRA and AQUA, (b) *a priori*, (c) *a posteriori*, and (d) increment between *a posteriori* and *a priori*. Modeled results were sampled and interpolated at the times and locations of MODIS AOT availability.



Figure 3. Comparisons between AERONET measurements and modeled results (a) showing the global distribution of assimilation efficiencies (AE) based on AERONET data. Color and size show AE values and observed monthly AOT, respectively. (b–i) AOT time series at AERONET sites. AERONET and MODIS observations are shown as green circles and orange cubes, respectively. *A posteriori* and *a priori* AOTs are shown with red and blue lines, respectively. AE, mean AOT (M) and correlation coefficients (R2) are also shown for observation (OBS), *a priori* (PRI) and *a posteriori* (POS).

(Yumimoto and Takemura, 2011)

Results

Much better agreement with MODIS

Validated by AERONET



Results

Much better agreement with MODIS

Validated by AERONET

Assimilated aerosol field modified direct radiative forcing

	a priori	a posteriori
Whole Sky @ TOA	-0.56 W/m ²	-1.1±0.35 W/m ²
Clear Sky @ TOA Ocean	-1.4 W/m ²	-2.5±0.47 W/m ²
Land	-1.5 W/m ²	$-2.7\pm0.52 \text{ W/m}^2$

(Yumimoto and Takemura, 2011)

Figure 4. Increment of whole-sky TOA direct aerosol effect (DRE) of anthropogenic and natural aerosols between *a posteriori* and *a priori* (a) shortwave and (b) longwave radiation.

5. SPRINTARS x 4D-Var x satellite (MODIS)

SPRINTARS



Schematic diagram of SPRINTARS/4D-Var data assimilation system

(Yumimoto and Takemura, 2013)

Observational constraints

Satellite (MODIS coarse-mode AOT)

Goals

Implement 4D-Var in SPRINTARS

8-year inversion experiment of Asian dust

5. SPRINTARS x 4D-Var x satellite (MODIS)



Results

Inverse estimate of 8-year dust emissions (a posteriori emission shows significant correlations with snow cover and SLP)

Analyzed dust deposition and radiative forcing

Concluding remarks

- Assimilation is a powerful tool for CTMs.
- Both 4D-Var and EnKF have their distinctive advantages.
- Accurate estimates of background covariance and its structure are important.
- Comprehensive DA, which assimilates observations from various platforms, is required.

(Strong co-operation between model and observation)

• DA works with MASINGAR (with JMA and JAXA) will be shown in the next ICAP meeting.