



Météo-France update

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- 1. The MOCAGE model**
 - 2. The latest operationnal version**
 - 3. On going and future work**
 - 4. Data assimilation update**
 - 5. Work on aerosol source inversion**
 - 5. Conclusion**

1. The MOCAGE model

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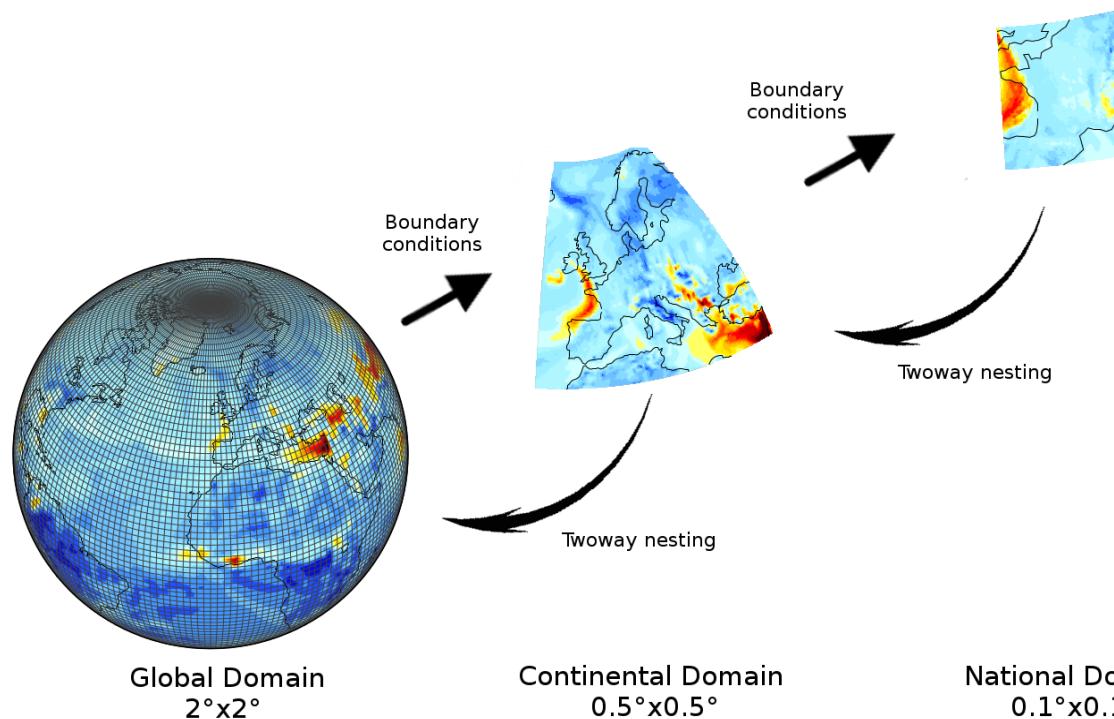
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The MOCAGE model : general features

- Off-line Chemistry Transport Model
- Semi-lagrangian transport scheme with convection (Bechtold et al., 2001) and diffusion (Louis, 1979)
- Two-ways nesting capabilities
- 47 σ -hybrid vertical levels from surface up to 5 hPa



The MOCAGE model : aerosols

- Chemical scheme RACM (troposphere) and REPROBUS (stratosphere)
- 95 gaseous species, 55 photolysis, 322 chemical reactions
- 4 primary aerosols :
 - Desert Dust : dynamic emissions (Marticorena and Bergametti, 1995)
 - Sea Salt : dynamic emissions (Gong, 2003 and Jaeglé, 2011)
 - Black Carbon : emission inventory (MACCity)
 - Primary Organic Carbon : emission inventory (MACCity)
- Secondary Inorganic Aerosols computed with ISORROPIA (v2.1)
- Sectionnal representation using 6 bins for each aerosol

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The latest operationnal version

- On January 31st a new version of the model was implemented
- Global domain $2^\circ \times 2^\circ \rightarrow 1^\circ \times 1^\circ$
- Complete operationnal configuration is now :
 - Global domain at $1^\circ \times 1^\circ$
 - European domain at $0.5^\circ \times 0.5^\circ$
 - France domain at $0.1^\circ \times 0.1^\circ$
- Diurnal cycle for Isoprene
- Desert dust distribution is now issued from Kok (2011)

The latest operationnal version : Dust distribution

- Previous distribution was Alfaro et al. (1998)
- Desert dust distribution is now issued from Kok (2011) :

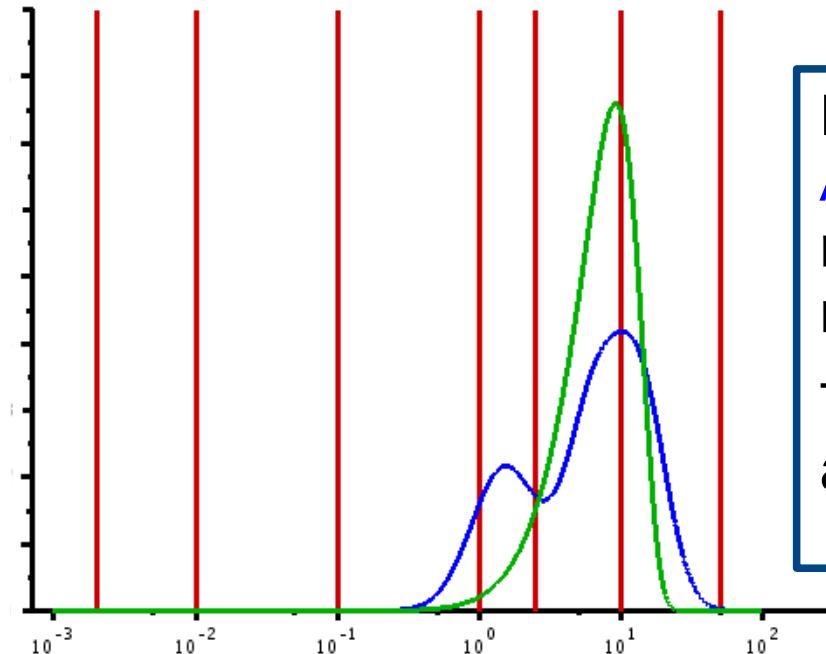
$$\frac{dV_d}{d\ln D_d} = \frac{D_d}{c_v} \left[1 + erf \left(\frac{\ln(D_d/D_s)}{\sqrt{2} \ln \sigma_s} \right) \right] \exp \left[- \left(\frac{D_d}{\lambda} \right)^3 \right]$$

D _s	σ _s	λ	C _v
3.4 μm	3.0	12 μm	12.62 μm

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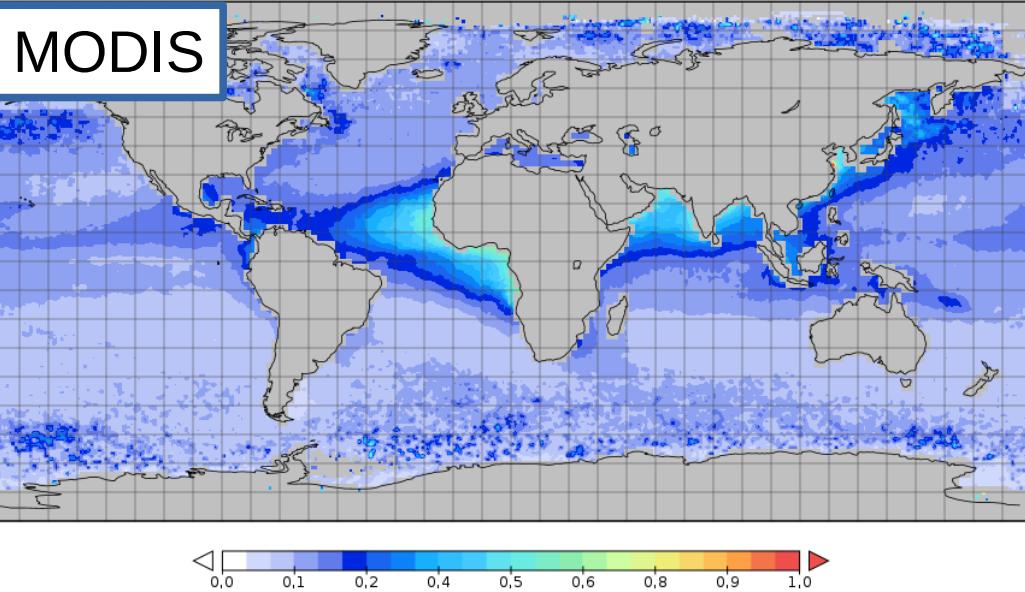
Distribution for the desert dust using [Alfaro et al. \(1998\)](#) and [Kok \(2011\)](#). The red bars represents the **section** in the model.

There are now less very big particles and less small particles.

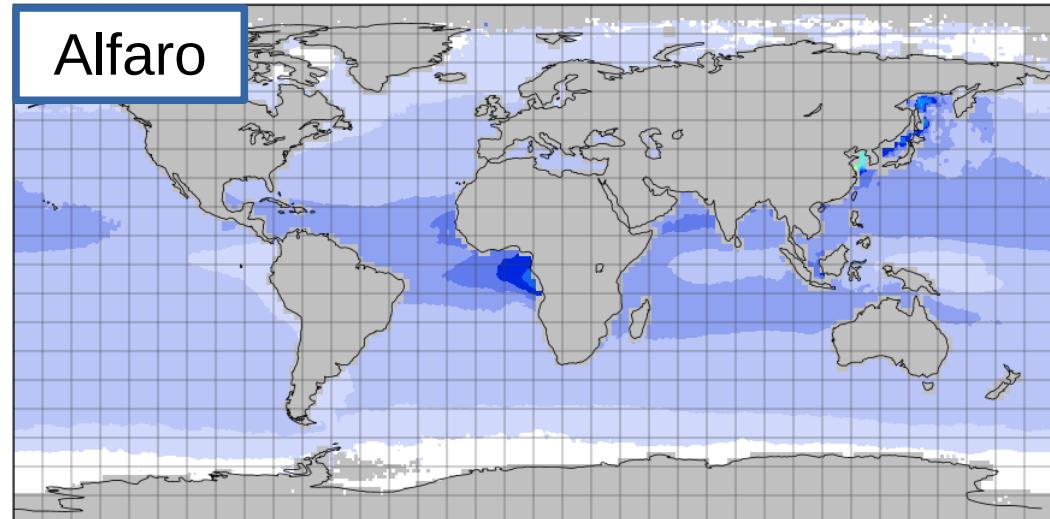
The latest operational version : Dust distribution

Mean annual AOD for 2012 :

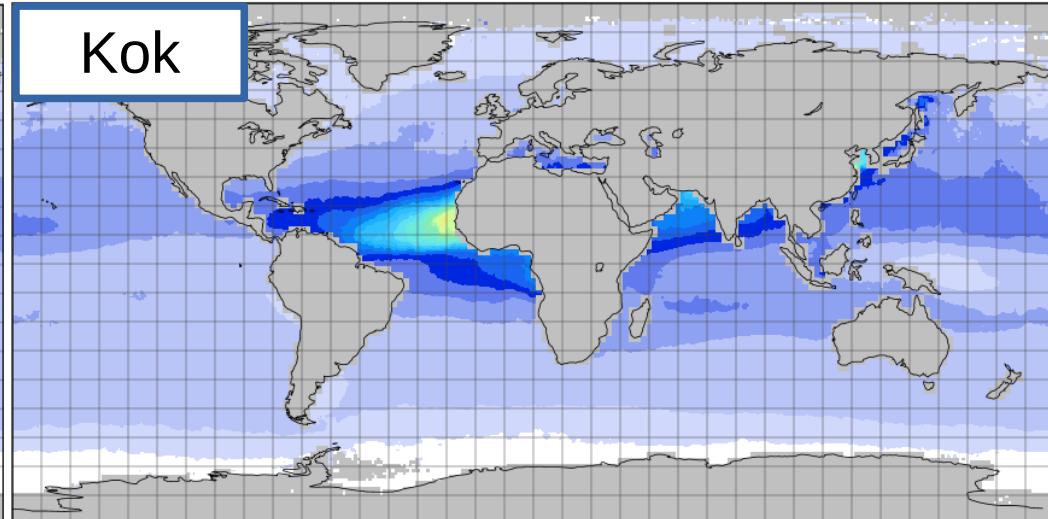
- The mean AOD is improved using the Kok distribution for desert dusts
- Simulation made at $2^\circ \times 2^\circ$ resolution



Alfaro



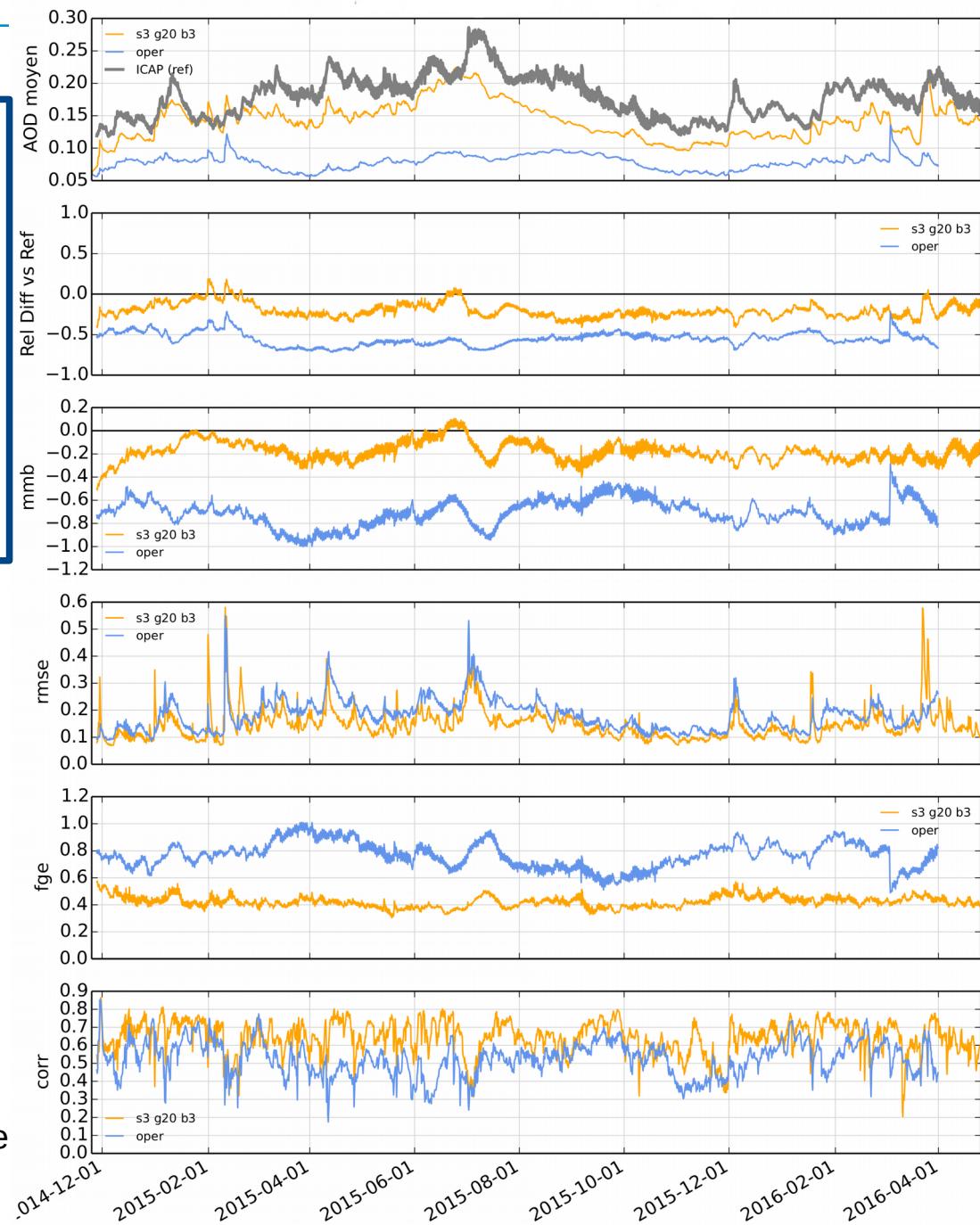
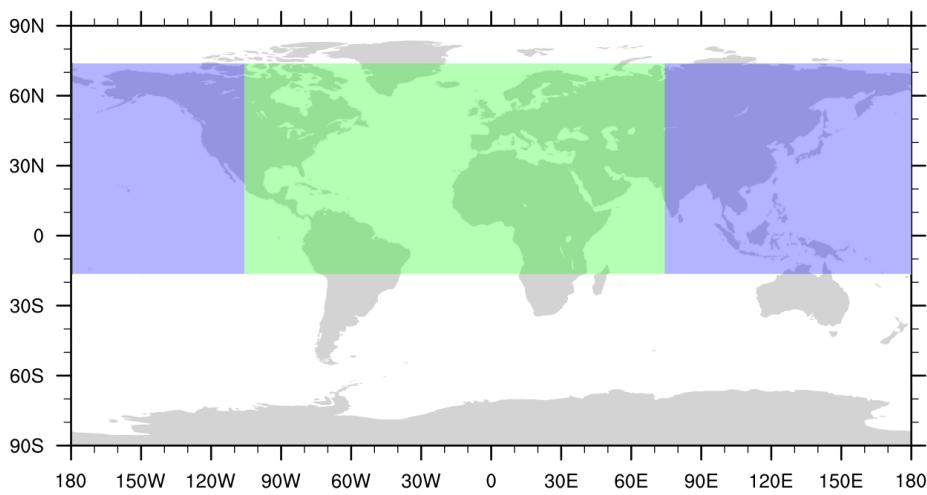
Kok



The latest operationnal version : Dust distribution

Validation against ICAP ensemble :

- Over the green zone on the figure
- The use of the Kok ditribution shows an improvement of the results when comparing to ICAP ensemble



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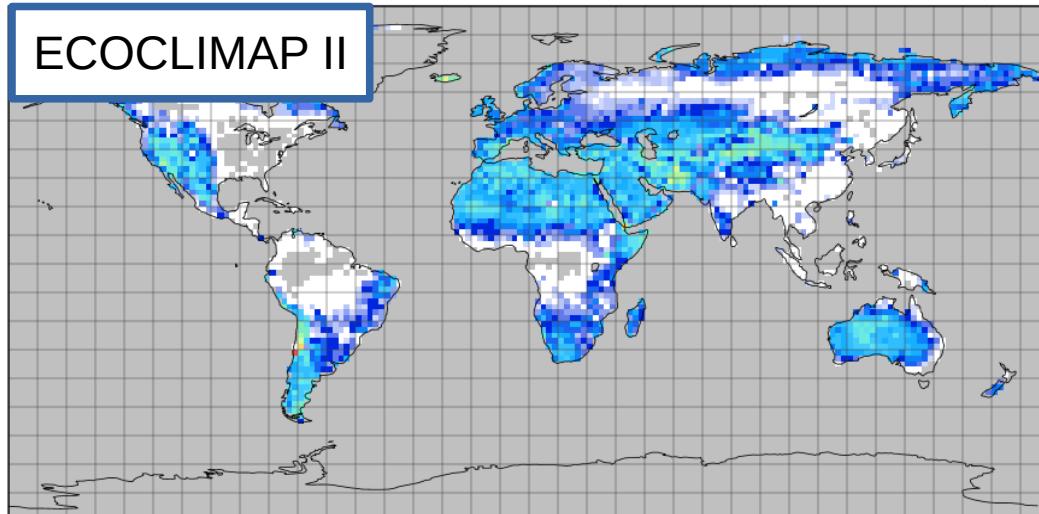
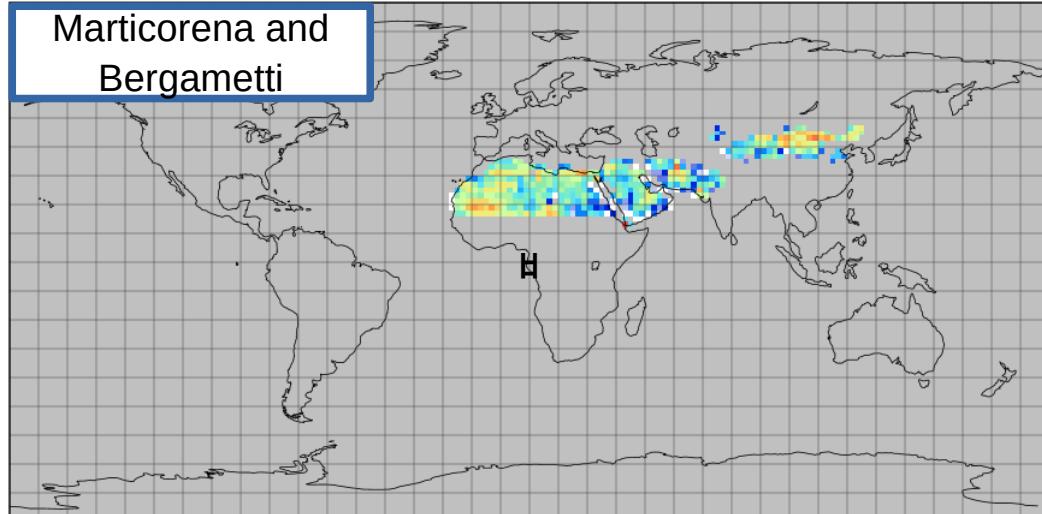
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On going and future work

- ISORROPIA (V2.1) has been partially rewritten with F90 and modules, allowing an easy and trusty parallelisation.
 - MOCAGE is around 14 times faster with this new version.
 - This improvement will allow us to work on the equilibrium assumption
- Secondary Organic Aerosols will be implemented into MOCAGE. Two schemes will be tested :
 - A simple parameterization based on CO emissions (Spracklen et al., 2011) → anthropogenic
 - The SOAP module developped at CEREA (Couvidat et Sartelet, 2015) → anthropogenic and biogenic

On going and future work

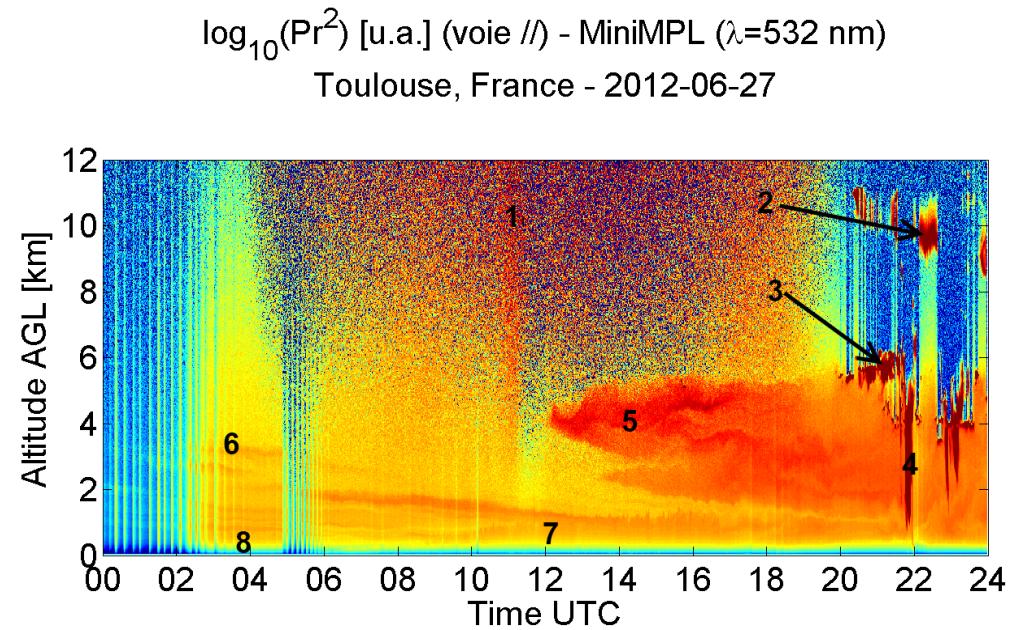
- Use of the emission height into GFAS product instead of fixed emission heights
- New emission of desert dust using ECOCLIMAP II (Kaptue Tchuente et al., 2010) instead of Marticorena and Bergametti (1995) database.



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Data Assimilation update

- In 2016, Météo-France bought and installed 6 lidars (Mini-MPL) :
 - 5 fixed : Brest, Trappes, Lille, Aleria and Momuy
 - 1 mobile that stays in Toulouse when not used for an emergency or an exercise
- At the end of 2017, the data should be available on the EPROFILE network

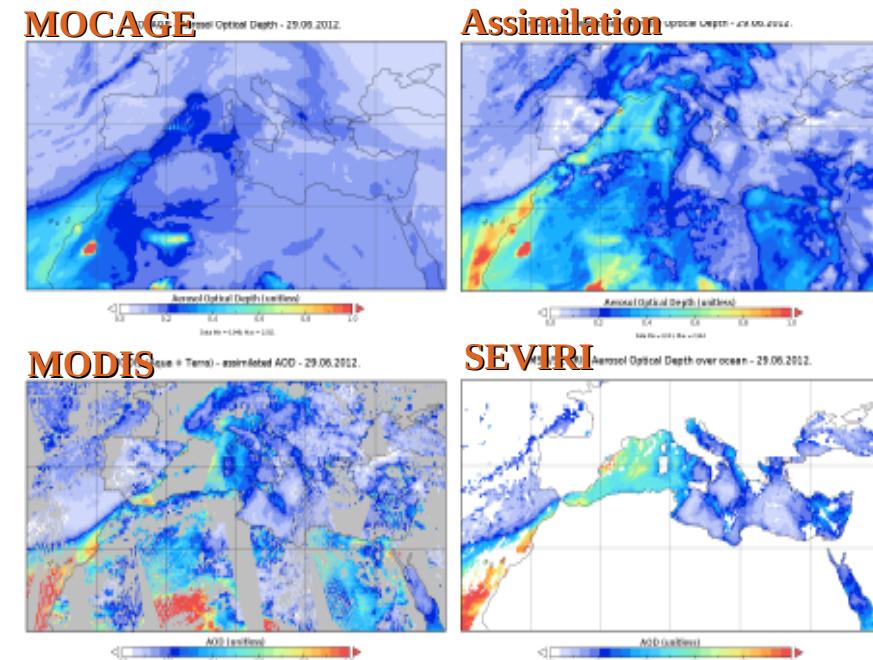


- 1 noise
- 2 high altitude clouds
- 3 medium altitude clouds
- 4 rain shower
- 5 Saharan desert dust
- 6 residual boundary layer
- 7 diurnal boundary layer
- 8 system overlap



Data Assimilation update

- The MOCAGE System is able to assimilate:
 - Aerosol Optical Depth (AOD) measurements
 - Lidar Signals : Backscatter Coefficient, Extinction Coefficient, Normalized Backscatter signal from ground, satellite, airplane (up or down)
 - Total concentration (in 3D) as a control variable



- Plan to assimilate the lidar network data and Callipso measurements
- Plan to assimilate AODs (eg MODIS) on a global scale
- Prepare assimilation of geostationary satellite data (Seviri products, FCI)

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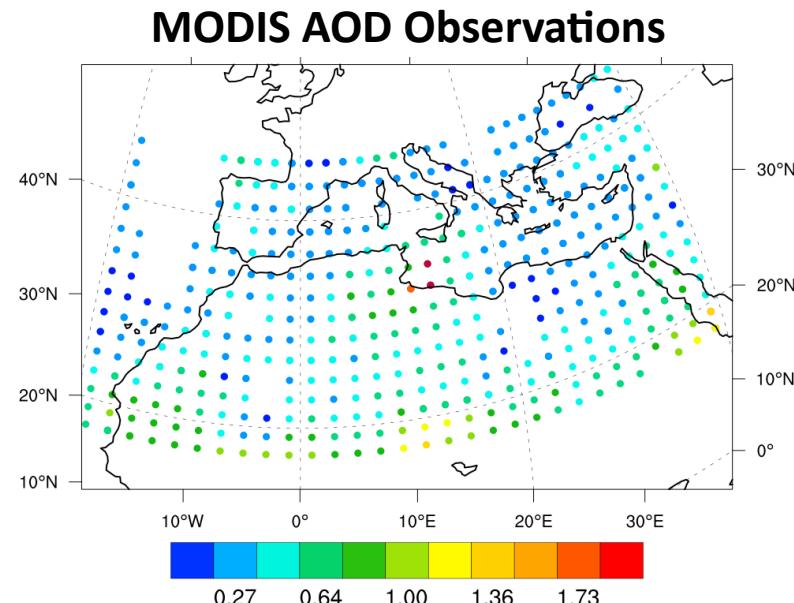
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Work on inversion of aerosol emissions

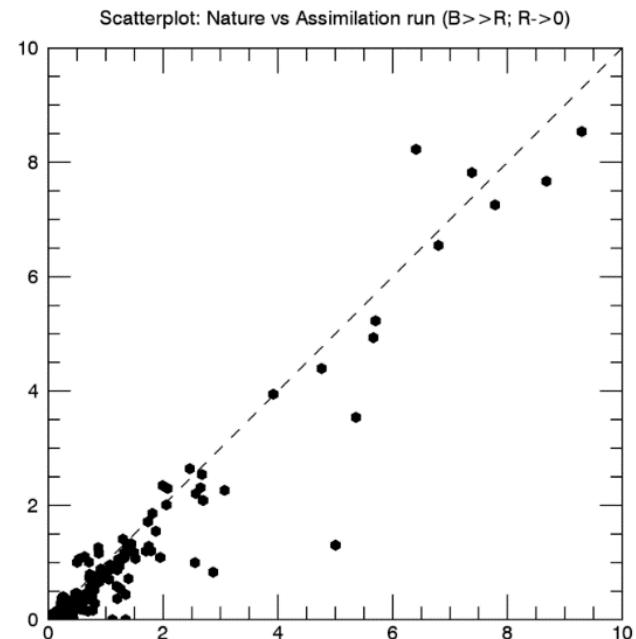
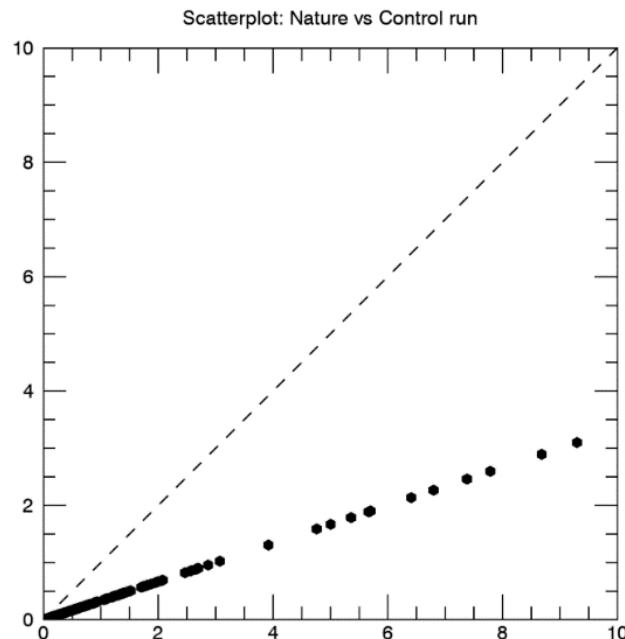
- The need to better understand aerosols emissions because of significant uncertainties (on the global and even more on the regional/local scale)
- The inversion could be applied on different aerosols events (desert dust outbreaks, volcanic ash, biomass burning, etc)
- Improving of the modelled emissions and the model forecast
- Using of global, high resolution (spatial and temporal) observations to constrain emissions → Aerosol Optical Depth (AOD) is the most adapted choice
- Our system MOCAGE-Valentina uses the variational 4D-Var method :

$$J(x) = \frac{1}{2} \|x_b - x\|_{B^{-1}}^2 + \frac{1}{2} \|y - \mathcal{H}(\mathcal{M}(x))\|_{R^{-1}}^2$$



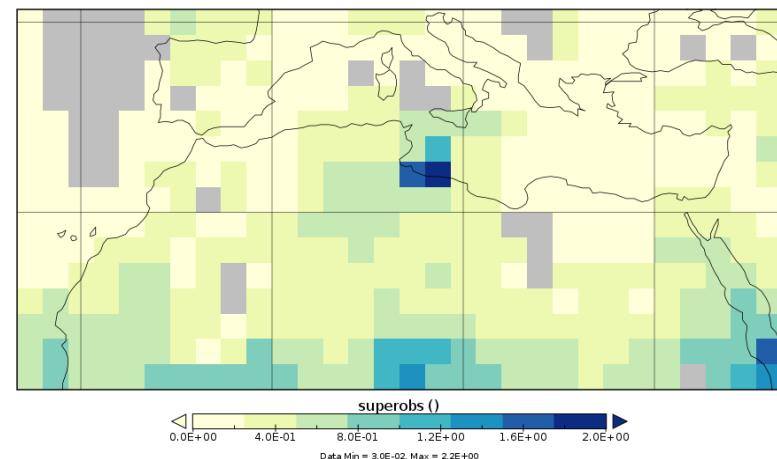
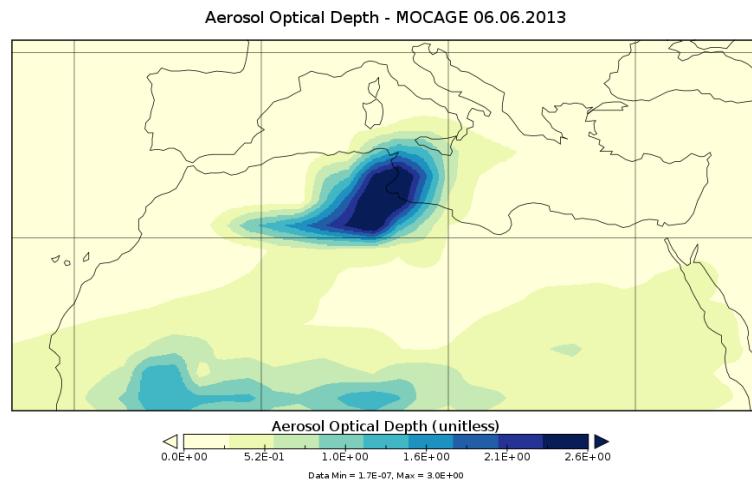
Work on inversion of aerosol emissions

- Can AOD observations really improve modelled emissions this way?
- Inversion with synthetic AOD generated with perturbed emissions (« Truth ») to validate the method
 - Fixed perturbation: -70% of the modeled emissions

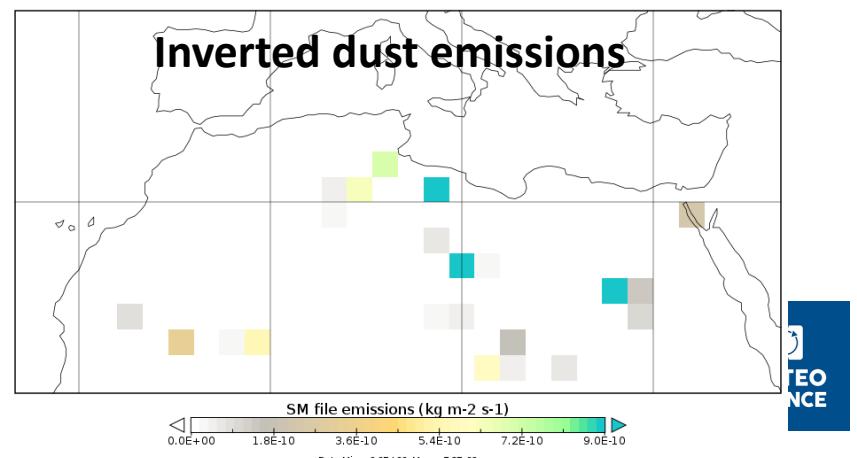
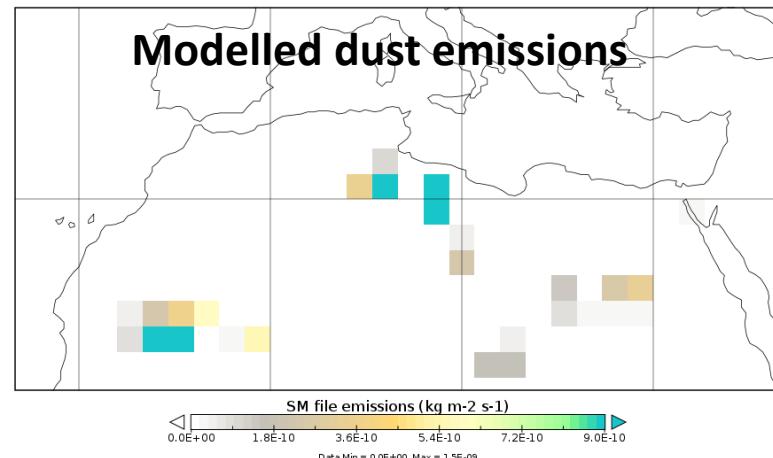


Work on inversion of aerosol emissions

- An example of desert dust aerosols emission inversion in the system MOCAGE-Valentina (CNRM-CERFACS)
- From **modeled aerosols** and **MODIS observed AOD ...**



- ... the system is able to make a correction of the dust emission field



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Conclusion

- New version of the operationnal model :
 - Better resolution
 - New distribution for desert dust
 - Improved results
- On going work on desert dust emissions
- Work on Secondary Organic Aerosols
- Projects on aerosol data assimilation of AOD and lidar signal



Thank you for your attention !

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