



Engineering Directorate Software Robotics and Simulation Division

Summer Internship Exit Presentation



ER5: Dynamic Systems Test Branch

June 8 – August 14, 2015



About Me





Hometown: Grand Rapids, MN

Home

MINNESOTA STATE UNIVERSITY MOORHEAD.

- BS in Physics, Emphasis in Medical Physics (2014)
- Minor in Astronomy



NDSU NORTH DAKOTA STATE UNIVERSITY

- Graduate Student, pursuing MS in Electrical Engineering
- Emphasis in Control Systems

Areas of Interest for future work/research

- Biomedical
- Robotics
- Propulsion

Personal Interests

- Soccer
- Hunting
- Fishing





Agenda



- ER5 Projects
- > Takeaways
- > Future Plans





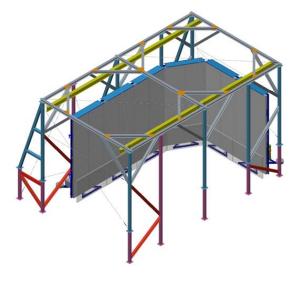
ER5 Projects



Projects

- ARGOS Operator Training
- Power Distribution of Future Video Wall for ARGOS
- Service Robot







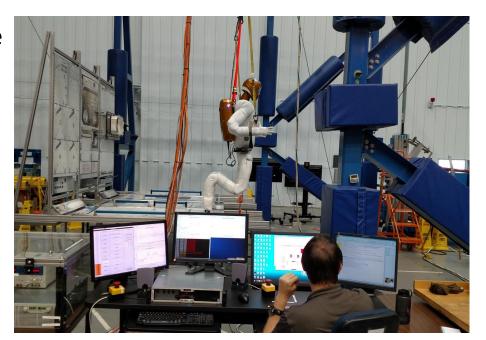


ARGOS Operator Training



- Trained as an ARGOS operator
 - Supported two days per week
 - Supported for R2 and SAFER testing
- Setup
 - Follow documented procedure for proper startup
 - Different payloads

- Operate
 - Maintain vigilance on the control system and the payload
- Shutdown
 - Follow documented procedure for proper shutdown





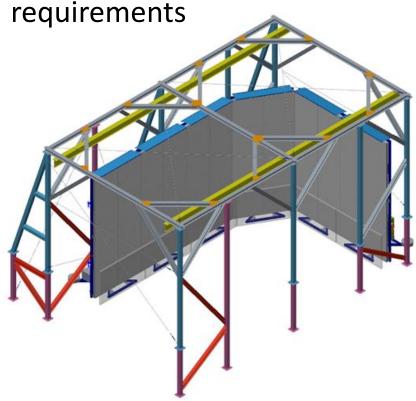
Video Wall Project

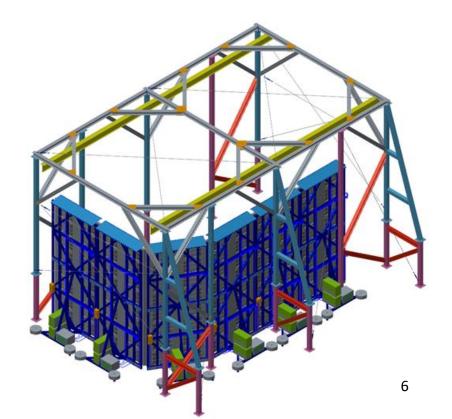


- Video Wall consists of 6 video towers
- Power distribution design for towers

Selected parts from given requirements

- Collaborated with:
 - Larry Dungan, Electrical Engineer
 - Frank Delgado, Project Manager/Software Designer
 - Bryan Griffith, Mechanical Engineer



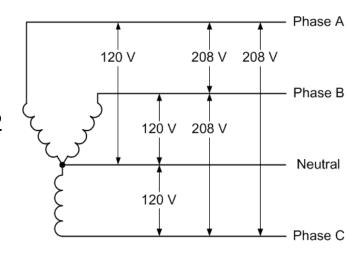




Power Distribution



- Only custom electrical design is the power distribution
 - Other connections are computers and monitors
- Utilize 3-phase 208VAC
 - Allows three 120VAC single-phase
- Adequate 208VAC is available in the facility for 2 video walls in support of initial deployment
- Minimizes electrical cables from video wall to facility
- UPSs were used for power conditioning
 - Also provides power backup due to 208VAC power sags in Building 9
- Equal distribution of loads across available power





Power Distribution



- Break down of power on three breakers
- Breaker selection based on data is 20A
- Wire size per National Electric Code is 12AWG solid core copper wire

Circuit 1	Hardware	Max Power (W)	Quantity	Wattage (W)	Current (A)
	Monitor	200	4	800	7
	Computer	1100	1	1100	9
			TOTAL	1900	16

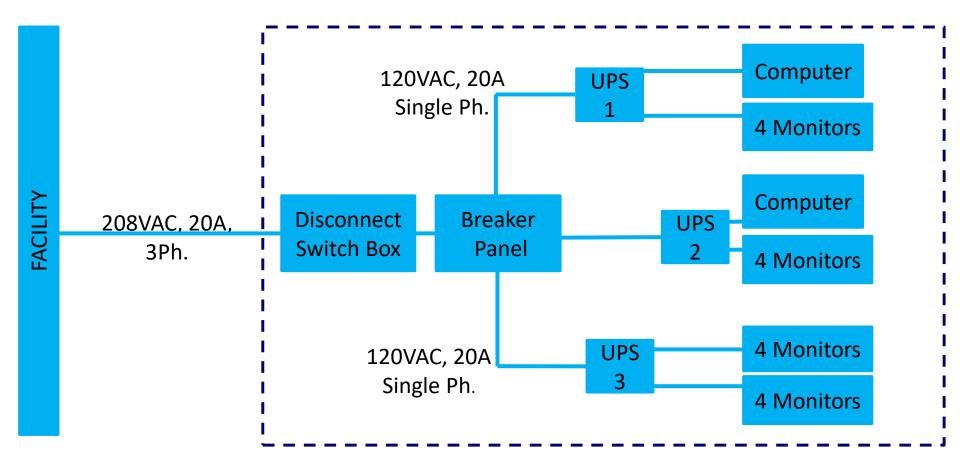
Circuit 2	Hardware	Max Power (W)	Quantity	Wattage (W)	Current (A)
	Monitor	200	4	800	7
	Computer	1100	1	1100	9
			TOTAL	1900	16

Circuit 3	Hardware	Max Power (W)	Quantity	Wattage (W)	Current (A)
	Monitor	200	8	1600	14
	Computer	1100	0	0	0
			TOTAL	1600	14



Block Diagram: One Video Tower

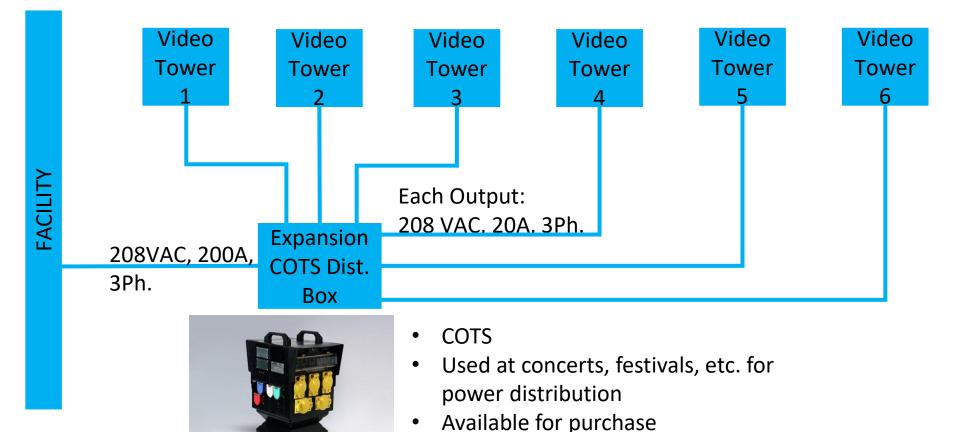






Block Diagram: Multi Video Towers





DB200N1J10DM-63



Service Robot Project



Goal:

- Build, program, and demonstrate a working service type robot
- Future usage in a new ER5 education outreach program

- Used VEX robotics kit to design service bot
- > Tested different software to program the robot
- Programmed bot with RobotC software
- Demonstrated service bot to Office of Education at JSC



Software: RobotC

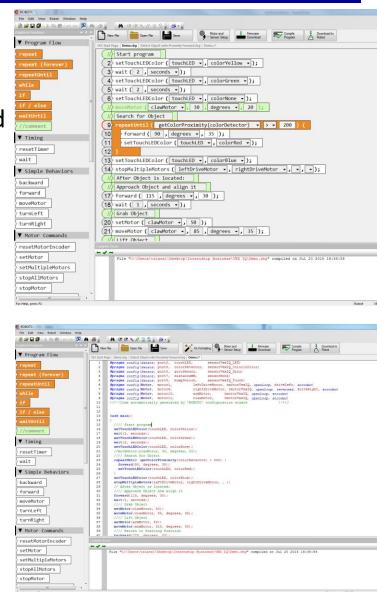


<u>Advantages</u>

- Simple VisualProgrammingLanguage (VPL) blocks
- Generates C code from the VPL blocks of code
- Drag and drop features all C code generation
- Real-time debugging features
- Multiple programs in one slot of robot brain

<u>Disadvantages</u>

Some code writing experience is needed











Takeaways



- Altium Software
 - Block diagrams for power distribution
- VEX Software
 - Modkit
 - RobotC
 - EasyC
- Networking at JSC
 - Interns and Co-ops
 - Coworkers and other employees
- Formal presentation of results
- Prioritizing and time management
- Working in a team setting
- Attended lectures and tours





Future Plans



- > Apply for more opportunities at NASA JSC
- Full time positions at JSC or contracting companies
- > Possibly more schooling after Master's degree



THANK YOU!



Caitlin Nolby Marissa Saad

North Dakota Space Grant Consortium



Questions



How long have you been at NASA R2?

